Due Oct 21, 2015

Topics for this problem set include round-off error and linear algebra.

- 1. As an example of an unstable algorithm, consider integer powers of the "Golden Mean" $\phi = (\sqrt{5}-1)/2$. It can be shown that $\phi^{n+1} = \phi^{n-1} \phi^n$, i.e. successively higher powers of ϕ can be computed from a single subtraction rather than a more expensive multiply. Write a single-precision program to compute a table consisting of the columns n, ϕ^n computed from the recursion relation, and ϕ^n computed directly (i.e. $\phi^n = \phi \phi^{n-1}$), for n ranging from 1 to 20. Is the round-off error random? What happens in double precision?
- 2. Write a program to compute the instantaneous spin period of a rigid body made up of identical, discrete, point particles. Use the fact that the angular momentum is

$$\mathbf{L} = \sum_{i} m_i(\mathbf{r}_i \times \mathbf{v}_i) = \mathbf{I}\boldsymbol{\omega},\tag{1}$$

where m_i is the mass of particle *i*, \mathbf{r}_i and \mathbf{v}_i are its position and velocity vectors with respect to the centre of mass, $\boldsymbol{\omega}$ is the spin vector, and \mathbf{I} is the inertia tensor

$$\mathbf{I} = \sum_{i} m_i (r_i^2 \mathbf{1} - \mathbf{r}_i \mathbf{r}_i),$$

where **1** is the unit matrix.¹ Write a program to solve Eq. (1) for $\boldsymbol{\omega}$ (feel free to use the routines in *Numerical Recipes*). The spin period is then $2\pi/|\boldsymbol{\omega}|$.

(a) Test your code by reading the data file

which is in the format $x \ y \ z \ v_x \ v_y \ v_z$ (i.e. 6 values to a line separated by white space). The units are mks (SI). What is the spin period in hours?

(b) Make a graphical representation of the body using your favorite graphing package. If you use 2-D projections, be sure to include enough viewing angles to get a complete picture.

¹For continuous bodies the summations are replaced by volume integrations and the particle masses become a mass density. In the present case the m_i 's can be omitted entirely since the particles are identical. The expression $\mathbf{r}_i \mathbf{r}_i$ is dyadic product of the 3 dimensional vectors \mathbf{r}_i , producing a 3x3 tensor \mathbf{T} with elements $T_{lm} = r_l r_m$, where l, m = 1, 2, 3 span over the x, y, z components of the vector \mathbf{r}_i .