

## Tensor manipulations

One final thing to learn about tensor manipulation is that the metric tensor is what allows you to raise and lower indices. That is, for example,  $v_\alpha = g_{\alpha\beta}v^\beta$ , where again we use the summation convention. Similarly,  $v^\alpha = g^{\alpha\beta}v_\beta$ , where  $g^{\alpha\beta}$  is the matrix inverse of  $g_{\alpha\beta}$ :  $g^{\alpha\beta}g_{\beta\gamma} = \delta_\gamma^\alpha$ , where  $\delta$  is the Kronecker delta (1 if  $\alpha = \gamma$ , 0 otherwise).

Another special tensor is the Levi-Civita tensor  $\epsilon_{\alpha\beta\gamma\delta}$ . This tensor is defined as being completely antisymmetric. In flat spacetime,  $\epsilon_{0123} = 1$  if 0 is the positive time direction and (123) is a right-handed set of spacetime basis vectors (e.g., xyz). Then  $\epsilon_{\alpha\beta\gamma\delta} = 1$  if  $(\alpha\beta\gamma\delta)$  is an even permutation of 0123,  $-1$  if it is an odd permutation, and 0 if any two indices are the same. In curved spacetime, we define the metric determinant  $g = \det||g_{\alpha\beta}|| < 0$ . Then, the Levi-Civita tensor is  $\epsilon_{\alpha\beta\gamma\delta} = (-g)^{1/2}[\alpha\beta\gamma\delta]$  where  $[\alpha\beta\gamma\delta]$  is  $+1$  for an even permutation,  $-1$  for an odd permutation, and zero if two indices are equal, as before. Note that the Levi-Civita tensor may be familiar from cross products:  $\mathbf{A} \times \mathbf{B} = \epsilon_{ijk}A^iB^j$ .

## Spacetime and Metrics

Now let's get a little more concrete, which will eventually allow us to introduce additional concepts. Let's concentrate on one particularly important geometry, the Schwarzschild geometry (aka spacetime). It is very useful, not least because it is more general than you might think. It is the geometry outside of (i.e., in a vacuum) any spherically symmetric gravitating body. It is *not* restricted to static objects; for example, it is the right geometry outside a supernova, if that supernova is good enough to be spherically symmetric. To understand some of its aspects we'll write down the line element (i.e., the metric in a particular set of coordinates). However, the coordinates themselves are tricky, so let's start with flat space.

**Ask class:** what is the Minkowski spacetime in spherical coordinates?

$$ds^2 = -dt^2 + dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2). \quad (1)$$

**Ask class:** what is the meaning of each of the coordinates (this is not a trick question!)? Everything is as you expect:  $\theta$  and  $\phi$  are the usual spherical coordinates,  $r$  is radius,  $t$  is time. In particular, if you have two things at  $r_1$  and  $r_2$  (same  $t$ ,  $\theta$ , and  $\phi$ ) then the distance between them is  $|r_2 - r_1|$ . No sweat. You could also say that the area of a sphere at radius  $r$  is  $4\pi r^2$ .

Well, why all this rigamarole? It's because in Schwarzschild spacetime things get trickier. Now let's reexamine the Schwarzschild line element

$$ds^2 = -(1 - 2M/r)dt^2 + dr^2/(1 - 2M/r) + r^2(d\theta^2 + \sin^2\theta d\phi^2). \quad (2)$$

Here we are using the (initially confusing!) standard convention in GR that  $c = G = 1$ , which is called geometrized units. In real units, for example,  $2M/r$  would be replaced by

$2GM/(rc^2)$ . **Ask class:** are the meanings of  $\theta$  and  $\phi$  changed? No, they're the same as always. This is guaranteed by the assumption of spherical symmetry that comes into the Schwarzschild derivation. But what about  $r$ ? **Ask class:** suppose  $dt = d\theta = d\phi = 0$ . What is the proper distance between  $r_1$  and  $r_2$ ? In this case,  $ds = g_{rr}^{1/2} dr$ , so the distance is

$$D = \int_{r_1}^{r_2} g_{rr}^{1/2} dr = \int_{r_1}^{r_2} (1 - 2M/r)^{-1/2} dr . \quad (3)$$

That means that if  $r_1 = 2M$ , for example, the radial distance measured is rather different than in flat space! But if you calculate the area of a sphere of radius  $r$ , you get  $4\pi r^2$  as usual, and the circumference of a circle is  $2\pi r$  as usual. This is one of the most extreme geometric indicators of the curved spacetime: “ $\pi$ ”=circumference/diameter drops like a rock as  $r \rightarrow 2M$ !

What about time? **Ask class:** what is the relation between proper time  $d\tau$  at  $r$  and the coordinate time  $dt$  if  $dr = d\theta = d\phi = 0$ ?  $d\tau^2 = -ds^2 = -g_{tt}dt^2 \Rightarrow d\tau = (1 - 2M/r)^{1/2}dt$ . Therefore, as  $r \rightarrow 2M$ , the elapsed proper time is tiny compared to the elapsed coordinate time. It turns out that  $t$ , the coordinate time, is the time as seen at infinity. Therefore, to a distant observer it looks like an object falling into the horizon takes an infinite time to do so. This is the origin of the term “frozen star” used by many until the 1970’s for black holes. You might think, then, that if you were to look at a black hole you’d see lots of frozen surprised aliens just outside the horizon. You actually would not, but more on that later.

### Conserved Quantities in Schwarzschild Spacetime

Let’s take another look at the Schwarzschild spacetime. It is spherically symmetric. It is also stationary, meaning that nothing about the spacetime is time-dependent (for example, the time  $t$  does not appear explicitly in the line element;  $dt$  does, but what we mean is that none of the coefficients of  $dt^2$ ,  $dr^2$ , etc., depend on  $t$ ). Now, in general in physics, any time you have a symmetry (for the pedants: you actually need a differentiable symmetry) you have a conserved quantity. **Ask class:** for a particle or photon moving under just the influence of gravity, what are some quantities that will be conserved in the motion of that particle, if the source of gravity is a time-independent point? As with any time-independent central force, energy and angular momentum will be conserved. These follow from, respectively, the symmetry with time and the symmetry with angle. In addition, the rest mass is conserved (more on that later). We have three conserved quantities, and four components to the motion, so if we knew one more we’d be set. Luckily, having spherical symmetry means that we can define a plane of motion for a single particle, so we only have three components to the motion (in particular, we might as well define the plane of motion to be the equatorial plane, so that  $\theta = \pi/2$  and we don’t have to worry about motion in the  $\theta$  direction). That means our task is eased when we follow (and check) geodesic motion in the Schwarzschild spacetime from the conserved quantities.

*Test particle.*—Here we pause briefly to define the concept of a *test particle*. This is useful in thinking about the effect of spacetime on the motion of objects. A test particle is something that reacts to fields or spacetime or whatever, but does not affect them in turn. In practice this is an excellent approximation in GR whenever the objects of interest have much less mass than the mass of the system; this applies, for example, to gas in accretion disks.

We can now think some more about four-velocity. This is a good time to show a useful technique, which is the computation of quantities in a reference frame where they are particularly simple.

We'll start with the four-momentum  $p^\alpha$ . From special relativity, you know that the time component is  $E$ , and the space component is the ordinary 3-momentum, call it  $\mathbf{P}$ . Let's consider the square of this four-momentum,  $p^\alpha p_\alpha = g_{\alpha\beta} p^\alpha p^\beta$ . Assume we have gone into a local Lorentz frame, so that  $g_{\alpha\beta} = \eta_{\alpha\beta}$  locally (but not necessarily globally; think about a very small portion of a sphere, which we can treat as locally flat). Then  $p^2 = p^\alpha p_\alpha = -E^2 + P^2$ . Of course, we can boost into another Lorentz frame in which the particle is not moving (assuming it's not a photon). **Ask class:** what's the square of the four-momentum then? In that frame,  $P = 0$ , so the square is just  $-E^2$ . But then the total energy is just the rest mass energy, so  $p^\alpha p_\alpha = -m^2 c^4$ . Now, the last step. **Ask class:** what kind of geometric object is  $p^\alpha p_\alpha$ ? Is it a scalar, vector, tensor, what? No free indicies, so this is a scalar and its value is the same in any Lorentz frame. Therefore, in general  $p^2 = -m^2$ , so we end up with  $-m^2 = -E^2 + P^2$ , or  $E^2 = m^2 + p^2$ . With units, it's just the famous equation  $E^2 = m^2 c^4 + p^2 c^2$ .

If you divide the four-momentum by the mass  $m$  you get the four-velocity  $u$ , at least for particles with nonzero rest mass. This means that for massive particles,  $u^2 = u^\alpha u_\alpha = -1$ . This leads to a cool proof. **Ask class:** what is the derivative of  $u^\alpha u_\alpha$ ? Since it's the derivative of  $-1$ , a constant, the derivative is zero! But if you write it out, the derivative is also twice the dot product of the four-velocity with the four-acceleration. Therefore, the four-acceleration is always orthogonal to the four-velocity (this is true in general, not just for motion under gravity).

Note the distinction from three-acceleration. In three-space, the acceleration could have a component parallel to the three-velocity (i.e., acceleration can speed something up or slow it down). If the three-acceleration is *perpendicular* to the three-velocity, then the speed doesn't change; think, for example, about uniform-speed motion in a circle, where the velocity changes but the speed doesn't because the acceleration is always pointed at the center of the circle, which is perpendicular to the velocity (which follows the tangent of the circle). What we're saying here is that the four-acceleration is *always* perpendicular to the four-velocity. You don't need to arrange this specially, and the argument is that because the magnitude of

the four-velocity is always the same, it has to be that the four-acceleration is perpendicular to the four-velocity, in the same way that uniform speed implies perpendicularity between the three-acceleration and the three-velocity.

What about a photon? There, the four-momentum is again  $p^2 = -E^2 + P^2$ , but since for a photon  $E = Pc$ , we always have  $p^2 = 0$ .

The four-velocity of a particle with mass can also be written as  $u^\alpha = dx^\alpha/d\tau$ , where  $\tau$  is the proper time (specifically,  $d\tau^2 = -ds^2$  in geometrized units). For a photon, it is trickier, since  $ds^2 = d\tau^2 = 0$  for a photon. We therefore need another way to describe the motion of a photon. The way to do this is to simply define some parameter, call it  $\lambda$ , which checks off the location on a given path of motion (this is called an affine parameter<sup>1</sup>). Then, look at motion with respect to that parameter. Let's think about the four-velocity of a photon.  $u^\alpha = dx^\alpha/d\lambda$ , so the squared four-velocity is  $u^2 = u^\alpha u_\alpha = (dx^\alpha/d\lambda)(dx_\alpha/d\lambda) = g_{\alpha\beta}(dx^\alpha/d\lambda)(dx^\beta/d\lambda) = (g_{\alpha\beta}dx^\alpha dx^\beta)/(d\lambda)^2$ . But the numerator is just the interval traveled by the photon. **Ask class:** what is that interval? It's zero, so (consistent with the squared four-momentum being zero) we find that the squared four-velocity of a photon is zero.

This, therefore, is true for *any* spacetime at all, and even in the presence of other arbitrary forces. For a particle with mass, the squared four-velocity is  $u^2 = -1$ , and for a photon or other massless particle  $u^2 = 0$ .

Let's see an example of how this can help us. In general, for a massive particle,  $u^t = dt/d\tau$ ,  $u^r = dr/d\tau$ ,  $u^\theta = d\theta/d\tau$ , and  $u^\phi = d\phi/d\tau$ . In Schwarzschild coordinates it is also true that  $u_t = -e$ , where  $e$  is the specific energy (energy per mass) of the particle ( $e = 1$  for a particle at rest at infinity) and  $u_\phi$  is the specific angular momentum of the particle. Suppose we have a particle in circular motion, although not necessarily Keplerian. Then there is no  $r$  or  $\theta$  motion and  $u^2 = -1$  gives us  $u^t u_t + u^r u_r + u^\theta u_\theta + u^\phi u_\phi = u^t u_t + u^\phi u_\phi = -1$ . We can put this into a more convenient form by writing  $(g^{t\alpha} u_\alpha) u_t + (g^{\phi\alpha} u_\alpha) u_\phi = -1$ . The Schwarzschild spacetime is diagonal, so this becomes simply  $g^{tt}(u_t)^2 + g^{\phi\phi}(u_\phi)^2 = -1$ . Consulting the line element, and remembering that the inverse of a diagonal matrix is just the original matrix but with the reciprocals of the original elements, we find  $g^{tt} = -1/(1 - 2M/r)$  and  $g^{\phi\phi} = 1/r^2$ , so the specific energy is

$$e = \sqrt{(1 - 2M/r)(1 + u_\phi^2/r^2)}. \quad (4)$$

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<sup>1</sup>What is an affine parameter? I haven't been able to find an easy physical description. In a way that might seem circular but is not, an affine parameter is a parameterization of a geodesic such that the geodesic equation is satisfied. If you have one affine parameter, call it  $\lambda$ , then  $\lambda' = a\lambda + b$  also works if  $a$  and  $b$  are constants. But  $\lambda' = \lambda^2$  wouldn't work. One attempt at a physical explanation is that (1) the proper time is an affine parameter for particles with nonzero rest mass, and (2) if you consider the momentum of a free particle with nonzero rest mass,  $p^\mu = m dx^\mu/d\tau$ , and fix that momentum as  $m \rightarrow 0$ , you can recognize that  $m/d\tau$  remains constant, so you can call that  $1/d\lambda$  where  $\lambda$  is an affine parameter.

For example, for a slowly rotating star with  $u_\phi \approx 0$ , the energy is  $e = \sqrt{1 - 2M/r}$ . This means that a particle of mass  $m$  originally at infinity will release a total energy  $m(1 - e)$  if it finally comes to rest on the star's surface. Let's check if this makes sense in the Newtonian limit  $r \gg M$ . Then  $e \approx 1 - M/r$ , so the energy released is  $mM/r$ , which is the Newtonian form (and recall that here  $G = c = 1$ , so with those constants restored we have an energy release of  $GmM/r$ ).