

FLUID INSTABILITIES

(1)

Frequently we can find a steady solution ($\frac{\partial}{\partial t} = 0$) of the hydrodynamic eqs., representing a long-term config.. Such solutions are typically "smooth" - e.g. circular flow with differential rotation for gas around a star representing a proto-stellar disk, or spherically-stratified solutions for stellar interiors.

In nature, however, small perturbations abound, so it is key to check for stability: will the perturbations remain small and oscillatory or will they grow, ultimately disrupting the basic solution? Or will they saturate, thus producing small-scale structure affecting the long-term flow? (e.g., Turbulence)

⇒ Perturbation Theory: flow consists of a "simple" solution + variations with small amplitude. Then we linearize eqs. to obtain eqs. of motion for perturbations. In many (but not all) situations we can consider the evolution of separate Fourier modes separately: i.e., assume space-time variations $\propto e^{i(\vec{k}\vec{x}-\omega t)}$ and solve eigenvalue ρ for relation among amplitudes (eigenvectors) and dispersion relation (ω - k relation). In some other cases, it's necessary to integrate t-dependent eqs. directly.

①

Sound Waves

②

Perhaps the simplest kind of disturbance. Good example to develop intuition about perturbation theory.

Suppose we have a uniform, adiabatic medium with EOS $P = K \rho^\gamma$ everywhere.

$$\Rightarrow P_0 + P_1 = K(\rho_0 + \rho_1)^\gamma = K\rho_0^\gamma \left(1 + \frac{\rho_1}{\rho_0}\right)^\gamma \approx K\rho_0^\gamma \left(1 + \gamma \frac{\rho_1}{\rho_0}\right)$$

$$P_0 = K\rho_0^\gamma$$

$$P_1 = K\rho_0^\gamma \gamma \frac{\rho_1}{\rho_0} = \gamma \frac{P_0}{\rho_0} \rho_1 = \frac{dP}{dp} \Big|_{\rho_1}$$

We can write the linearized mass and momentum eqs.:)

$$\left[\frac{\partial \rho_0}{\partial t} = 0, \vec{v}_0 = 0 \text{ initial solution steady } \begin{matrix} \text{mass} \\ \text{momentum} \end{matrix}, \rho = \rho_1 + \rho_0 \propto \rho_0 \right]$$

$$\Rightarrow \left\{ \begin{array}{l} \frac{\partial \rho_1}{\partial t} + \nabla_0 \cdot (\vec{v}_1 \rho_0) = 0 \Rightarrow \frac{\partial}{\partial t} \left(\frac{\rho_1}{\rho_0} \right) + \nabla_0 \cdot \vec{v}_1 = 0 \\ \frac{\partial \vec{v}_1}{\partial t} = - \frac{\nabla P_1}{\rho_0} = - \frac{\gamma P_0}{\rho_0} \nabla \left(\frac{\rho_1}{\rho_0} \right) \end{array} \right.$$

$$\downarrow \vec{v}_1 \nabla \vec{v}_1 \sim \text{small } O(2)$$

$$\begin{aligned} \frac{D \vec{v}}{Dt} &= - \frac{\nabla P}{\rho} \\ \frac{\partial}{\partial t} (\rho_0 + \rho_1) + (\rho_0 + \rho_1) \nabla (\rho_0 + \rho_1) &= \nabla \left(\frac{(\rho_0 + \rho_1)}{\rho_0 + \rho_1} \right) \\ \frac{\partial \vec{v}_1}{\partial t} + \vec{v}_1 \nabla \vec{v}_1 + \frac{\rho_1}{\rho_0} \nabla \rho_0 &= - \frac{\nabla P_1}{\rho_0} \end{aligned}$$

$$\text{Assume } \frac{\rho_1}{\rho_0}, \vec{v}_1 \propto e^{i(\vec{k} \cdot \vec{x} - \omega t)}$$

$$\Rightarrow -i\omega \left(\frac{\rho_1}{\rho_0} \right) + i\vec{k} \cdot \vec{v}_1 = 0 \Rightarrow \frac{\rho_1}{\rho_0} = \frac{\vec{k} \cdot \vec{v}_1}{\omega} \quad (1)$$

$$-i\omega \vec{v}_1 = -i\vec{k} \left(\frac{\gamma P_0}{\rho_0} \right) \frac{\rho_1}{\rho_0} \Rightarrow \vec{v}_1 = \frac{\vec{k}}{\omega} \left(\frac{\gamma P_0}{\rho_0} \right) \frac{\rho_1}{\rho_0} \quad (2)$$

$$\Rightarrow \vec{v}_1 = \frac{\vec{k}}{\omega^2} \left(\frac{\gamma P_0}{\rho_0} \right) \bullet \vec{k} \cdot \vec{v}_1 \Rightarrow \text{dot-product with } \vec{k}, \text{ factor } (\vec{k} \cdot \vec{v}_1)$$

(3)

$$\Rightarrow \omega^2 = k^2 \left(\frac{\gamma P_0}{\rho_0} \right) \Rightarrow \omega = \pm \left(\frac{\gamma P_0}{\rho_0} \right)^{1/2} |\vec{k}|$$

This ~~is~~ is a real value \Rightarrow wave propagation is stable

Note That: 1) \vec{v}_i is parallel to \vec{k}

$$2) \text{phase velocity } \omega/|k| = \left(\frac{\gamma P_0}{\rho_0} \right)^{1/2}$$

$$3) \text{group velocity } dw/d|k| = \left(\frac{\gamma P_0}{\rho_0} \right)^{1/2} = c_0$$

This is the sound speed

For \hat{x} along \hat{k} direction, $\vec{r} = v_x \hat{x} \Rightarrow$

- forward prop. wave has $\omega > 0$ and ρ_1/ρ_0 max. at the rest of v_{ix}
- Backward prop. wave has $\omega < 0$ and ρ_1/ρ_0 min at the max of v_{ix}

$$\frac{\rho_1}{\rho_0} = \frac{\vec{k} \cdot \vec{v}_i}{\omega} = \frac{k v_{ix}}{\omega} e^{i(kx - \omega t)}$$

Rayleigh-Taylor instability

(4)

Static stratified atmosphere in external grav. field \vec{g}
 (e.g. stellar interior). We will take the plane-parallel limit.

$$\frac{D\vec{v}}{Dt} = -\frac{\nabla P}{\rho} - \nabla \Phi \Rightarrow$$



$$0 = \frac{1}{\rho} \frac{\partial P}{\partial z} - f(z) \quad \text{static solution}$$

$\vec{v}_0 = 0$ static

$$\left\{ \begin{array}{l} \frac{\partial \vec{v}_1}{\partial t} + \underbrace{\vec{r} \cdot \nabla \vec{v}_1}_{\substack{\text{2nd order} \\ \rightarrow \text{drop}}} = \frac{\nabla P_0}{\rho_0^2} \rho_1 - \frac{\nabla P_1}{\rho_0} \quad \text{moment (1)} \\ \frac{\partial \rho_1}{\partial t} + \nabla \cdot (\vec{v}_1 \rho_0) = 0 \quad \text{mass (2)} \end{array} \right.$$

Internal energy eq.: $\frac{\partial}{\partial t} (\rho \epsilon) + \nabla \cdot (\rho \vec{v} \epsilon) = -P \nabla \cdot \vec{v}$

$$\epsilon = \frac{1}{\gamma-1} \frac{P}{\rho} \quad \text{perfect gas} \Rightarrow \rho \epsilon = \frac{1}{\gamma-1} P$$

Linearizing yields

$$\frac{\partial}{\partial t} \left(\frac{1}{\gamma-1} \rho_1 \right) + \nabla \cdot \left(\frac{1}{\gamma-1} P_0 \vec{v}_1 \right) = -P_0 \nabla \cdot \vec{v}_1 \quad (3)$$

Assume sinusoidal perturbation $\propto e^{i(\vec{k} \cdot \vec{x} - \omega t)}$

$$\nabla \rightarrow i\vec{k}, \quad \frac{\partial}{\partial t} \rightarrow -i\omega$$

$$\Rightarrow \left\{ -i\omega \vec{v}_1 = \frac{\nabla P_0}{\rho_0^2} \rho_1 - \frac{i\vec{k} \cdot \vec{P}_1}{\rho_0} \quad (1) \right.$$

$$\left. -i\omega \rho_1 + i\vec{k} \cdot \vec{v}_1 \rho_0 + \vec{v}_1 \cdot \nabla \rho_0 = 0 \quad (2) \right.$$

$$\left. -i\omega P_1 + i\vec{k} \cdot \vec{v}_1 P_0 + \vec{v}_1 \cdot \nabla P_0 = -(\gamma-1) P_0 (i\vec{k} \cdot \vec{v}_1) \quad (3) \right.$$

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Physical cause: buoyancy

Consider a "blob" in an atmosphere and displace it upward adiabatically.

$$\delta M = g(z_0)(\delta x)^3, \quad P = P(z_0) \text{ @ original location}$$

Assume pressure equilibrium \Rightarrow @ new location

$$P(z + \delta z) = P(z_0) + \delta z \left. \frac{\partial P}{\partial z} \right|_{z_0}$$

Adiabaticity implies:

$$P(z_0) \rho(z_0)^{-\gamma} = \left(P(z_0) + \left. \frac{\partial P}{\partial z} \right|_{z_0} \delta z \right) \left(\rho(z_0) + (\delta \rho)_{\text{blob}} \right)^{-\gamma}$$

$\left[(+) \gamma \sim 1 - \gamma x \right]$
and these 2nd
order terms

$$\left. \frac{1}{P_0} \frac{\partial P}{\partial z} \right|_{z_0} \delta z = \gamma \frac{\delta \rho_{\text{blob}}}{\rho_0} \Rightarrow (\delta \rho)_{\text{blob}} = \frac{1}{\gamma} \frac{\rho_0}{P_0} \left. \frac{\partial P}{\partial z} \right|_{z_0} \delta z$$

The density of the new surroundings is

$$\rho_0(z_0) + \left. \frac{\partial \rho}{\partial z} \right|_{z_0} \delta z \Rightarrow (\delta \rho)_{\text{background}} = \left. \frac{\partial \rho}{\partial z} \right|_{z_0} \delta z$$

\Rightarrow density of blob relative to background is

$$(\delta \rho)_{\text{blob}} - (\delta \rho)_{\text{background}} = \left(\frac{1}{\gamma} \frac{\rho_0}{P_0} \left. \frac{\partial P}{\partial z} \right|_{z_0} - \left. \frac{\partial \rho}{\partial z} \right|_{z_0} \right) \delta z$$

$$= \frac{1}{\gamma} \left(\frac{\partial \ln P \rho^{-\gamma}}{\partial z} \right) \delta z$$

If the blob is underdense, then it will be buoyant and keep rising \Rightarrow The condition for instability is

$$(\delta \rho)_{\text{blob}} - (\delta \rho)_{\text{background}} < 0 \Rightarrow \frac{\partial \ln P \rho^{-\gamma}}{\partial z} < 0$$

\Rightarrow Specific entropy decreases upward, just as we found in the formal analysis.

(5)

$$\Rightarrow \begin{cases} P_1 = \frac{1}{i\omega} \left(P_0(\gamma_0) \vec{k} \cdot \vec{v}_1 + \vec{v}_1 \cdot \nabla P_0 \right) & (3) \\ \vec{v}_1 = \frac{1}{i\omega} \left(\frac{i\vec{k}}{P_0} P_1 - \frac{\nabla P_0}{P_0} \frac{f_1}{f_0} \right) & (4) \\ f_1 = \frac{1}{i\omega} \left(i\vec{k} \cdot \vec{v}_0 + \vec{v}_1 \cdot \nabla P_0 \right) & (2) \end{cases}$$

\Rightarrow After substituting for P_1 in \vec{v}_1 and for f_1 in \vec{v}_1 , and multiplying by $i\omega$, we find:

$$\omega^2 \vec{v}_1 = -\frac{\gamma P_0}{P_0} \vec{k} \cdot \vec{v}_1 \vec{k} + i \vec{v}_1 \cdot \frac{\nabla P_0}{P_0} \vec{k} - \frac{\nabla P_0}{P_0^2} (i\vec{k} \cdot \vec{v}_0 + \vec{v}_1 \cdot \nabla P_0)$$

Simplest case: one component of \vec{k} \parallel to $\nabla P_0, \nabla P_0$ (coll \hat{x})
one component \perp (coll $i\tau \hat{z}$)

$$\Rightarrow -\omega^2 (v_x \hat{x} + v_z \hat{z}) = -\frac{\gamma P_0}{P_0} (k_x v_x + k_z v_z) (k_x \hat{x} + k_z \hat{z}) + i \frac{v_z}{P_0} \frac{\partial P_0}{\partial z} (k_x \hat{x} + k_z \hat{z}) - \frac{1}{P_0^2} \frac{\partial P_0}{\partial z} \hat{z} (i(k_z v_z + k_x v_x) f_0 + v_z \frac{\partial f_0}{\partial z})$$

Evaluating like terms:

$$-\omega^2 v_x + \frac{\gamma P_0}{P_0} (k_x v_x + k_z v_z) k_x - i \frac{v_z}{P_0} \frac{\partial P_0}{\partial z} k_x = 0$$

$$-\omega^2 v_z + \frac{\gamma P_0}{P_0} (k_x v_x + k_z v_z) k_z - i \frac{v_z}{P_0} \frac{\partial P_0}{\partial z} k_z + i \frac{\partial P_0}{\partial z} (k_z v_z + k_x v_x) + \frac{1}{P_0^2} \frac{\partial P_0}{\partial z} v_z \frac{\partial f_0}{\partial z} = 0$$

~~cancel terms~~

After some manipulation, we find that:

$$\frac{v_x}{v_z} = \frac{\frac{\gamma P_0}{P_0} k_z k_x - \frac{i}{P_0} \frac{\partial P_0}{\partial z} k_x}{-\omega^2 + \frac{\gamma P_0}{P_0} k_x^2} = \frac{-\omega^2 + \frac{\gamma P_0}{P_0} k_z^2 + \frac{1}{P_0^2} \frac{\partial P_0}{\partial z} \frac{\partial P_0}{\partial z}}{\frac{\gamma P_0}{P_0} k_x k_z + \frac{i}{P_0} \frac{\partial P_0}{\partial z} k_x} \quad (6)$$

Some more manipulation yields a quadratic equation in ω

$$(\omega^2)^2 - \omega^2 C_0^2 \left(k^2 + \frac{1}{\gamma} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln P_0}{\partial z} \right) + (C_0^2)^2 \left(\frac{1}{\gamma} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln P_0}{\partial z} - \frac{1}{\gamma^2} \left(\frac{\partial \ln P_0}{\partial z} \right)^2 \right)$$

$k_x = 0$

That has the solutions

$$\omega^2 = \frac{1}{2} \left[C_0^2 \left(k^2 + \frac{1}{\gamma} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln P_0}{\partial z} \right) \pm \left[C_0^4 \left(k^2 + \frac{1}{\gamma} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln P_0}{\partial z} \right)^2 - 4 C_0^2 \cdot k_x \left(\frac{1}{\gamma} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln P_0}{\partial z} - \frac{1}{\gamma^2} \left(\frac{\partial \ln P_0}{\partial z} \right)^2 \right) \right]^{1/2} \right]$$

Instability requires $\omega^2 < 0$, so ~~the $\omega^2 = \frac{1}{2} \left[C_0^2 \left(k^2 + \frac{1}{\gamma} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln P_0}{\partial z} \right) + \left[C_0^4 \left(k^2 + \frac{1}{\gamma} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln P_0}{\partial z} \right)^2 - 4 C_0^2 \cdot k_x \left(\frac{1}{\gamma} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln P_0}{\partial z} - \frac{1}{\gamma^2} \left(\frac{\partial \ln P_0}{\partial z} \right)^2 \right) \right]^{1/2}$~~
~~term under square root is always positive~~ ω^2 has the form $A \pm \sqrt{A^2 + B}$
 $\Rightarrow B > 0$

$$\Rightarrow k_x^2 \left[\frac{1}{\gamma^2} \left(\frac{\partial \ln P_0}{\partial z} \right)^2 - \frac{1}{\gamma} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln P_0}{\partial z} \right] > 0$$

$$\Rightarrow k_x^2 \neq 0 \text{ and } \frac{1}{\gamma^2} \frac{\partial \ln P_0}{\partial z} \left(\frac{\partial \ln P_0}{\partial z} - \gamma \frac{\partial \ln P_0}{\partial z} \right) > 0$$

$$\Rightarrow \frac{1}{\gamma^2} \frac{\partial \ln P_0}{\partial z} \left(\frac{\partial \ln P_0}{\partial z} - \gamma \frac{\partial \ln P_0}{\partial z} \right) > 0$$

Since $\frac{\partial \ln P_0}{\partial z} < 0$ for atm. in grav. field ($\frac{\partial P_0}{\partial z} = -\gamma g(z)$)

$$\Rightarrow \text{need } \boxed{\frac{\partial \ln(P_0 \gamma^{-1})}{\partial z} < 0}$$

\Rightarrow Entropy must decrease with increasing height. ($S \propto \ln(P \gamma^{-1})$)

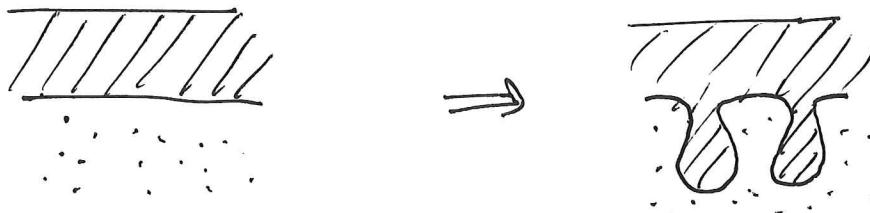
This is Schwarzschild's criterion for convective instability.

Key physical concept: entropy is buoyant.

If the entropy gradient is opposite to the gradient of the grav. field Then the medium is stable; if the entropy gradient is the same as gravity, then is unstable.

Particularly important example: interface where density increases upward, with P constant

$$\Rightarrow \frac{\partial \ln(P\phi_0^{-\gamma})}{\partial z} = -\gamma \underbrace{\frac{\partial \ln \phi_0}{\partial z}}_{>0} < 0 \Rightarrow \text{unstable}$$



Rayleigh-Taylor
"fingers" of
heavy material
penetrating light
material

\Rightarrow Phenomenon is at the heart of convection instabilities: high opacity traps radiation, creating an adverse entropy gradient leading to convective instability.

The same general effect is responsible for the fact that expanding SN shell breaks up in pieces (with acceleration playing the role of gravity).

(Later we'll see an analog of this with \vec{B} playing the role of entropy)

Note that requiring $k_x \neq 0$ is crucial \Rightarrow needs some flow \perp to gravity in order for overturning / mixing to occur

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If we assume $k_z = 0 \Rightarrow$

$$\omega^2 = c_0^2 \left(k_z^2 + \frac{1}{\rho} \frac{\partial \ln P_0}{\partial z} \frac{\partial \ln \rho_0}{\partial z} \right) \times \left\{ \begin{array}{l} 0 \\ \text{R} \end{array} \right.$$

\Rightarrow sound waves modified by pressure and density gradients ("R") or zero-buoyancy horizontal displacement ("0")
 (with $v_{z0} = 0$, $\gamma_x = \text{const}$, and $\frac{1}{\rho} \frac{\partial P_0}{\partial z} = i k_z \frac{P_0}{\rho_0} \frac{f_0}{f_1}$)

KELVIN-HELMHOLTZ instabilities

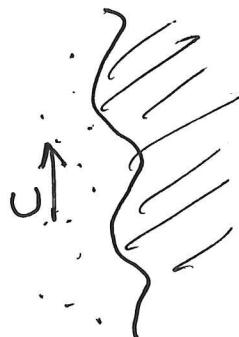
Associated with the presence of a discontinuity in a velocity field. E.g., interface between a rapid stream and slowly moving material.

$$\Delta_{\text{ripple}} = \frac{2\pi}{k} \Rightarrow \text{growth rate of perturbation is } \gamma = \frac{k U}{1+r} r^{1/2}$$

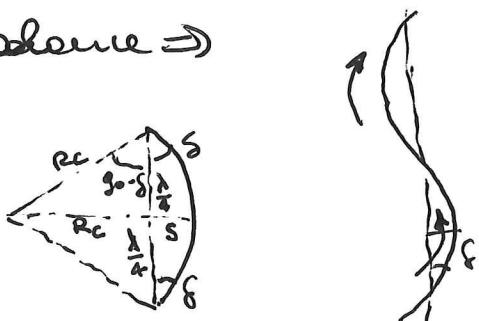
$$\text{where } r = \rho_A / \rho_B$$

\Rightarrow maximum growth if

$$\rho_A = \rho_B$$



Reason for growth: centrifugal effect. If initially in pressure balance \Rightarrow



bending of interface causes force

$$\sim \frac{U^2}{R_C} \quad \frac{\lambda/4}{R_C} = \sin \theta \quad \sim \theta$$

with $R_C \sim \frac{\lambda/4}{\theta}$ radius of curvature
 $s = s_0 e^{i\omega t - k_R z}$

$$\Rightarrow \frac{\text{force}}{\text{mass}} \sim \frac{U^2 \theta}{\lambda/4}, \text{ displacement } s \sim \theta \lambda/4 \Rightarrow \ddot{s} \sim U^2 \theta / (\lambda/4) \downarrow$$

$$\Rightarrow -\omega^2 \theta \lambda/4 \sim U^2 \theta / \lambda \Rightarrow \omega^2 \sim -(U/\lambda)^2 \Rightarrow \gamma \sim U/\lambda$$

$\sim U \Omega^2$

Tends to increase θ

$$(\lambda = \frac{2\pi}{k})$$

④ Rotational Infall

(10)

What about rotational motion? Is it stable?

Ignore p gradients and buoyancy effects.

Consider only eqs. of motion of fluid elements:

$\vec{\zeta}$ ≡ displacement of fluid element from initial position

③ $\vec{R}_0, \vec{\Omega}$ ang. velocity of rot. frame.

$$\vec{\xi} = \frac{d\vec{\zeta}}{dt} + \vec{\Omega} \times (\vec{\zeta} + \vec{R}_0) = \frac{D\vec{\zeta}}{Dt}$$

$$\vec{\alpha} = \frac{d^2\vec{\zeta}}{dt^2} + \vec{\Omega} \times \frac{d\vec{\zeta}}{dt} + \vec{\Omega} \times \left(\frac{d\vec{\zeta}}{dt} + \vec{\Omega} \times (\vec{\zeta} + \vec{R}_0) \right) = \frac{D^2\vec{\zeta}}{Dt}$$

$$\Rightarrow \vec{\alpha} = \ddot{\vec{\zeta}} + 2\vec{\Omega} \times \dot{\vec{\zeta}} + \vec{\Omega} \times (\vec{\Omega} \times (\vec{\zeta} + \vec{R}_0))$$

$$\text{Assume } \vec{\Omega} \cdot \dot{\vec{\zeta}} = 0, \vec{\Omega} \cdot \vec{R}_0 = 0$$

$$\Rightarrow \vec{\alpha} = \ddot{\vec{\zeta}} + 2\vec{\Omega} \times \dot{\vec{\zeta}} - \vec{\Omega}^2 \vec{\zeta} - \vec{\Omega}^2 \vec{R}_0$$

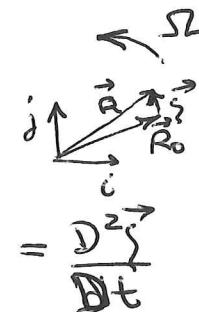
$$\text{Force is } -\nabla \Phi \Big|_{\vec{R} = \vec{R}_0 + \vec{\zeta}} = -\nabla \Phi(\vec{R})$$

$$|\vec{R}|^2 = |\vec{R}_0 + \vec{\zeta}|^2 \approx R_0^2 + 2\vec{R}_0 \cdot \vec{\zeta} \Rightarrow |\vec{R}| \approx (R_0^2 + 2\vec{R}_0 \cdot \vec{\zeta})^{1/2} \approx R_0 \left(1 + \frac{\vec{R}_0 \cdot \vec{\zeta}}{R_0^2}\right) = R_0 + \frac{\vec{R}_0 \cdot \vec{\zeta}}{R_0}$$

$$\vec{F} = \left(-\frac{\partial \Phi}{\partial \vec{R}} \Big|_{R_0} - \frac{\partial^2 \Phi}{\partial \vec{R}^2} \frac{\vec{R}_0 \cdot \vec{\zeta}}{R_0} \right) \hat{\vec{R}} \quad (\text{to first order})$$

$$\hat{\vec{R}} = (R_0 + \zeta_r) \hat{\vec{r}} + \zeta_\varphi \hat{\vec{\varphi}} \Rightarrow |\hat{\vec{R}}| = (R_0^2 + 2R_0 \zeta_r)^{1/2} = R_0 \left(1 + \frac{\zeta_r}{R_0}\right) = R_0 + \zeta_r$$

$$\hat{\vec{R}} = \frac{\vec{R}}{|\vec{R}|} = \frac{\vec{R}}{R_0 + \zeta_r}$$



Lagrangian approach

$$\hat{\vec{R}} \approx \frac{\text{Rot}}{\text{Rot}} \vec{r} \cdot \hat{\vec{r}} + \frac{\zeta_\varphi}{R_0} \hat{\vec{\varphi}} = \hat{\vec{r}} + \frac{\zeta_\varphi}{R_0} \hat{\vec{\varphi}}$$

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Using sinusoidal solutions: $\frac{d}{dt} \rightarrow i\omega$

$$\Rightarrow \vec{\alpha} = -\nabla\Phi \rightarrow -\omega^2 \vec{\zeta} + 2i\omega \vec{\Omega} \times \vec{\zeta} - \Omega^2 \vec{\zeta} - \Omega^2 R_0 \hat{\vec{r}} = -\left(\frac{\partial \Phi}{\partial R} \Big|_{R_0} + \frac{\partial^2 \Phi}{\partial R^2} \Big|_{R_0} \zeta_r\right) (\hat{\vec{r}} + \frac{\zeta_\varphi}{R_0} \hat{\vec{\varphi}})$$

$$\begin{cases} -\omega^2 \zeta_r - 2i\omega \Omega \zeta_\varphi - \Omega^2 \zeta_r - \Omega^2 R_0 = -\left(\frac{\partial \Phi}{\partial R} \Big|_{R_0} + \frac{\partial^2 \Phi}{\partial R^2} \Big|_{R_0} \zeta_r\right) \\ -\omega^2 \zeta_\varphi + 2i\omega \Omega \zeta_r - \Omega^2 \zeta_\varphi = -\frac{\partial \Phi}{\partial R} \Big|_{R_0} \cdot \frac{\zeta_\varphi}{R_0} \end{cases}$$

$$\Rightarrow \zeta_\varphi \left(-\omega^2 - \Omega^2 + \frac{\partial \Phi}{\partial R} \Big|_{R_0} \right) = -2i\omega \zeta_r \Omega$$

$$-\Omega^2 R_0 = -\frac{\partial \Phi}{\partial R} \Big|_{R_0} \quad \left. \begin{array}{l} \text{centrifugal =} \\ \text{for attractive} \\ \text{for steady solution} \end{array} \right\}$$

$$-\omega^2 \zeta_r - 2i\omega \Omega \zeta_\varphi - \Omega^2 \zeta_r = -\frac{\partial^2 \Phi}{\partial R^2} \Big|_{R_0} \zeta_r$$

$$\Rightarrow \zeta_\varphi = \frac{2i\omega \Omega}{\omega^2} \zeta_r = \frac{2i\Omega}{\omega} \zeta_r$$

$$\zeta_r \left(-\omega^2 - \Omega^2 + \frac{\partial^2 \Phi}{\partial R^2} \Big|_{R_0} \right) = 2i\omega \Omega \zeta_\varphi = 2i\omega \Omega \left(\frac{2i\Omega}{\omega} \right) \zeta_r$$

$$\Rightarrow -\omega^2 - \Omega^2 + \frac{\partial^2 \Phi}{\partial R^2} \Big|_{R_0} = -(2\Omega)^2$$

$$\Rightarrow \omega^2 = 3\Omega^2 + \frac{\partial^2 \Phi}{\partial R^2} \Big|_{R_0} = 3\Omega^2 + \frac{2}{\partial R} (-\Omega^2 R) = 4\Omega^2 + R \frac{d\Omega^2}{dR}$$

$$\Rightarrow \omega^2 = \frac{1}{R^3} \frac{d}{dR} (\Omega^2 R^4) = k^2, \text{ The } \text{epicyclic frequency squared}$$

$$\frac{f^2}{R^2} = \frac{1}{R^3} \frac{d}{dR} (\bar{J}^2) \quad \bar{J} = \Omega R^2 = \text{specific angular mom.}$$

(12)

Instability occurs for $\omega^2 < 0 \Leftrightarrow$ if specific angular momentum decreases outward

Typical rotating systems:

$$\text{Kepler has } \Omega \propto R^{-3/2} \Rightarrow \bar{J} \propto R^{1/2} \text{ increasing outward}$$

$$\text{Galaxy with constant vel. rot. curve has } \Omega \propto \bar{R}^{-1} \Rightarrow \bar{J} \propto R \text{ increasing}$$

So, for generic cases rotational motion is stable

The condition $\frac{d}{dR} (\Omega^2 R^4) > 0$ for stability is known as "Rayleigh's criterion"

3D Grav. instability

Standard Treatment introduced by Sir James Jeans.

Unperturbed state: uniform density and temp. medium with no grav. forces

This is not self consistent: no equilibrium is possible in infinite medium against self gravity w/o pressure gradients.

Nevertheless, it does produce the correct answer for whether instability would occur.

$$\text{uniform, adiabatic medium: } P = K \rho T \Rightarrow P_0 + P_1 = K \rho_0 T \left(1 + \frac{P_1}{\rho_0} \right)$$

$$\Rightarrow P_1 = \frac{\gamma P_0}{\rho_0} \rho_1 \stackrel{\Delta}{=} c_0^2 \rho_1, \quad c_0^2 = \frac{\gamma P_0}{\rho_0} \text{ square of sound speed}$$

Mass continuity:

$$\textcircled{1} \quad \frac{\partial \rho_1}{\partial t} + \nabla \cdot (\rho_0 \vec{v}_1) = 0$$

Momentum conservation:

$$\textcircled{2} \quad \frac{\partial \vec{v}_1}{\partial t} = -\frac{\nabla P_1}{\rho_0} - \nabla \Phi_1$$

Gravity:

$$\textcircled{3} \quad \nabla^2 \Phi_1 = 4\pi G \rho_1 \quad \begin{matrix} \text{Jeans} \\ (\text{check: does } \nabla^2 \Phi_0 = 4\pi G \rho_0) \end{matrix}$$

Eq. of state:

$$\textcircled{4} \quad P_1 = c_0^2 \rho_1$$

Ausatz is $\propto e^{i(\vec{k} \cdot \vec{x} - \omega t)}$

$$\Rightarrow \begin{cases} -i\omega \rho_1 + i\vec{k} \cdot \vec{v}_1, \rho_0 = 0 & (1) \\ -i\omega \vec{v}_1 = -i\vec{k} \frac{P_1}{\rho_0} - i\vec{k} \Phi_1 & (2) \\ -k^2 \Phi_1 = 4\pi G \rho_1 & (3) \\ P_1 = c_0^2 \rho_1 & (4) \end{cases}$$

$$\Rightarrow (1) \Rightarrow \frac{\rho_1}{\rho_0} = \frac{\vec{k} \cdot \vec{v}_1}{\omega} \xrightarrow{\text{as for sound waves}} ; \quad (4) \Rightarrow \frac{P_1}{\rho_0} = \frac{c_0^2}{\omega} \vec{k} \cdot \vec{v}_1$$

$$(3) \Rightarrow \Phi_1 = -\frac{4\pi G \rho_0}{k^2} \frac{\vec{k} \cdot \vec{v}_1}{\omega}$$

$$\Rightarrow \text{Plugging them into (2)} \Rightarrow -i\omega \vec{v}_1 = -i\vec{k} \frac{c_0^2}{\omega} \vec{k} \cdot \vec{v}_1 - i\vec{k} \cdot \left(\frac{-4\pi G \rho_0}{k^2} \cdot \frac{\vec{k} \cdot \vec{v}_1}{\omega} \right)$$

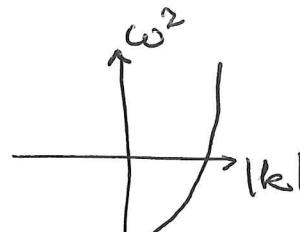
Multiply by $i\omega \Rightarrow$

$$\omega^2 \vec{v}_i = \vec{k} c_0^2 \vec{k} \cdot \vec{v}_i - 4 \frac{\pi G \rho_0}{k^2} \vec{k} \cdot \vec{k} \cdot \vec{v}_i$$

Dot-product with $\vec{k} \Rightarrow$

$$\omega^2 = k^2 c_0^2 - 4 \pi G \rho_0$$

\Rightarrow For $|k| < \left(\frac{4 \pi G \rho_0}{c_0^2} \right)^{1/2} \equiv k_J$ This is unstable



$$\text{Jeans wavelength } d_J \triangleq \frac{2\pi}{k_J} = 2\pi \left(\frac{c_0^2}{4\pi G \rho_0} \right)^{1/2} = c_0 \left(\frac{\pi}{G \rho_0} \right)^{1/2}$$

If $d > d_J \Rightarrow$ Those scales are unstable

$$\omega^2 = c_0^2 (k^2 - k_J^2)$$

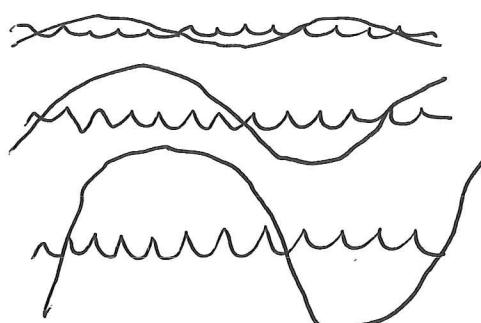
$$\text{Growth rate } \gamma \equiv |\omega| = c_0 (k_J^2 - k^2)^{1/2} \text{ for } k < k_J$$

~~$$\propto \text{scale} \propto (d/d_J)^{1/3}$$~~

\Rightarrow Growth rate \uparrow for $d \uparrow$

\Rightarrow Small scale perturbations inside large scale perturb. end up getting swallowed-up in the large scale collapse (unless their amplitude is initially larger \rightarrow not usually the case)

big one grows
faster than
small one



Most unstable wavelength is that of the whole medium, if $L > d_J$, which has unphysical unperturbed state. The actual growth rate won't be accurate, but the question of instability is still ok.

$$\text{Mass inside } d_J^3 \text{ box is } M_J \approx \rho_0 c_0^3 \left(\frac{\pi}{6\rho_0} \right)^{3/2}$$

Physical interpretation: Consider its grav. potential

$$\Phi \sim -\frac{6\pi}{d} \sim -\frac{6d^3\rho_0}{d} \sim 6d^2\rho_0$$

Specific thermal energy of fluid element

$$\frac{3}{2} \frac{kT}{\mu} \sim c_s^2$$

If $c_s^2 > -\Phi_g$ \Rightarrow expect unbound

$c_s^2 < -\Phi_g$ \Rightarrow expect bound

$$\Rightarrow c_s^2 = 6d^2\rho_0 \quad c_s \left(\frac{1}{6\rho} \right)^{1/2} = \left(\frac{c_s^2}{6\rho} \right)^{1/2} = d$$

$$\Rightarrow d_J \approx c_s \left(\frac{\pi}{6\rho} \right)^{1/2}$$

Density waves and the grav. instab. of rotating gas disks

We looked ②: rotating media w/o pressure

self-gravitating media w/ pressure but w/ rot.

Stability of galactic or protostellar disks?

We'll consider only axisymmetric ($\frac{\partial}{\partial \varphi} = 0$), since non-axisymmetric disturbances don't have modes $\propto e^{i(\vec{k}\vec{r}-\omega t)}$.

Eqs. of motion: Treat as locally uniform pressure and density with adiabatic / isothermal eos.

$\Delta \ll R \Rightarrow$ neglect curvature terms, using $\frac{1}{R} \ll k$

$$z\text{-integrate} \Rightarrow \rho \rightarrow \Sigma = \rho H$$

$$P \rightarrow \Pi = P H$$

Perturbations are $\propto e^{i(\vec{k}(R-R_0)\hat{R} - \omega t)}$
radial

$$\nabla = \left(\frac{\partial}{\partial r}, \frac{1}{r} \frac{\partial}{\partial \varphi}, \frac{\partial}{\partial z} \right)$$

$$\nabla_0 \vec{r} = \left(\frac{\partial}{\partial r}, \frac{\partial}{\partial r} (\vec{r} \cdot \vec{v}_0) + \frac{1}{r} \frac{\partial \vec{v}_0}{\partial \varphi} \right)$$

$$\frac{\partial \Sigma_i}{\partial t} + \nabla_0 \cdot (\Sigma_0 \vec{v}_i) = 0 \Rightarrow \frac{\partial \Sigma_i}{\partial t} = -\Sigma_0 \nabla \cdot \vec{v}_i \quad (\nabla \Sigma_0 = 0 \text{ uniform})$$

$$\Rightarrow \boxed{-i\omega \Sigma_i = -\Sigma_0 i k_r v_{iR}} \quad (\text{drop } \frac{v_{iR}}{R} \text{ term})$$

$$\frac{\partial \vec{v}_i}{\partial t} + (\vec{v}_i \cdot \nabla) \vec{v}_0 + \vec{v}_0 \cdot \nabla \vec{v}_i = -\frac{\nabla \Pi_i}{\Sigma_0} - \nabla \Phi_i$$

$$\frac{\partial \vec{v}_i}{\partial t} = \underbrace{\left(-\left(\frac{v_{iR}}{R} \frac{\partial}{\partial \varphi} + v_{iR} \frac{\partial}{\partial R} \right) (\Omega R \hat{\varphi}) \right)}_{\vec{v}_0 \cdot \nabla \vec{v}_i} - \underbrace{\left(\frac{\Omega R}{R} \frac{\partial}{\partial \varphi} \right) (v_{i\varphi} \hat{\varphi} + v_{iR} \hat{R})}_{\vec{v}_0 \cdot \nabla \vec{v}_i} - \frac{\nabla \Pi_i}{\Sigma_0} - \nabla \Phi_i$$

$$= 2\Omega v_{ir} \hat{R} - v_{ir} \frac{\partial}{\partial R} [(\Omega R) \hat{\varphi}] - \Omega v_{ir} \hat{\varphi} - \frac{\nabla \Pi_1}{\Sigma_0} - \nabla \Phi, \quad (17)$$

$\left[\frac{\partial \hat{R}}{\partial \hat{\varphi}} = \hat{x}, \quad \frac{\partial \hat{\varphi}}{\partial \hat{r}} = -\hat{R} \right]$

$$\left. \begin{aligned} -i\omega v_{ir} &= 2\Omega v_{ir} - ik \Pi_1 - ik \Phi_1 \\ -i\omega v_{ir} &= -v_{ir} \frac{\partial}{\partial R} (\Omega R) - \Omega v_{ir} \end{aligned} \right\}$$

$$\Pi_1 = C^2 \Sigma_1 \leftarrow \text{adiabatic eos}$$

$$\text{Poisson: } \nabla^2 \Phi_1 = 4\pi G \rho_1 \quad \rightarrow \text{assume thin disk} \quad \begin{array}{c} \rho_1 = 0 \\ \rho_1 \neq 0 \\ \rho_1 = 0 \end{array}$$

$$\text{Above and below disk } \rho_1 = 0 \Rightarrow \left(\frac{\partial^2}{\partial z^2} + \nabla_{\text{plane}}^2 \right) \Phi_1 = 0$$

$$\Phi_1 = e^{ikx} f(z) \text{ by assumption } (x \equiv R - R_0)$$

$$-k^2 f + \frac{\partial^2 f}{\partial z^2} = 0 \Rightarrow f \propto e^{\pm ikz}$$

$$\text{Want to have } f \rightarrow 0 \text{ for } z \rightarrow \infty \Rightarrow f \propto e^{-|kz|}$$

$$\Rightarrow \Phi_1(x, z) = \Phi_k e^{ikx} e^{-|kz|}$$

Take $\nabla^2 \Phi_1 = 4\pi G \rho_1$ and integrate from below to above the plane

$$\int dz \left(\frac{\partial^2 \Phi_1}{\partial z^2} \right) = \int 4\pi G \rho_1 dz$$

$$\Rightarrow 2 \left. \frac{\partial \Phi_1}{\partial z} \right|_{z=0^+} = 4\pi G \Sigma_1$$

$$\Phi_1 \propto e^{-|kz|} \text{ for } z > 0 \Rightarrow -2|k| \Phi_1 = 4\pi G \Sigma_1$$

$$\Rightarrow \boxed{\Phi_1 = -\frac{2\pi G \Sigma_1}{|k|}}$$

$$\Sigma_1 = \frac{\Sigma_0 k v_{ir}}{\omega}$$

$$\Rightarrow v_{ir} = -\frac{i}{\omega} \left[\frac{1}{R} \frac{d}{dR} (\Omega R^2) \right] v_{ir}$$

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$$\Phi_1 = -\frac{2\pi G \sum_1}{|k_1|} = -\frac{2\pi G}{|k_1|} \frac{\sum_0 k}{\omega} v_{ir}$$

$$-i\omega v_{ir} = 2\Omega \left(\frac{-i}{\omega R} \frac{d(\Omega R^2)}{dR} \right) v_{ir} - \frac{ik}{\sum_0} c_0^2 \sum_0 k v_{ir} - ik \left(-\frac{2\pi G \sum_0 k}{\omega |k_1|} \right) v_{ir}$$

\Rightarrow multiplying by $i\omega$:

$$\omega^2 = \frac{2\Omega}{R} \frac{d}{dR} (\Omega R^2) + c_0^2 k^2 - \frac{k^2}{|k_1|} 2\pi G \sum_0$$

$$= \frac{1}{R^3} \frac{d}{dR} ((\Omega R^2)^2) + c_0^2 k^2 - |k_1| 2\pi G \sum_0$$

$$\Rightarrow \boxed{\omega^2 = c_0^2 k^2 + k_1^2 - 2\pi G \sum_0 |k_1|}$$

density wave
dispersion relation

For $\begin{cases} P=0 \\ \text{self-gravity}=0 \end{cases}$ ($c_0^2=0$) we get back $\omega^2 = k_1^2$ in the "fluid particle" treatment of rotation

For no rotation and no self gravity $\Rightarrow \omega^2 \propto k^2$ sound waves

More generally:

- restoring force from rotation (k_1^2)
- " " " " pressure ($c_0^2 k^2$)
- destabilizing " " gravity ($2\pi G \sum_0 |k_1|$)

(Just like Jeans', but with $2\pi G \sum_0 |k_1|$ instead of $4\pi G \rho_0$)

$\downarrow_{\text{for } k=0}$

with $K=0$, $\omega^2 = (c_0^2 |k| - 2\pi G \Sigma) / |k|$

\Rightarrow unstable for $|k| < \frac{2\pi G \Sigma}{c_0^2} \equiv k_J$ equiv. to Jeans wave# for thin disk

Stability with $K \neq 0$

Galaxy is unstable to run-away fragmentation if $\min. \text{ of } V_{\omega^2} < 0$

$$\Rightarrow \text{for } |k| = \frac{\pi G \Sigma}{c_0^2} \pm \left(\left(\frac{\pi G \Sigma}{c_0^2} \right)^2 - 4 \frac{K^2}{c_0^2} \right)^{1/2}$$

$$\frac{d \omega^2}{d |k|} = 2 c_0^2 |k| - 2\pi G \Sigma_0$$

$$\Rightarrow (|k|)_{\min} = \frac{\pi G \Sigma_0}{c_0^2} = \frac{k_J}{2}$$

$$\text{At } |k| = k_J/2, \quad \omega^2 = -\left(\frac{\pi G \Sigma}{c_0}\right)^2 + K^2$$

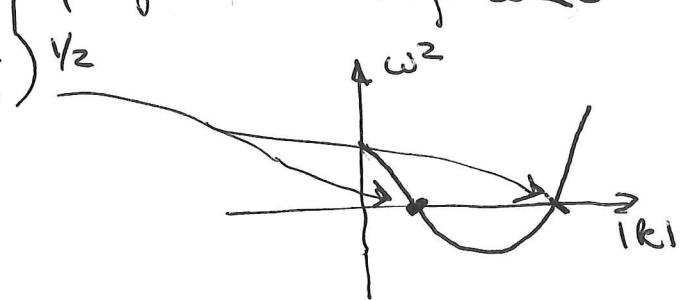
$$\text{So } \omega^2 < 0 \text{ if } K^2 < \left(\frac{\pi G \Sigma}{c_0}\right)^2, \text{ i.e. } \frac{K c_0}{\pi G \Sigma} < 1$$

$\frac{K c_0}{\pi G \Sigma}$ is known as "Toomre's Q"

\Rightarrow Gas in a galaxy disk is unstable/stable to "ring like" fragmentation if $Q < 1 / Q > 1$

For non-axisymmetric perturb. The ~~collapse~~ collapse analysis is more complicated. A process known as "scoring amplification" leads to growth of perturbations.

Woo-Tae Kim's Thesis shows that $Q \lesssim 1.5$ for instability



This value allows for 3D, \vec{B} , and Turbulence in initial conditions.

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With \vec{B} , critical Q is lower (maybe even < 1).

This is smaller than axisymmetric result because finite thickness dilutes gravity: Q_{crit} for thick disk is $< Q_{\text{Toomre}}$.