

Dynamics and how to use the orbits of stars to do interesting things

chapter 3 of S+G- parts of ch 2 of B&T and parts of Ch 11 of MWB (Mo, van den Bosch, White)

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A Guide to the Next Few Lectures

- The geometry of gravitational potentials : methods to derive gravitational potentials from mass distributions, and visa versa.
- Potentials define how stars move
consider stellar orbit shapes, and divide them into orbit classes.
- The gravitational field and stellar motion are interconnected :
the Virial Theorem relates the global potential energy and kinetic energy of the system.
- Collisions?
- The Distribution Function (DF) :
the DF specifies how stars are distributed throughout the system and with what velocities.

For collisionless systems, the DF is constrained by a continuity equation :
the Collisionless Boltzmann Equation

- This can be recast in more observational terms as the Jeans Equation.
The Jeans Theorem helps us choose DFs which are solutions to the continuity equations

A Reminder of Newtonian Physics sec 2.1 in B&T

Newtons law of gravity tells us that two masses attract each other with a force

$$\frac{d}{dt}(m\mathbf{v}) = -\frac{GmM}{r^3}\mathbf{r}$$

$\phi(\mathbf{x})$ is the potential

If we have a collection of masses acting on a mass m_α the force is

$$\frac{d}{dt}(m_\alpha \mathbf{v}_\alpha) = -\sum_\beta \frac{Gm_\alpha M_\beta}{|\mathbf{x}_\alpha - \mathbf{x}_\beta|^3}(\mathbf{x}_\alpha - \mathbf{x}_\beta), \alpha \neq \beta$$

$$\frac{d}{dt}(m\mathbf{v}) = -m\nabla\phi(\mathbf{x}),$$

with

$$\phi(\mathbf{x}) = -\sum_\alpha \frac{Gm_\alpha}{|\mathbf{x} - \mathbf{x}_\alpha|}, \text{ for } \mathbf{x} \neq \mathbf{x}_\alpha$$

Gauss's thm $\int \nabla\phi \cdot d\mathbf{s} = 4\pi GM$
the Integral of the normal component over a closed surface = $4\pi G$ x mass within that surface

the gravitational potential. If we can approximate the discrete stellar distribution with a continuous distribution ρ .

$$\phi(\mathbf{x}) = -\int \frac{G\rho(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} d^3\mathbf{x}'$$

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Conservation of Energy and Angular Momentum

In the absence of external forces a star will conserve energy along its orbit

$$\mathbf{v} \cdot \frac{d}{dt}(m\mathbf{v}) = -m\mathbf{v} \cdot \nabla\phi(\mathbf{x}),$$

$$\mathbf{v} \cdot \frac{d}{dt}(m\mathbf{v}) + m\mathbf{v} \cdot \nabla\phi(\mathbf{x}) = 0$$

But since $\frac{d\phi}{dt} = \mathbf{v} \cdot \nabla\phi(\mathbf{x})$

$$\nabla = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}$$

$$\frac{d}{dt} \left[\frac{m}{2} (\mathbf{v}^2) + m\phi(\mathbf{x}) \right] = 0$$

where $(\hat{x}, \hat{y}, \hat{z})$ are the unit vectors in their respective directions.

This is just the KE + PE

$$\frac{dL}{dt} = \mathbf{x} \times m \frac{d\mathbf{v}}{dt} = -m\mathbf{x} \times \nabla\phi$$

Angular momentum L

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Some Basics - M. Whittle

- The gravitational potential energy is a scalar field
- its gradient gives the net gravitational force (per unit mass) which is a vector field :

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = \nabla \cdot \nabla = \nabla^2$$

$$\Phi(\mathbf{r}) = -G \int_V \frac{\rho(\mathbf{r}')}{|\mathbf{r}' - \mathbf{r}|} d^3\mathbf{r}'$$

$$\mathbf{F}(\mathbf{r}) = -\nabla\Phi(\mathbf{r}) = G \int_V \frac{\mathbf{r}' - \mathbf{r}}{|\mathbf{r}' - \mathbf{r}|^3} \rho(\mathbf{r}') d^3\mathbf{r}'$$

$$\nabla \cdot \mathbf{F}(\mathbf{r}) = -4\pi G\rho(\mathbf{r})$$

$$\nabla^2\Phi(\mathbf{r}) = 4\pi G\rho(\mathbf{r}) \longleftrightarrow \text{Poissons eq inside the mass distribution}$$

$$\nabla^2\Phi(\mathbf{r}) = 0 \longleftrightarrow \text{Outside the mass dist} \quad 5$$

Poisson's Eq+ Definition of Potential Energy (W)

So the force per unit mass is

$\rho(x)$ is the density dist

$$\mathbf{F}(\mathbf{x}) = -\nabla\Phi(\mathbf{x}) = \int G\rho(\mathbf{x}') \frac{(\mathbf{x} - \mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|^3} d^3\mathbf{x}'$$

To get the differential form we start with the definition of Φ and applying ∇^2 to both sides S+G pg 112-113

$$\begin{aligned} \nabla^2\Phi(\mathbf{x}) &= -\nabla^2 \int \frac{G\rho(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} d^3\mathbf{x}' \\ &= 4\pi G\rho(\mathbf{x}) \quad \text{Poisson's equation.} \end{aligned}$$

Potential energy W

$$W = \frac{1}{2} \int_V \rho(\mathbf{r}) \Phi(\mathbf{r}) d^3\mathbf{r} = -\frac{1}{8\pi G} \int_V |\nabla\Phi|^2 d^3\mathbf{r}$$

Derivation of Poisson's Eq

So the force per unit mass is

$$\mathbf{F}(\mathbf{x}) = -\nabla\Phi(\mathbf{x}) = \int G\rho(\mathbf{x}') \frac{(\mathbf{x}-\mathbf{x}')}{|\mathbf{x}-\mathbf{x}'|^3} d^3\mathbf{x}'$$

To get the differential form we start with the definition of Φ and applying ∇^2 to both sides

$$\nabla^2\Phi(\mathbf{x}) = -\nabla^2 \int \frac{G\rho(\mathbf{x}')}{|\mathbf{x}-\mathbf{x}'|} d^3\mathbf{x}'$$

$$= 4\pi G\rho(\mathbf{x})$$

Poisson's equation.

see S+G pg112 for detailed derivation or web page 'Poisson's equation'

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Characteristic Velocities

$v_{\text{circular}}^2 = r \frac{d\Phi(r)}{dr} = GM/r$; $v = \sqrt{GM/r}$ Keplerian

velocity dispersion $\sigma^2 = (1/\rho) \int \rho (\partial\Phi(r,z)/\partial z) dz$

or alternatively $\sigma^2(R) = (4\pi G/3M(R)) \int r\rho(r) M(R) dr$

escape speed $= v_{\text{esc}} = \sqrt{2\Phi(r)}$ or $\Phi(r) = 1/2 v_{\text{esc}}^2$

so choosing r is crucial

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More Newton-Spherical Systems B&T 2.2

Newtons 1st theorem: a body inside a spherical shell has no net gravitational force from that shell; e.g. $\nabla\Phi(r)=0$

Newtons 2nd theorem: the gravitational force on a body outside a spherical shell is the same as if all the mass were at a point at the center of the shell.

Simple examples:

Point source of mass M; potential $\Phi(r) = -GM/r$;

definition of circular speed; speed of a test particle on a circular orbit at radius r

$v_{\text{circular}}^2 = r \, d\Phi(r)/dr = GM/r$; $v_{\text{circular}} = \sqrt{GM/r}$;Keplerian

velocity dispersion $\sigma^2 = (1/\rho) \int \rho (\partial\Phi(r,z)/\partial z) dz$

escape speed $= \sqrt{2\Phi(r)} = \sqrt{2GM/r}$; from equating kinetic energy to potential energy $1/2mv^2 = |\Phi(r)|$

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Escape Speed

- As r goes to infinity $\phi(r)$ goes to zero
- so to escape $v^2 > 2\phi(r)$; e.g. $v_{\text{esc}} = \sqrt{-2\phi(r)}$
- Alternate derivation using conservation of energy
- Kinetic+Gravitational Potential energy is constant
- $KE_1 + U_1 = KE_2 + U_2$
- Grav potential $= -GMm/r$; $KE = 1/2mv_{\text{escape}}^2$
- Since final velocity=0 (just escapes) and U at infinity=0
- $1/2mv_{\text{escape}}^2 - GMm/r = 0$

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Gravity and Dynamics-Spherical Systems- Repeat

- Newtons 1st theorem : a body inside a a spherical shell has no net force from that shell $\nabla\phi = 0$
- Newtons 2nd theorem ; a body outside the shell experiences forces as if they all came from a point at the center of the shell-Gravitational force at a point outside a closed **sphere** is the same as if all the mass were at the center
 - This does not work for a thin disk- cannot ignore what is outside of a given radius
- One of the prime observables (especially for spirals) is the circular velocity; in general it is $V^2(R)/R=G(M<R)/R^2$ more accurate estimates need to know shape of potential
- so one can derive the mass of a flattened system from the rotation curve

- point source has a potential $\phi=-GM/r$
- A body in orbit around this point mass has a circular speed $v_c^2=r \phi/d/dr=GM/r$
- $v_c=\text{sqrt}(GM/r)$; Keplerian
- Escape speed from this potential $v_{\text{escape}}=\text{sqrt}(2\phi)=\text{sqrt}(2GM/r)$ (conservation of energy $KE=1/2mv_{\text{escape}}^2$)

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Homogenous Sphere B&T sec 2.2.2

- Constant density sphere of radius a and density ρ_0
- $M(r)=4\pi Gr^3\rho_0$; $r<a$
- $M(r)=4\pi Ga^3\rho_0$; $r>a$

$$\phi(R)=-d/dr(M(R)) ; \phi(R)=-3/5GM^2/R ; \text{B\&T 2.41}$$

$$R>a \phi(r)=4\pi Ga^3\rho_0=-GM/r$$

$$R<a \phi(r)=-2\pi G\rho_0(a^2-1/3r^2);$$

$$v_{\text{circ}}^2 = (4\pi/3)G\rho_0 r^2 ; \text{solid body rotation } R<a$$

$$\text{Orbital period } T=2\pi r/v_{\text{circ}}=\text{sqrt}(3\pi/G\rho_0)$$

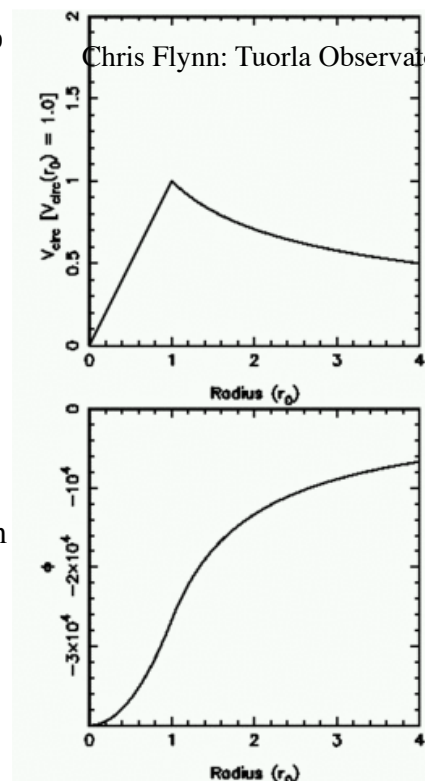
$$\text{Dynamical time}=\text{crossing time } =T/4=\text{sqrt}(3\pi/16G\rho_0)$$

Potential is the same form as an harmonic oscillator with angular freq $2\pi/T$ (B&T 2.2.2(b))

Regardless of r a particle will reach $r=0$ (in free fall) in a time $T=4$

Eq of motion of a test particle INSIDE the sphere is $dr^2/dt^2=-GM(r)/r^2=-(4\pi/3)G\rho_0 r$

General result dynamical time $\sim\text{sqrt}(1/G\rho)$



Some Simple Cases

- **Constant density sphere** of radius a and density ρ_0

Potential energy (B&T) eq 2.41, 2.32

$$\phi(R) = -d/dr(M(R));$$

$$R > a \quad \phi(r) = 4\pi G a^3 \rho_0 = -GM/r$$

$$R < a \quad \phi(r) = -2\pi G \rho_0 (a^2 - 1/3 r^2);$$

$$v_{\text{circ}}^2 = (4\pi/3) G \rho_0 r^2 \text{ solid body rotation}$$

Potential is the same form as a harmonic oscillator

e.g. the eq of motion is $d^2r/dt^2 = -GM(r)/r = 4\pi/3 G \rho r$; solution to harmonic oscillator is

$$r = A \cos(\omega t + \phi) \text{ with } \omega = \sqrt{4\pi/3 G \rho} = 2\pi/T$$

$$T = \sqrt{3\pi/G\rho_0} = 2\pi r/v_{\text{circ}}$$

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Spherical Systems: Homogenous sphere of radius a Summary

- $M(r) = 4/3\pi r^3 \rho$ ($r < a$); $r > a$ $M(r) = 4/3\pi r^3 a$
- Inside body ($r < a$); $\phi(r) = -2\pi G \rho (a^2 - 1/3 r^2)$ (from eq. 2.38 in B&T)

Outside ($r > a$); $\phi(r) = -4\pi G \rho (a^3/3)$

Solid body rotation $v_c^2 = 4\pi G \rho (r^2/3)$

Orbital period $T = 2\pi r/v_c = \sqrt{3\pi/G\rho}$;

a crossing time (dynamical time) $= T/4 = \sqrt{3\pi/16G\rho}$

potential energy $W = -3/5 GM^2/a$

The motion of a test particle inside this sphere is that of a simple harmonic oscillator $d^2r/dt^2 = -G(M(r)/r^2) = 4\pi G \rho r/3$ with angular freq $2\pi/T$

no matter the initial value of r , a particle will reach $r=0$ in the dynamical time $T/4$

In general the dynamical time $t_{\text{dyn}} \sim 1/\sqrt{G\langle\rho\rangle}$

and its 'gravitational radius' $r_g = GM^2/W$

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Star Motions in a Simple Potential

- if the density ρ in a spherical galaxy is constant, then a star following a circular orbit moves so that its angular speed $\Omega(r) = V(r)/r$ is constant.
- a star moving on a radial orbit, i.e., in a straight line through the center, would oscillate harmonically in radius with period
- $P = \sqrt{3\pi/G\rho} \sim 3t_{\text{ff}}$, where $t_{\text{ff}} = \sqrt{1/G\rho}$: S&G sec 3.1

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Not so Simple - Plummer Potential sec 2.2 in B&T

- Many astrophysical systems have a 'core'; e.g. the surface brightness flattens in the center (globular clusters, elliptical galaxies, clusters of galaxies, bulges of spirals) so they have a characteristic length
- so imagine a potential of the form $-\phi(r) = -GM/\sqrt{r^2+b^2}$; where b is the Plummer scale length

$$\nabla^2\Phi(r) = (1/r^2) d/dr(r^2 d\phi/dr) = 3GMb^2/(r^2+b^2)^{5/2} = 4\pi G\rho(r) \text{ Poissons eq}$$

and thus

$$\rho(r) = (3GM/4\pi b^3)[1+(r/b)^2]^{-5/2}$$

Now take limits $r \ll b$ $\rho(r) = (3GM/4\pi b^3)$ constant

$$r \gg b \quad \rho(r) = (3GM/4\pi b^3)r^{-5} \text{ finite}$$

Plummer potential was 'first' guess at modeling 'real' spherical systems; it is one of a more general form of 'polytropes' B&T (pg 300)

Potential energy $W = 3\pi GM^2/32b$

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Spherical systems- Plummer potential

- Another potential with an analytic solution is the Plummer potential - in which the density is constant near the center and drops to zero at large radii - this has been used for globular clusters, elliptical galaxies and clusters of galaxies.
- One such form- Plummer potential
 $\phi = -GM / (\sqrt{r^2 + b^2})$; b is called a scale length

The density law corresponding to this potential is

(using the definition of $\nabla^2 \phi$ in a spherical coordinates)

$$\nabla^2 \equiv \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin^2 \phi} \frac{\partial^2}{\partial \theta^2} + \frac{1}{r^2 \sin \phi} \frac{\partial}{\partial \phi} \left(\sin \phi \frac{\partial}{\partial \phi} \right).$$

$$\nabla^2 \phi = (1/r^2) d/dr (r^2 d\phi/dr) = (3GMb^2) / ((r^2 + b^2)^{5/2})$$

$$\rho(r) = (3M/4\pi b^3) (1 + (r/b)^2)^{-5/2}$$

$$\text{Potential energy } W = -3\pi GM^2/32b$$

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- B&T pgs 65-72 ; there are many more forms which are better and better approximations to the true potential of 'spherical' systems; I will not cover them in detail in the lectures, please read the relevant sections of the text.
- However I will cover 2 others- the **modified Hubble law** which is frequently used for clusters of galaxies
- B&T eq 2.53 starts with the luminosity density $j = j_0 (1 + (r/a)^2)^{-3/2}$
- which gives surface brightness
 $I(r) = 2aj_0 (1 + (r/a)^2)^{-1}$
- at $r = a$; $I(a) = 1/2I(0)$; **a is the core radius**
- Now if light traces mass and the mass to light ratio is constant

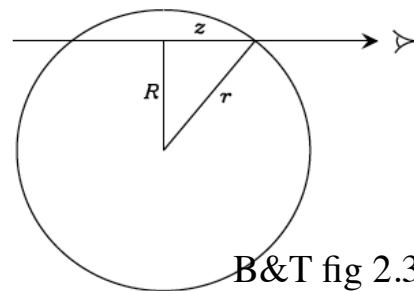
$$M = \int j(r) d^3r =$$

$$4\pi a^3 G j_0 [\ln[R/a + \sqrt{1 + (r/a)^2}] - (r/a)(1 + (r/a)^2)^{-1/2}]$$

$$\text{B\&T eq 2.56}$$

- and the potential is also analytic

Many More Not So Simple Analytic Forms



Problems: mass diverges logarithmically
 BUT potential is finite and at $r \gg a$ is almost GM/r

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Spherical Systems

- A frequently used analytic form for the surface brightness of an elliptical galaxy is the Modified Hubble profile
- $I(R)=2j(o)a/[(1+(r/a)^2]$ which has a luminosity density distribution
 $j(r)=j(0)[(1+(r/a)^2]^{-3/2}$
- this is also called the 'pseudo-isothermal' sphere distribution
- the eq for ϕ is analytic and finite at large r even though the mass diverges (eq. 2.56, 2.57 in B+T)
 $\phi=-GM/r-(4\pi Gj_0a)^2/\text{sqrt}[1+(r/a)^2]$

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Last Spherical Potential

- In the last 15 years numerical simulations have shown that the density distribution of dark matter can be well described by a form called 'NFW' density distribution (B+T eq 2.65)

$$\rho(r)=\rho(0)/[(r/a)^\alpha(1+(r/a))^{\beta-\alpha}] \text{ with } (\alpha,\beta)=(1,3)$$

Integrating to get the mass

$$M(r)=4\pi G\rho(0)a^3\ln[1+(r/a)]-(r/a)/[1+(r/a)]$$

and potential $\phi=[\ln(1+(r/a))]/(r/a)$

See problem 3.7 in S&G

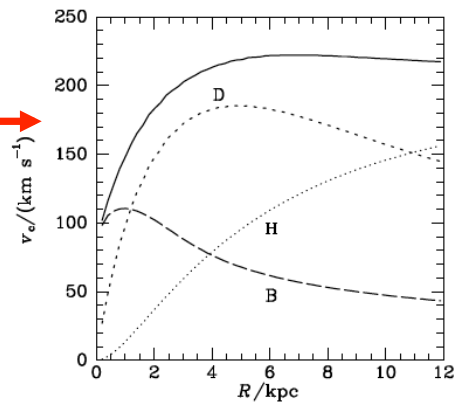
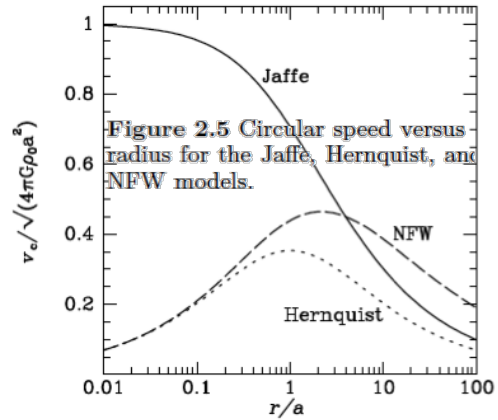
There is a long history of different potentials and B&T goes thru it... no longer relevant to modern work except to improve your skills !

The NFW density distribution is an analytic approximation to numerical simulations of cold dark matter

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Other Forms

- B+T discuss many other forms which are interesting mathematically but are not really relevant to the rest of our class.
- However all the forms so far have a Keplerian rotation $v \sim r^{-1/2}$ while real galaxies have flat rotation curves $v_c(R) = v_0$
- A potential with this property must have $d\phi/dr = v_0^2/R$; $\phi = v_0^2 \ln R + C$
- However this is a rather artificial form; real galaxies seem to be composed of 3 parts: disk (D), bulge (B), halo (H) and it is the sum of the 3 that gives the flat rotation curve (very fine tuned and very flexible)



Summary of Dynamical Equations

- **gravitational pot'l** $\Phi(\mathbf{r}) = -G \int \rho(\mathbf{r}') / |\mathbf{r} - \mathbf{r}'| d^3r'$
 - **Gravitational force** $\mathbf{F}(\mathbf{r}) = -\nabla\Phi(\mathbf{r})$
 - **Poissons Eq** $\nabla^2\Phi(\mathbf{r}) = 4\pi G\rho$; if there are no sources
Laplace Eq $\nabla^2\Phi(\mathbf{r}) = 0$
 - **Gauss's theorem** : $\int \nabla\Phi(\mathbf{r}) \cdot d\mathbf{s} = 4\pi GM$
 - **Potential energy** $W = 1/2 \int \rho(\mathbf{r}) \nabla\Phi d^3r$
- In words Gauss's theorem says that the integral of the normal component of $\nabla\Phi$ over and closed surface equals $4\pi G$ times the mass enclosed

Potentials are Separable

- We make the fundamental assumption that the potential of a system can be decomposed into separable parts-
- This is because Poisson's equation is linear :
- differences between any two $\phi-\rho$ pairs is also a $\phi-\rho$ pair, and differentials of $\phi-\rho$ or ρ are also $\phi-\rho$ pairs
- e.g. $\phi_{\text{total}} = \phi_{\text{bulge}} + \phi_{\text{disk}} + \phi_{\text{halo}}$

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So Far Spherical Systems

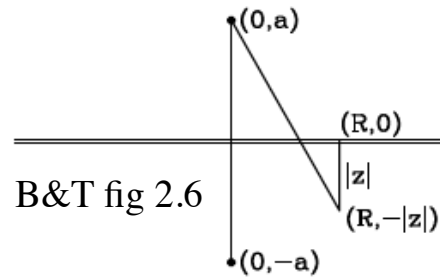
- But spiral galaxies have a significant fraction of the mass (?; at least the baryons) in a flattened system.

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Kuzmin Disk B&T sec 2.3 S&G Prob 3.4;

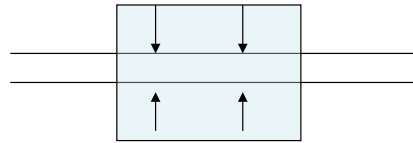
- This ansatz is for a flattened system and separates out the radial and z directions
- Assume $\phi_K(z,R) = GM / [\text{sqrt}(R^2 + (a+z)^2)]$; axisymmetric (**cylindrical**)
R is in the x,y plane
- Analytically, outside the plane, ϕ_K has the form of the potential of a point mass displaced by a distance 'a' along the z axis
– e.q. $R(z) = \begin{cases} (0, a); & z < 0 \\ (0, -a); & z > 0 \end{cases}$
- Thus $\nabla^2 \Phi = 0$ everywhere except along $z=0$ -Poisson's eq
- Applying Gauss's thm $\int \nabla \Phi d^2s = 4\pi GM$ and get $\Sigma(R) = aM / [2\pi(R^2 + a^2)^{3/2}]$

this is in infinitely thin disk... not too bad an approx



B&T fig 2.6

Use of Gauss's thm (divergence) the sum of all sources minus the sum of all sinks gives the net flow out of a region.



$$\int \nabla \Phi d^2s = 4\pi GM = 2\pi G \Sigma$$

$$\text{as } z \rightarrow 0; \Sigma = (1/2\pi) G d\Phi/dr$$

Isothermal Sheet MBW pg 498

- simple model for the vertical structure of disk galaxies
- Allows an estimate the disk mass from a measurement of the vertical velocity dispersion, σ_z , and the radial scale length, R_d , if one knows the vertical scale height of the tracer population
- The relevant Poisson eq is $d^2\phi_z/d(z/z_d)^2 = 1/2 \exp(-\phi_z)$;
- $\phi_z = \phi / \sigma_z^2$ and $z_d = \sigma_z / \text{sqrt}(8\pi G \rho(R,0))$
 $\sigma_z^2(R) = (z/z_d) GM_d R_d \exp(-RR_d)$
- where z_d is the vertical scale height of the disk and R_d is the radial scale length
- can solve for the density distribution the disk
- *Why do we want to do this??- Estimates of the mass for face on galaxies where radial velocity data are impossible.*

Flattened +Spherical Systems-B&T eqs

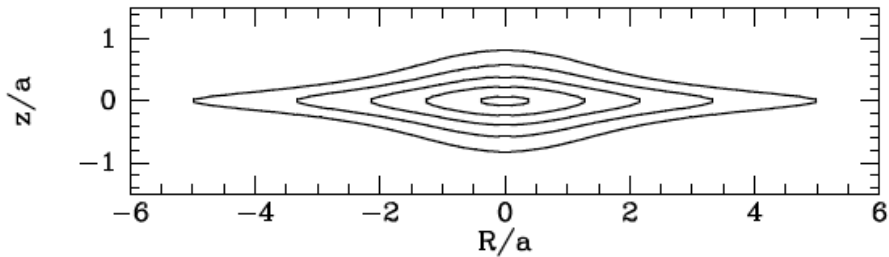
- Add the Kuzmin to the Plummer potential

$$\Phi_M(R, z) = -\frac{GM}{\sqrt{R^2 + (a + \sqrt{z^2 + b^2})^2}} \quad (2.69a)$$

- When $b/a \sim 0.2$, qualitatively similar to the light distributions of disk galaxies,

When $a = 0$, Φ_M reduces to Plummer's spherical potential (2.44a), and when $b = 0$, Φ_M reduces to Kuzmin's potential of a razor-thin disk (2.68a). Thus, depending on the choice of the two parameters a and b , Φ_M can represent the potential of anything from an infinitesimally thin disk to a spherical system. If we calculate $\nabla^2 \Phi_M$, we find that the mass distribution with which it is associated is (Miyamoto & Nagai 1975)

$$\rho_M(R, z) = \left(\frac{b^2 M}{4\pi}\right) \frac{aR^2 + (a + 3\sqrt{z^2 + b^2})(a + \sqrt{z^2 + b^2})^2}{[R^2 + (a + \sqrt{z^2 + b^2})^2]^{5/2} (z^2 + b^2)^{3/2}} \quad (2.69b)$$



Contours of equal density in the (R; z) plane for $b/a=0.2$ 27

Potential of an Exponential Disk B&T sec 2.6

- As discussed earlier the light profile of the stars in most spirals has an exponential scale LENGTH

$\Sigma(R) = \Sigma_0 \exp(-R/R_d)$ (this is surface brightness NOT surface mass density)- see next page for formula's

Do we learn anything from this ?? see MWB 11.1.2

Fig 2.17 in B&T - how the circular speed (a potential observable) depends on the scale length for different mass distributions.

Mass of exponential disk
 $M(R) = \int \Sigma(R) R dr = 2\pi \Sigma_0 R_d^2 [1 - \exp(-R/R_d)(1 + R/R_d)]$

when R gets large
 $M \sim 2\pi \Sigma_0 R_d^2$

Potential of an Exponential Disk B&T sec 2.6

The circular velocity peaks at $R \sim 2.16 R_d$ approaches Keplerian for a point mass at large R (eq. 11.30 in MWB) and depends only on Σ_0 and R_d

As long as the vertical scale length is much less than the radial scale the vertical distribution has a small effect - e.g. separable effects !

IF the disk is made only of stars (no DM) and if they all have the same mass to light ratio Γ , R_d is the scale length of the stars, then the observables $I_0, R_d, v_{\text{circ}}(r)$ have all the info to calculate the mass!

$$M(R) = \int \Sigma(R) R dr = 2\pi \Sigma_0 R_d^2 [1 - \exp(-R/R_d)(1 + R/R_d)]$$

when R gets large
 $M \sim 2\pi \Sigma_0 R_d^2$

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Explaining Disks

- Remember the most important properties of disk dominated galaxies (MBW pg 495)
 - Brighter disks are on average
 - larger, redder, rotate faster, smaller gas fraction
 - flat rotation curves
 - surface brightness profiles close to exponential
 - lower metallicity in outer regions
 - traditional to model them as an infinitely thin exponential disk with a surface density distribution $\Sigma(R) = \Sigma_0 \exp(-R/R_d)$
 - This gives a potential (MBW pg 496) which is a bit messy

$$\phi(R, z) = -2\pi G \Sigma_0^2 R_D \int [J_0(kR) \exp(-k|z|)] / [1 + (kR_D)^2]^{3/2} dk$$

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Exponential Disks

- Motivated by the exponential surface brightness profiles of disks examine a potential that is generated by such a distribution (B+T 2.162)

$\Sigma(R) = \Sigma_0 \exp(-R/R_D)$ which gives a mass distribution

$$M(R) = 2\pi \int \Sigma(R) R dR = 2\pi \Sigma_0 R_D^2 [1 - \exp(-R/R_D)(1 + R/R_D)];$$

as shown in detail in eqs B&T 2.153-2.157 one gets a potential in the form of Bessel functions

This comes from the use of Hankel functions (analogs of Fourier transforms but for cylindrically symmetric systems)

$$S(k) = -2\pi G \int J_0(kR) \Sigma(R) R dR ; J_0 \text{ is a Bessel function order zero}$$

$$\phi(R, z) = -2\pi G \Sigma_0 R_D^2 \int [J_0(kR) \exp(-k|z|)] / [1 + (kR_D)^2]^{3/2} dk$$