

Universal IMF *vs* dark halo response in early-type galaxies: breaking the degeneracy with the Fundamental Plane

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ABSTRACT

We use the relations between aperture stellar velocity dispersion (σ_{ap}), stellar mass (M_{SPS}), and galaxy size (R_e) for a sample of $\sim 150\,000$ early-type galaxies from SDSS/DR7 to place constraints on the stellar initial mass function (IMF) and dark halo response to galaxy formation. We build Λ CDM based mass models that reproduce, by construction, the relations between galaxy size, light concentration and stellar mass, and use the spherical Jeans equations to predict σ_{ap} . Given our model assumptions (including those in the stellar population synthesis models), we find that reproducing the median σ_{ap} vs M_{SPS} relation is not possible with *both* a universal IMF and a universal dark halo response. Significant departures from a universal IMF and/or dark halo response are required, but there is a degeneracy between these two solutions. We show that this degeneracy can be broken using the strength of the correlation between residuals of the velocity-mass ($\Delta \log \sigma_{\text{ap}}$) and size-mass ($\Delta \log R_e$) relations. The slope of this correlation, $\partial_{\text{VR}} \equiv \Delta \log \sigma_{\text{ap}} / \Delta \log R_e$, varies systematically with galaxy mass from $\partial_{\text{VR}} \simeq -0.45$ at $M_{\text{SPS}} \sim 10^{10} M_{\odot}$, to $\partial_{\text{VR}} \simeq -0.15$ at $M_{\text{SPS}} \sim 10^{11.6} M_{\odot}$. The virial fundamental plane (FP) has $\partial_{\text{VR}} = -1/2$, and thus we find the tilt of the observed FP is mass dependent. Reproducing this tilt requires *both* a non-universal IMF and a non-universal halo response. Our best model has mass-follows-light at low masses ($M_{\text{SPS}} \lesssim 10^{11.2} M_{\odot}$) and unmodified NFW haloes at $M_{\text{SPS}} \sim 10^{11.5} M_{\odot}$. The stellar masses imply a mass dependent IMF which is “lighter” than Salpeter at low masses and “heavier” than Salpeter at high masses.

Key words: dark matter, galaxies: elliptical and lenticular, cD – galaxies: fundamental parameters – galaxies: haloes – galaxies: kinematics and dynamics – stars: luminosity function, mass function

1 INTRODUCTION

The form of the stellar initial mass function (IMF) and the response of dark matter haloes to galaxy formation are two fundamental unknowns, which are important in many areas of astrophysics. For example, the IMF is needed in order to convert observations of integrated stellar light into stellar masses and star formation rates (two fundamental parameters in galaxy evolution studies), and for modelling the supernova rates, chemical evolution, and production of ionizing photons in galaxies. The response of dark matter haloes to galaxy formation is needed in order to constrain the nature of dark matter from observations of the structure of dark matter haloes (e.g., central density slopes, central den-

sities) and indirect dark matter detection experiments. Halo response also plays a key role in determining the fundamental scaling relations between velocity and light of galaxies (Faber & Jackson 1976, Tully & Fisher 1977).

For many years the IMF and dark halo response were thought to be universal: The IMFs of external galaxies are the same as measured in the Milky Way (Kroupa 2001, Chabrier 2003); and dark matter haloes contract adiabatically in response to galaxy formation (Blumenthal et al. 1986; Gnedin et al. 2004). However, recent observations and numerical simulations have cast doubt on these assumptions. We note that while there have been claims of observational evidence for dark halo contraction in early-type galaxies (e.g., Schulz et al. 2010; Napolitano et al. 2010; Trujillo-Gomez et al. 2011; Chae et al. 2012) these conclu-

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sions depend (trivially) on the assumption of a universal Milky Way type IMF (e.g., Dutton et al. 2011a).

It has been known for many years that baryonic effects can, in principle, result in reduced halo contraction or even halo expansion (e.g., Navarro, Eke, & Frenk 1996; El-Zant et al. 2001). But only recently have these effects been demonstrated in fully cosmological simulations of galaxy formation (Johansson et al. 2009; Abadi et al. 2010; Duffy et al. 2010; Governato et al. 2010; Macciò et al. 2012; Martizzi et al. 2012). Although some authors still maintain that dark halo contraction is an unavoidable consequence of galaxy formation in Λ CDM cosmologies (e.g., Gnedin et al. 2011).

The traditional route to constraining the IMF is through direct star counts. In the Milky Way this has shown the IMF to have a power-law shape $dN/dm \propto m^{-x}$, with $x \simeq -2.3$ at masses above $m \simeq 1M_{\odot}$ (Salpeter 1955), and a turn over at lower masses (Kroupa 2001; Chabrier 2003). Since most of the mass is in low-mass stars, Kroupa/Chabrier IMFs have lower stellar mass-to-light ratios (by about 0.20 to 0.25 dex) than a Salpeter IMF. Outside of our Galaxy, counting individual stars is usually not feasible (especially down to the low masses required to fully constrain the IMF). There are several approaches which can be used to probe the IMF at different mass scales in extragalactic systems.

Constraints on the shape of the IMF at high masses typically involve measurements of $H\alpha$ and/or far ultraviolet (FUV) fluxes. For example, the equivalent width of $H\alpha$ can constrain the slope of the IMF above $\sim 1M_{\odot}$ (Kennicutt 1983, Hoversten & Glazebrook 2008), and the ratio between $H\alpha$ and FUV fluxes probes the IMF above $\sim 10M_{\odot}$ (Meurer et al. 2009; Lee et al. 2009). Broadly speaking these methods show that the high mass IMF in external galaxies is similar to that of the Milky Way, but there are systematic discrepancies which could be explained by variation in the slope and/or upper mass limit of the IMF. Note that while modest changes in the upper end of the IMF don't impact the stellar mass-to-light ratios of old stellar populations, top heavy IMFs can leave behind enough stellar remnants to significantly increase stellar mass-to-light ratios.

The low mass end (below $\sim 1M_{\odot}$) of the IMF can be probed by comparing the mass (or an upper limit) of all the stars from dynamics and/or strong gravitational lensing to the stellar mass obtained from stellar population synthesis (SPS) models. Such studies require IMFs lighter (i.e., lower stellar mass-to-light ratios) than Salpeter in spiral galaxies (Bell & de Jong 2001; Bershady et al. 2011; Dutton et al. 2011a, Barnabè et al. 2012; Brewer et al. 2012), but are consistent with a universal Milky Way type IMF.

In elliptical and lenticular galaxies, Cappellari et al. (2006) showed that a Salpeter IMF over-predicts the dynamical mass-to-light ratios of some “fast-rotating” galaxies. Using dynamics and strong gravitational lensing from the SLACS survey (Bolton et al. 2006) Treu et al. (2010) showed that in fact a Salpeter IMF is allowed in massive (stellar mass $M_{\text{star}} \gtrsim 10^{11}M_{\odot}$, velocity dispersion $\sigma \gtrsim 200 \text{ km s}^{-1}$) elliptical galaxies, even accounting for “standard” dark matter haloes. Extending this study to include constraints from weak lensing, predictions from Λ CDM, and the possibility of dark halo contraction, Auger et al. (2010a) concluded that a Salpeter-type IMF was

strongly favored over Milky Way type IMF. In order to minimize uncertainties in subtracting off the dark matter, Dutton, Mendel, & Simard (2012) studied the densest $\simeq 3\%$ of early-type galaxies in the SDSS. These galaxies have a fundamental plane correlation consistent with no dark matter within an effective radius. The average IMF of these galaxies is close to Salpeter, with evidence that redder/bluer galaxies have heavier/lighter IMFs. A Salpeter-type IMF is also favored in the bulges of massive spiral galaxies (Dutton et al. 2013), and brightest cluster galaxies (Newman et al. 2013).

Another method for probing the low mass end of the IMF (in non star forming galaxies) is by measuring the strength of dwarf star sensitive absorption lines. Applying this method to nearby massive elliptical galaxies van Dokkum & Conroy (2010) found an IMF steeper (below $\sim 1M_{\odot}$) than that of the Milky Way, and most likely steeper than Salpeter. This result has been confirmed with larger samples of galaxies (Smith et al. 2012; Spiniello et al. 2012; Conroy & van Dokkum 2012). These studies also find evidence for a dependence of the (low mass) IMF slope on stellar velocity dispersion and α -abundance, with steeper slopes at higher dispersions and shorter star formation timescales.

Thus there is good agreement from different methods that the IMFs of the most massive or most dense elliptical galaxies are heavier than that of the Milky Way, and most likely similar to a Salpeter IMF below $\sim 1M_{\odot}$. The next step is to constrain how the IMF varies in a more general sample of early-type galaxies. The ATLAS3D project has made progress towards this aim (Cappellari et al. 2012a), but their study is limited by the inherent degeneracies between the baryonic and dark matter components in the mass modeling of galaxies (e.g., Dutton et al. 2005). Specifically there is a factor of ~ 2 range in derived stellar mass-to-light ratios between models in which mass-follows-light and models with cosmologically motivated adiabatically contracted dark matter haloes (see also Dutton et al. 2011a).

In this paper we place constraints on the mass dependence of the IMF and dark halo response using scaling relations of a large sample ($> 10^5$) of early-type galaxies from the Sloan Digital Sky Survey (SDSS, York et al. 2000). This approach has strengths and weaknesses compared to detailed mass models of individual galaxies (e.g., Dutton et al. 2011b; Sonnenfeld et al. 2012; Cappellari et al. 2012a). The weakness is we only get constraints for average galaxies (of a given mass), the strength is that our constraints are free of statistical uncertainties (in e.g., stellar mass-to-light ratios, dark halo masses, dark halo concentrations, etc) that necessarily effect studies with smaller samples. Both approaches are valid, providing complementary constraints to the variability of the IMF and dark halo response.

We construct dynamical models that consist of spherical distributions of stars and dark matter. These models are constrained to reproduce a number of observational and theoretical constraints (e.g., Dutton et al. 2011a). These models have two unknowns: the stellar IMF and the response of the dark matter halo to galaxy formation. We use the observed stellar velocity dispersion - stellar mass (Faber-Jackson) relation to single out allowable combinations of IMF and halo response. We show that the IMF and/or the halo response has to vary with galaxy mass. However, from the velocity dispersion vs stellar mass relation alone, we are unable to

uniquely determine which if either should vary, or the absolute normalization of the IMF and halo response.

Our additional constraint is the slope of the correlation between the residuals of the velocity - stellar mass ($\Delta \log \sigma$) and size - stellar mass ($\Delta \log R$) relations, which for brevity we denote $\partial_{\text{VR}} \equiv \Delta \log \sigma / \Delta \log R$. This is a useful constraint because it depends on the dark matter fraction within (roughly) the half-light radius (Courteau & Rix 1999; Dutton et al. 2007). If there is no dark matter then $\partial_{\text{VR}} = -1/2$, while dark matter dominated galaxies are expected to have $\partial_{\text{VR}} > 0$. As we show below ∂_{VR} is related to a more familiar concept – namely the tilt of the fundamental plane (FP, Dressler et al. 1987; Djorgovski & Davis 1987). A related approach was taken by Borriello et al. (2003), who used the fundamental plane constraints the dark matter content of early-type galaxies.

This paper is organized as follows. The relation between ∂_{VR} and the tilt of the FP is shown in §2, the main observed scaling relations are presented in §3, with additional details given in appendix A. Constraints on the IMF and halo response from the velocity - mass relation and the tilt of the FP are discussed in §4, and §5 respectively. A discussion of systematic effects is given in §6, and a summary is given in §7. Appendix A gives the details of our mass models. We adopt a Λ CDM cosmology with $\Omega_{\Lambda} = 0.7$, $\Omega_{\text{M}} = 0.3$ and $H_0 = 70 \text{ km s}^{-1} \text{ Mpc}^{-1}$

2 THE TILT OF THE FUNDAMENTAL PLANE

The fundamental plane is a well-known scaling relation between the size (R), and surface brightness (I), and velocity dispersion (σ) of early-type galaxies:

$$R \propto \sigma^a I^b. \quad (1)$$

For r -band sizes and surface brightnesses, the exponents are $(a, b) = (1.49 \pm 0.05, -0.75 \pm 0.01)$ (e.g. Bernardi et al. 2003). This differs from the simplest mass-follows-light model, known as the virial plane, in which $(a, b) = (2, -1)$. The differences in exponent are referred to as the tilt of the fundamental plane.

The origin of the tilt has been the subject of debate for many years (e.g., van der Marel 1991; Bender, Burstein & Faber 1992; Ciotti, Lanzoni, & Renzini 1996; Graham & Colless 1997; Prugniel & Simien 1996, 1997; Pahre, Djorgovski, & de Carvalho 1998; Padmanabhan et al. 2004; Trujillo, Burkert, & Bell 2004; Robertson et al. 2006; Bolton et al. 2007, 2008; Graves & Faber 2010). There are two principle explanations for the tilt: (1) Variation of total mass to light ratio; and (2) Structural non-homology. Using the fact that $I \propto L/R^2$ one can re-write Eq. 1 as

$$R\sigma^2/L \propto \sigma^{2-a} I^{-1-b}. \quad (2)$$

Thus the virial plane corresponds to $R\sigma^2/L = \text{constant}$, and the tilt of the fundamental plane corresponds to variation in $R\sigma^2/L$.

In the case of structural homology the total mass, M_{tot} , within radius R , is directly proportional to $R\sigma^2$, and thus variation in $R\sigma^2/L$ corresponds to variation in M_{tot}/L . The total mass-to-light ratio can vary as a result of variation in stellar mass-to-light (M_{star}/L) or variation in the total mass to stellar mass ($M_{\text{tot}}/M_{\text{star}}$) ratio. The former is a result of

stellar population differences, while the latter is a result of variation of dark matter fractions.

In the case of constant M_{tot}/L , structural non-homology results in the total mass not being directly proportional to $R\sigma^2$. Examples of structural non-homology are variation of the stellar mass profile (e.g., a variation in the Sérsic index or concentration parameter), and variation in the anisotropy of stellar orbits.

Going back to the fundamental plane as written Eq. 1, both coefficients are tilted with respect to the virial prediction. It turns out that the fundamental plane can be written so that the tilt is in a single coefficient. We can re-write Eq. 1 as

$$\sigma \propto L^c R^d \quad (3)$$

where $c = -b/a$, and $d = (1 + 2b)/a$. The corresponding virial coefficients are $(c, d) = (1/2, -1/2)$. The exponents from Bernardi et al. (2003) result in $(c, d) = (0.50 \pm 0.02, -0.33 \pm 0.01)$, and thus the tilt of the r -band fundamental plane is consistent with being entirely due to $d \neq -1/2$. Replacing luminosity with stellar mass in Eq. 3, we see that the strength of the correlation between the velocity-mass and size-mass relations is equivalent to the tilt of the fundamental plane, i.e., $\partial_{\text{VR}} \equiv d$.

3 OBSERVED SCALING RELATIONS

3.1 Sample Overview

Here we give an overview of our observational sample of early-type galaxies. We use a similar (but not identical) selection procedure as described in more detail in Dutton et al. (2011a). In summary we use four selection criteria: (1) A spectroscopic redshift $0.005 < z < 0.3$; (2) A spectrum classified as early-type by SDSS (eCLASS < 0); (3) A red ($g - r$) color, based on valley in color - stellar mass plane; (4) A minor-to-major axis ratio, $b/a > 0.5$ (which removes dusty edge-on spirals). These cuts are designed to select non-star forming galaxies, so our sample includes ellipticals and lenticulars. We also apply a redshift dependent minimum stellar mass to remove the color bias at fixed stellar mass which results from the SDSS r -band magnitude limit for spectroscopy. Our final sample consists of $\sim 150\,000$ early-type galaxies.

We use structural parameters (such as sizes and axis ratios) from the Sérsic $n = 4$ plus $n = 1$ fits of Simard et al. (2011). Unless otherwise stated the sizes we use here, R_e , are the circularized half-light sizes derived from the model of the total light profile.

There are two velocity dispersion measurements publicly available for SDSS galaxies. We refer to these as ‘‘SDSS’’ and ‘‘Princeton’’. At most masses these two measurements are in excellent agreement, in addition the scatter in these two measurements is in good agreement with the reported uncertainties. However, at low masses (and low dispersions) there are significant differences (see also Hyde & Bernardi 2009). In what follows, for the observed velocity dispersion we adopt the logarithmic average of the two measurements. Where appropriate we will use the individual measurements to gauge systematic uncertainties in scaling relations.

When constructing the Faber-Jackson relation and the

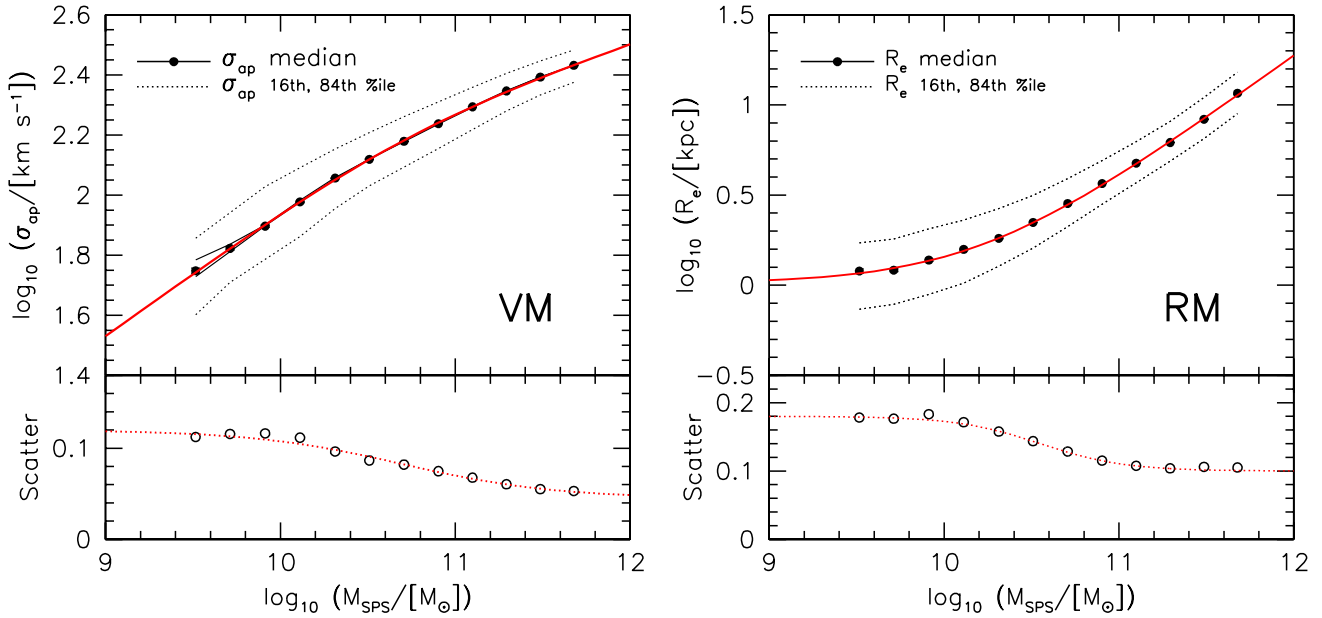


Figure 1. Observed velocity - stellar mass (VM, left) and size - stellar mass (RM, right) relations for SDSS early-type galaxies. Velocity dispersions (σ_{ap}) are measured within the SDSS 3 arcsec diameter aperture, the stellar masses (M_{SPS}) assume a Chabrier (2003) IMF, the sizes (R_e) are circularized half-light radii measured in the r -band. For the VM relation the black solid lines show the relations obtained for the two different velocity dispersion measurements, which are only visibly different at low masses. *Upper panels:* The solid points show medians in bins of 0.2 dex width in M_{SPS} . The solid red lines show double power-law fits to these points (parameters in Table A2), while the dotted lines show the 16th and 84th percentiles. *Lower panel:* The open points show the scatter in each mass bin. The red dotted lines show fits to these points (parameters given in Table A2).

fundamental plane from fiber spectroscopy it is customary to correct the aperture velocity dispersions to some fiducial radius, such as the effective radius (R_e), or one eighth of the effective radius. However, doing so requires making an assumption for the variation of σ with radius. Since we will directly use the strength of the correlation between σ and R_e at fixed mass to constrain our models, we do not wish to introduce an artificial correlation. Instead, our approach is to measure observed scaling relations using the uncorrected fiber velocity dispersions, σ_{ap} , and to explicitly compute the velocity dispersion within the SDSS fiber in our models using the spherical Jeans equations (see Appendix A for details).

We use stellar masses from the MPA/JHU database¹. These are derived by fitting *ugriz* photometry with Bruzual & Charlot (2003) SPS models assuming a Chabrier (2003) IMF. To account for a non-universal IMF, or systematic errors in stellar mass measurements, we allow for an offset between the true stellar masses, M_{star} , and these SPS stellar masses, M_{SPS} , which we denote $\Delta_{\text{IMF}} \equiv \log(M_{\text{star}}/M_{\text{SPS}})$.

The uncertainty on the stellar masses are nominally ≈ 0.1 dex, but there will be some galaxies with much larger uncertainties. At the highest masses, and largest size-offsets, these outliers can bias the slopes of the scaling relations. As in Dutton, Mendel, & Simard (2012) we clean the sample by using the relation between stellar mass-to-light ratio and velocity dispersion: M_{SPS}/L_r vs σ_{ap} . We remove ~ 700 galaxies (0.5% of our early-type galaxy sample) that are more than $\pm 4\sigma$ from the median relation. This number is ~ 100

times higher than the expected number of high- σ offsets for log-normal scatter in M_{SPS}/L_r .

3.2 Mean Relations

The observed velocity dispersion - stellar mass (VM) and size - stellar mass (RM) relations for our sample of SDSS early-type galaxies are shown in Fig. 1. The upper panels shows the median (filled circles) together with the 16th and 84th percentiles (dotted lines) of velocity and size in bins of stellar mass (these data points are given in Table A1). The median relations are well fitted with double power-laws (in the variables 10^x and 10^y):

$$y = y_0 + \alpha(x - x_0) + \frac{(\beta - \alpha)}{\gamma} \log \left[\frac{1}{2} + \frac{1}{2} 10^{\gamma(x - x_0)} \right]. \quad (4)$$

Here α is the slope at $x \ll x_0$, β is the slope at $x \gg x_0$, x_0 is the transition scale, $y_0 = y(x_0)$, and γ controls the sharpness of the transition (higher γ results in a sharper transition). The parameters of the fits are given in Table A2. For the velocity-mass relation the slope varies from ~ 0.4 at low masses to ~ 0.2 at high masses, while for the size-mass relation the slope varies from ~ 0.0 at low masses to ~ 0.7 at high masses.

The lower panels show the scatter about the median relations (open circles). For both velocity-mass and size-mass relations the scatter decreases from low to high mass. The mass dependence of the scatter is fitted with the following function:

$$y = y_2 + \frac{y_1 - y_2}{1 + 10^{\gamma(x - x_0)}}. \quad (5)$$

¹ Available at <http://www.mpa-garching.mpg.de/SDSS/DR7/>

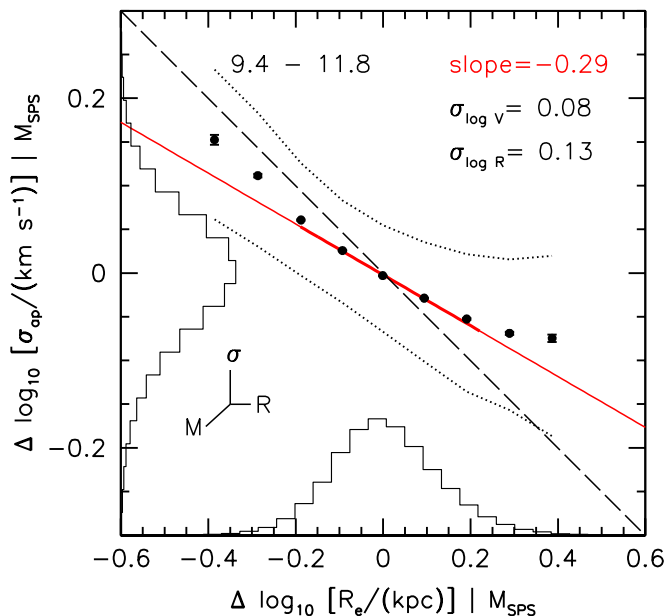


Figure 2. Correlation between residuals of the velocity-mass and size-mass relations (Fig. 1) for all early-type galaxies. The solid line shows the best fit linear relation which has a slope of $\partial_{\text{VR}} = -0.29$. The thick portion of this line shows the region fitted, which corresponds to the 5th and 95th percentiles of the distribution of size offsets. The long-dashed line is the virial relation with slope $= -0.5$. The compass shows the direction the median errors on velocity (σ_{ap}), size (R_e), and mass (M_{SPS}) scatters galaxies in this plane. This shows that most of the scatter about the median relation is due to observational errors.

Here y_1 is the asymptotic value at $x \ll x_0$, y_2 is the asymptotic value at $x \gg x_0$, x_0 is the transition scale, and γ controls the sharpness of the transition. The values of the best fit parameters are given in Table A2.

3.3 Residual Relations

The correlation between the residuals of the VM and RM relations, $\Delta \log R_e$ and $\Delta \log \sigma_{\text{ap}}$, for the full sample of early-type galaxies is shown in Fig. 2. The histograms show the distribution of $\Delta \log R_e$ and $\Delta \log \sigma_{\text{ap}}$. The standard deviation of the velocity and size residuals is 0.08 dex and 0.13 dex, respectively. The filled circles show the median $\Delta \log \sigma_{\text{ap}}$ in bins of $\Delta \log R_e$, while the dotted lines show the 16th and 84th percentiles of the distribution. The median errors on velocity, size, and mass are indicated with the compass, and shows that most of the scatter about the median relation is due to observational errors. Note that due to the curvature in the size-mass and velocity-mass relations, the direction of the stellar mass error changes from almost vertical at low masses, to almost horizontal at high masses.

A power-law fit to these data (over the region indicated by the thick line) results in a slope of $\partial_{\text{VR}} = -0.29 \pm 0.01$. The virial fundamental plane has $\partial_{\text{VR}} = -0.5$, which is shown with the diagonal dashed line. Thus the fact that we observed $\partial_{\text{VR}} \neq -0.5$ is equivalent to the statement that the *observed* fundamental plane is tilted with respect to the virial fundamental plane. The slope varies with $\Delta \log R_e$, in-

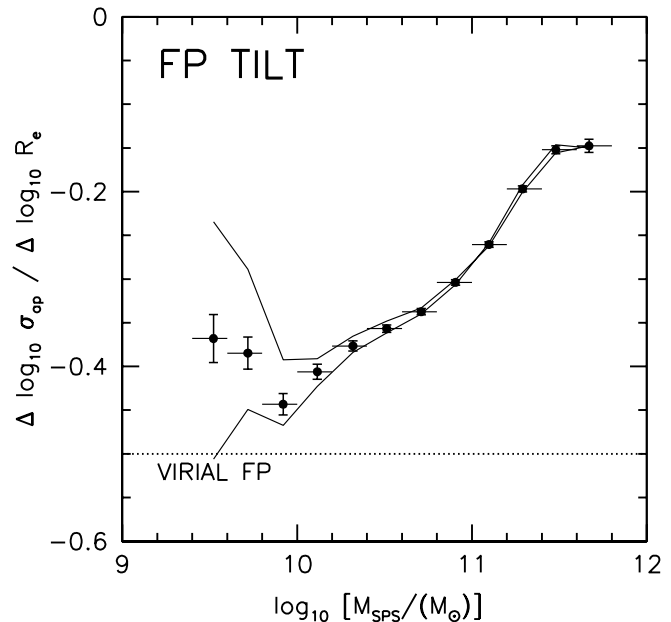


Figure 3. Slopes of the correlation between residuals of the velocity-mass ($\Delta \log \sigma_{\text{ap}}$) and size-mass ($\Delta \log R_e$) relations, as a function of stellar mass. The horizontal bar shows the width of the bin in stellar mass, while the vertical error bar shows the uncertainty on the slope. The two solid lines show the results obtained using the two different set of stellar velocity dispersions, indicating systematic errors at low masses. The virial FP has a slope of -0.5 , and thus we find that the tilt of the observed FP is mass dependent.

dicating that the tilt of the *observed* fundamental plane is not a constant. For large negative size offsets, $\partial_{\text{VR}} \simeq -0.5$, suggesting that baryons dominate within the effective radius, whereas for large positive size offsets, $\partial_{\text{VR}} \simeq 0$, suggesting that there is significant dark matter (Courteau & Rix 1999). These nominal trends of dark matter fraction with size offset are qualitatively consistent with the expectations for galaxies embedded in extended dark matter haloes — for a fixed halo mass and stellar mass, smaller galaxies will have lower dark matter fractions within an effective radius, and hence smaller (more negative) ∂_{VR} .

Fig. 3 shows ∂_{VR} computed in stellar mass bins of width 0.2 dex (these data points are given in Table A1). This shows that while ∂_{VR} is always negative, it is not a constant, i.e., the tilt of the *observed* fundamental plane increases with increasing stellar mass. This echoes previous studies which show there is curvature to the fundamental plane (e.g., Zaritsky et al. 2006, 2011; Hyde & Bernardi 2009; Tollerud et al. 2011). As an estimate of systematic uncertainties we measure ∂_{VR} using the two sets of velocity dispersions available for SDSS galaxies. The two measurements are shown with the solid lines in Fig. 3. They are in good agreement above $M_{\text{SPS}} \sim 10^{10} M_{\odot}$, but below this mass there are significant differences.

As a final note we stress that the data shown in Figs. 2 & 3 are not corrected for aperture effects or measurement errors, which both tend to weaken the observed correlations. Aperture effects are more important when the fiber only covers a small fraction of the galaxy light (i.e., intrinsically

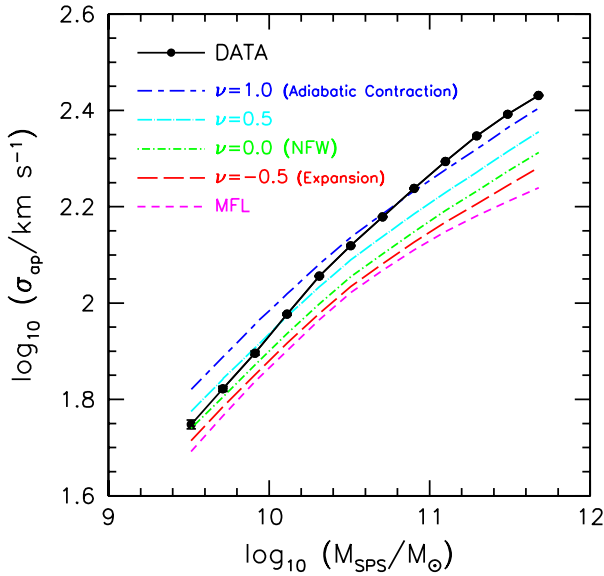


Figure 4. Comparison between observed and model VM relations assuming a Chabrier IMF. The filled circles and solid black line shows the observed median relation, with error bars indicating the error on the median. The colored lines show the model relations assuming isotropic stellar velocity dispersions ($\beta = 0$). The models only differ in the structure of the dark matter halo, which ranges from adiabatically contracted NFW dark matter haloes ($\nu = 1$, blue line) to no dark matter (MFL, magenta line). None of these models reproduces the slope of the VM relation, indicating the need for a non-universal IMF and/or non-universal dark halo response.

larger galaxies or galaxies at lower redshifts). Measurement errors in stellar masses are most important (especially at high masses) as these couple offsets from the size-mass and velocity mass relations. Rather than try to correct the data (which in the case of aperture corrections is model dependent, and thus non unique), our approach is to explicitly include these effects in our models. We will show that an observed $\partial_{VR} \sim -0.3$ can be explained by models in which mass follows light (and thus follow the virial fundamental plane between σ_e , R_e , and M_{star}).

4 CONSTRAINTS FROM THE VELOCITY-MASS RELATION

In this section we use the velocity-stellar mass relation to constrain the two free parameters of our model (see Dutton et al. 2011a and Appendix A for more details): the stellar mass normalization $\Delta_{IMF} = \log(M_{star}/M_{SPS})$ and dark halo response ν .

4.1 Universal IMF and universal halo response

We start by constructing model samples with a universal Chabrier IMF. We consider four halo responses: standard adiabatic contraction $\nu = 1$ (Blumenthal et al. 1986), reduced halo contraction $\nu = 0.5$ (c.f., Abadi et al. 2010); no halo contraction $\nu = 0$ (i.e., NFW haloes); and halo expansion $\nu = -0.5$. In addition we consider a model in

which mass-follows-light (MFL). For each model we compute aperture velocity dispersions for 5000 model galaxies evenly spaced in $\log(M_{SPS}/M_{\odot})$ (from 9.3 to 11.9), and including log-normal scatter in sizes, dark halo masses, and dark halo concentrations. We then re-sample these galaxies (100 times) according to the observed intrinsic distribution of stellar masses, and add measurement errors in stellar mass, size and velocity dispersion (see Appendix A). This procedure results in a sample of $\sim 150\,000$ model galaxies with the same distribution of stellar masses and sizes as our observed sample.

The median velocity-mass relations of these models are shown in Fig. 4. None of our models is able to reproduce the observed VM relation, even allowing for zero point offsets (corresponding to different, but still universal IMFs). There are two primary solutions to this problem: 1) Allow the stellar mass to vary from that predicted by a universal Chabrier IMF, with “heavier” IMFs in more massive (i.e., higher M_{SPS}) galaxies; or 2) Allow the halo response to vary with galaxy mass, with e.g., no halo contraction in low mass galaxies and stronger halo contraction in progressively higher mass galaxies.

In principle, another solution would be to allow the stellar anisotropy to vary with galaxy mass, however, observations find no evidence for a mass dependence to the stellar anisotropy (e.g., Gerhard et al. 2001). Furthermore, as we show below, the maximum range of reasonable anisotropy only has a $\simeq 10\%$ effect on the derived masses.

We now construct models with non-universal IMFs and/or non-universal halo responses that reproduce the median VM relation. In § 5 we will use the tilt of the fundamental plane (Fig. 3) to distinguish between these models.

4.2 Non-universal IMF with mass-follows-light

For MFL models we can easily calculate the stellar masses required to match the observed velocity dispersions using

$$M_{star} = M_{SPS}(\sigma_{ap}/\sigma_{ap,SPS})^2, \quad (6)$$

where σ_{ap} is the observed velocity dispersion and $\sigma_{ap,SPS}$ is the model velocity dispersion computed assuming M_{SPS} . The stellar mass offset, Δ_{IMF} , as a function of SPS mass for two MFL models (with different anisotropy) is shown in the right panels of Fig. 5. For $10^{9.7} \lesssim M_{SPS} \lesssim 10^{11.5}$ the stellar mass offset is well fitted with a linear relation:

$$\Delta_{IMF} = \log(M_{star}/M_{SPS}) = a + b \log(M_{SPS}/10^{11} M_{\odot}). \quad (7)$$

For both isotropic ($\beta = 0$) and radially anisotropic orbits (with $\beta = 0.5$) we find a slope of $b \simeq 0.14 \pm 0.01$. This results in a factor of $\simeq 2$ difference in Δ_{IMF} across the range of M_{SPS} that we study. In terms of normalization, for $\beta = (0.0, 0.5)$ we find $a = (0.278, 0.238)$, which is slightly higher than a Salpeter IMF ($\Delta_{IMF} \simeq 0.23 \pm 0.01$).

Previous studies have determined the slope, b , for early-type galaxies under the assumption of MFL, spherical symmetry, and isotropic orbits, but using the Sérsic profile to parametrize the light. For example, the result from Trujillo, Burkert & Bell (2004; T04) is equivalent to $b \simeq 0.03 \pm 0.04$ (assuming a correction of 0.07 for stellar population effects), while the result from Taylor et al. (2010; T10) is equivalent to $b \simeq 0.09 \pm 0.10$ (where the error is dominated by systematics). Our result of $b \simeq 0.14 \pm 0.01$ is consistent with the

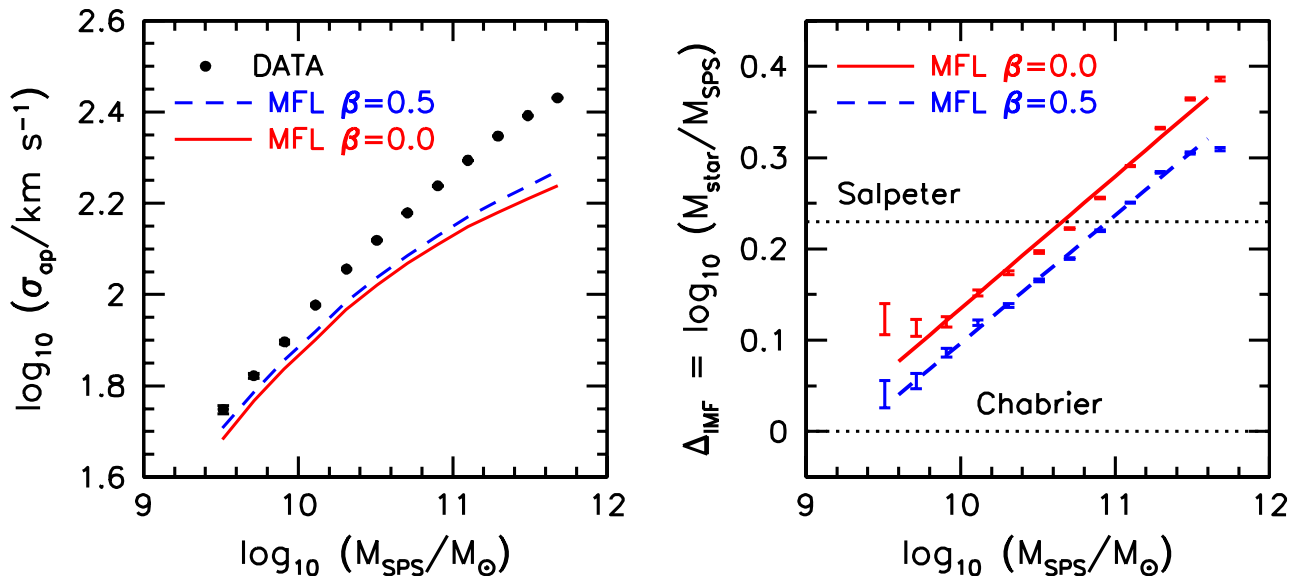


Figure 5. *Left:* VM relations for data (black filled circles) and mass-follows-light (MFL) models (red and blue lines) assuming a Chabrier (2003) IMF. The model galaxies have constant velocity anisotropy with $\beta = 0$ (red solid line) and $\beta = 0.5$ (blue dashed line). *Right:* Relation between stellar mass (M_{star}) required for the model to match the observed VM relation and stellar population synthesis mass (M_{SPS}). The offset between these two masses is well fitted with a power-law, with parameters as indicated. Interpreting this offset in terms of the IMF requires “heavier” IMFs in more massive galaxies.

latter, and shows that the choice of how one parametrizes the light profile is not critical. While the result from T04 is statistically different from ours, they use a very small sample (45 galaxies compared to ~ 1800 for T10, and $\sim 150\,000$ by us) and thus are subject to cosmic variance and/or environmental selection effects.

While it is encouraging that our result is consistent with previous studies, it should be stressed that the assumption of mass-follows-light is known to be false in massive early-type galaxies (e.g., Koopmans et al. 2006, 2009; Gavazzi et al. 2008) – below we will show that it is also unable to account for the tilt of the fundamental plane in massive early-type galaxies. Thus this exercise in building mass-follows-light models and interpreting the tilt of the fundamental plane is somewhat academic (at least for the most massive galaxies).

Furthermore, as shown in Appendix A1, there is a fundamental inconsistency in the methodology of Taylor et al. (2010). Fig. A2 shows the effects of non-homology on dynamical masses are much weaker when one uses velocity dispersions measured within the effective radius, σ_e , compared to one eighth an effective radius, σ_{e8} . However, the standard aperture corrections (used by e.g., Taylor et al. 2010) result in a constant offset of 0.060 dex between σ_e and σ_{e8} . Thus if T10 had corrected the SDSS fiber velocity dispersions to σ_e and then applied the same assumptions of MFL and isotropy, they would have arrived at different conclusions regarding the importance of non-homology in deriving dynamical masses. We do not have this inconsistency in our models because we explicitly model the fiber velocity dispersions.

Table 1. Parameters of models, where $\Delta_{\text{IMF}} = a + b \log(M_{\text{SPS}}/[10^{11}M_{\odot}])$.

Halo Response	Anisotropy	Δ_{IMF} zero	Δ_{IMF} slope
ν	β	a	b
Variable (see text)	0.0	0.08	0.00
1.0	0.0	0.03	0.14
0.5	0.0	0.15	0.14
0.0	0.0	0.22	0.14
-0.5	0.0	0.26	0.14
MFL	0.0	0.28	0.14
MFL	0.5	0.24	0.14

4.3 Degeneracy between IMF and halo response

For models with dark matter haloes the model velocity dispersion depends non-trivially on the stellar mass, and thus when we change Δ_{IMF} or the halo response, we need to recalculate the model. We determine the IMF offset parameters (a, b) for such models with a grid search. The stellar mass offset parameters for our suite of models are given in Table 1, and the VM relations are shown in Fig. 6. All models require a variable IMF, but the mass dependence, $b = 0.14$, is consistent with being independent of the halo response model. At the reference stellar mass ($M_{\text{SPS}} = 10^{11}M_{\odot}$) standard adiabatic contraction ($\nu = 1$, Blumenthal et al. 1986) requires an IMF close to Chabrier, while no dark halo contraction ($\nu = 0$) requires an IMF close to Salpeter. This is in agreement with our earlier study Dutton et al. (2011a).

One can construct models that match the VM relation with a universal IMF, but a non-universal halo response. An

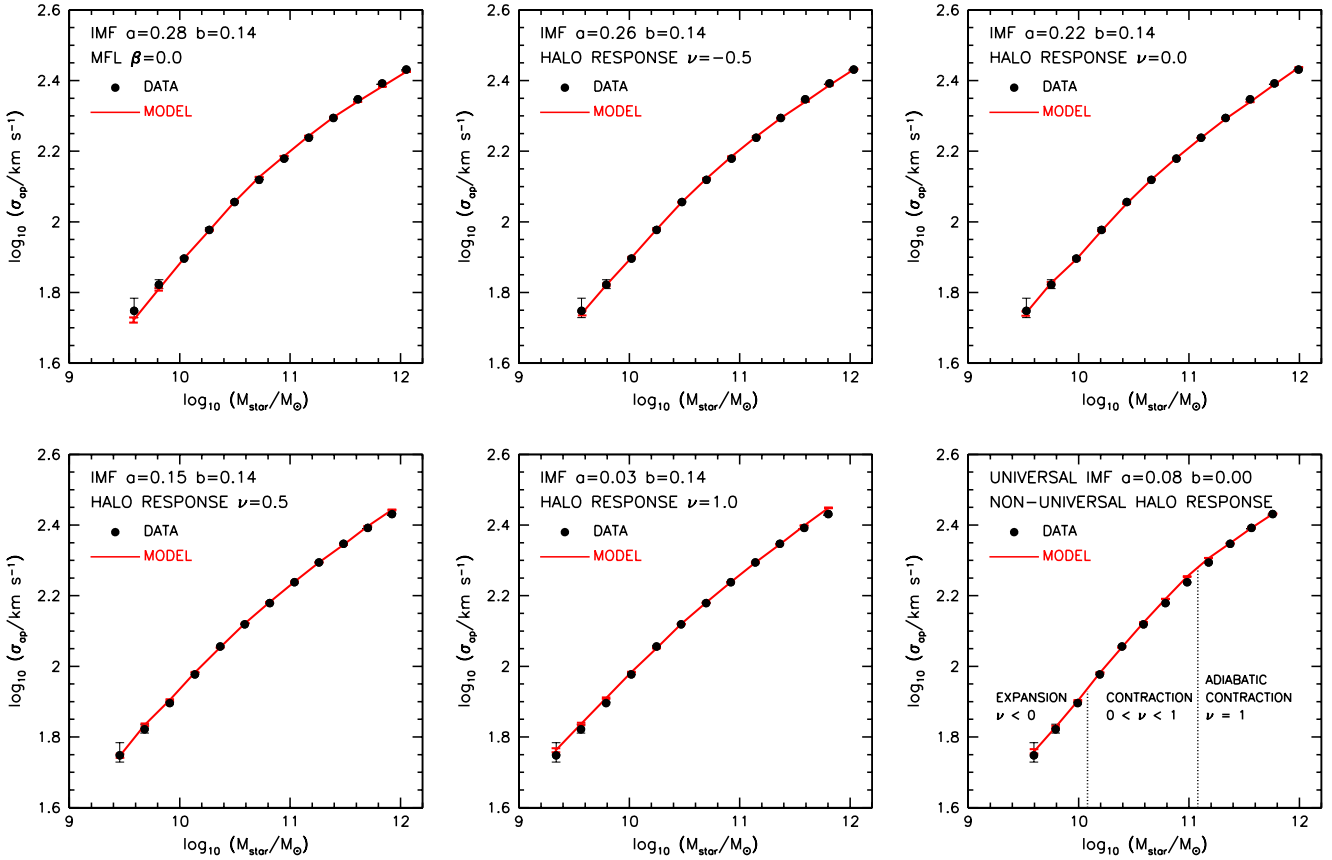


Figure 6. Comparison between observed (black circles) and model (red lines) VM relations. Each model has a different halo response (parametrized by ν) and stellar mass normalization (parametrized by a and b). Models with stronger halo contraction require lighter IMFs (lower a). For a universal halo response (i.e., fixed ν) a non-universal IMF ($b \neq 0$) is required.

example of such a model is shown in the lower right panel of Fig. 6. The IMF normalization $a = 0.08$ is only slightly heavier than a Kroupa (2001) IMF. The halo response parameter depends on stellar mass as $\nu = 1.0 + 1.0(\log M_{\text{SPS}} - 11)$, with a maximum of $\nu = 1$. So this model has adiabatic contraction for $M_{\text{SPS}} > 10^{11} M_{\odot}$, and no-contraction at $M_{\text{SPS}} = 10^{10} M_{\odot}$.

The most relevant study in the literature to ours is by Auger et al. (2010a). These authors fitted Λ CDM based models to a sample of ~ 50 massive ($M_{\text{SPS}} = 10^{11.35 \pm 0.20} M_{\odot}$) elliptical galaxy strong lenses from the SLACS survey (Bolton et al. 2006). Observational constraints were masses from strong lensing, aperture stellar velocity dispersions from SDSS, and weak lensing data from the Hubble Space Telescope. Auger et al. (2010a) parametrized the relation between M_{SPS} and M_{star} by $\log M_{\text{SPS}} = \log M_{\text{star}} - \eta(\log M_{\text{star}} - 11) - \alpha$. In terms of our parametrization: $a = \alpha/(1-\eta)$ and $b = \eta/(1-\eta)$. Their best fitting model had uncontracted NFW haloes and a mass dependent IMF with $\alpha = 0.03 \pm 0.03$ and $\eta = 0.08 \pm 0.04$, where the reference IMF was Salpeter (1955). Converting to a Chabrier (2003) IMF results in $a = 0.26 \pm 0.06$, $b = 0.09 \pm 0.06$, which is consistent with our results for the masses our respective studies overlap.

5 CONSTRAINTS FROM THE TILT OF THE FUNDAMENTAL PLANE

We now use the tilt of the fundamental plane to break the degeneracy between IMF and halo response. Fig. 7 shows a comparison between ∂_{VR} and stellar mass for models and observations. The observations are shown with black points, lines and error bars (as in Fig. 3). The models are shown with colored shaded regions, as indicated. The models include measurement errors in stellar masses, sizes and velocity dispersions. The effect of measurement errors is to increase the strength of fundamental plane tilt (i.e., ∂_{VR} becomes less negative). Errors on stellar masses have the strongest effect on ∂_{VR} . To indicate the dependence of our results to stellar mass errors the dashed lines show models with 20% higher and lower measurement errors on stellar masses (i.e., varying from 0.08 dex to 0.12 dex).

The first thing that is apparent is that all of the models predict that ∂_{VR} should vary with stellar mass, with (generally) more negative ∂_{VR} at lower masses, in qualitative agreement with the observations. However, none of the models reproduces the shape and normalization of ∂_{VR} vs M_{SPS} in detail. In particular models with standard adiabatic contraction (blue line, lower middle panel) or a universal Milky Way type IMF (grey line, lower right panel) are the most discrepant, under predicting the strength of ∂_{VR} by up to

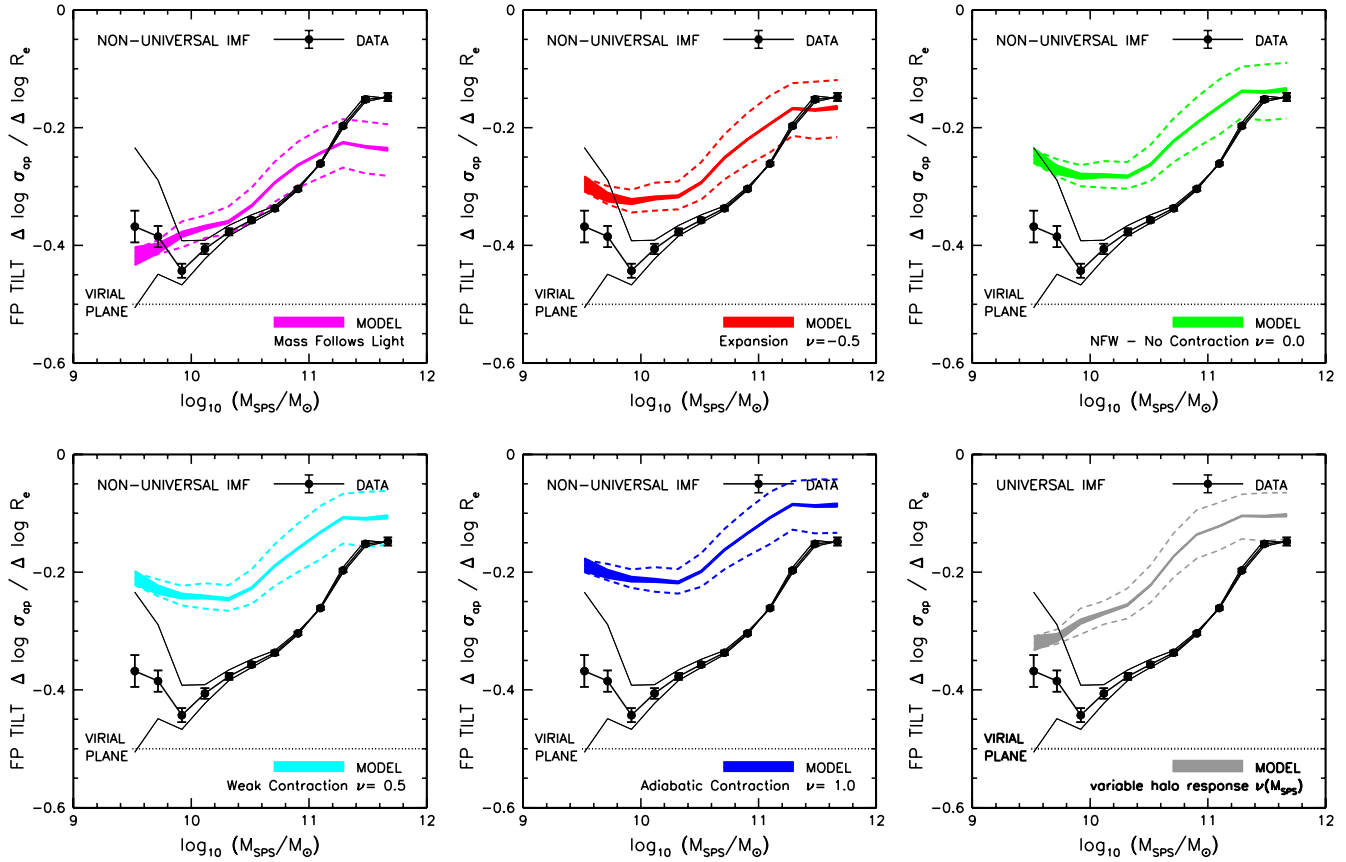


Figure 7. Fundamental Plane (FP) tilt vs stellar mass. Slopes of the relation between residuals of the VM and RM relations (∂_{VR}) vs stellar mass (normalized to a Chabrier IMF) for models in Fig. 6. The data (black points) is as in Fig. 3. For the models the shaded region corresponds to the fiducial measurement errors, while the dashed region shows 20% higher and lower errors on stellar masses. For all but the highest masses the mass-follows-light (MFL) model (magenta, upper left panel) fits the data the best. For the highest masses, models with no halo contraction are favored, but mild halo contraction is consistent with the data. Thus reproducing the tilt of the fundamental plane requires *both* non-universal IMF and non-universal halo response.

~ 0.2 . These models have the “lightest” IMF normalizations, and hence the highest dark matter fractions ($\simeq 50\%$) within an effective radius (See Fig. 8). The increased dark matter has the effect of dampening the changes in velocity that are expected from changing the sizes of the galaxies.

Below a stellar mass of $M_{SPS} \sim 10^{11.2}$ the MFL model (magenta line, upper left panel) is the only one that is consistent with the data. At the lowest masses ($M_{SPS} \sim 10^{9.6}$) there is significant uncertainty in the observations, and while MFL models fit best, they are not required. Above $M_{SPS} \sim 10^{11.2}$ the MFL model progressively over-predicts the strength of ∂_{VR} . Reproducing the observations thus requires a mass dependent halo response: expansion (red line) for masses $10^{11.2} \lesssim M_{SPS} \lesssim 10^{11.4}$, and uncontracted NFW haloes (green line) for $M_{SPS} \sim 10^{11.5}$. Given reasonable uncertainties in the stellar mass errors, models with contracted dark matter haloes (cyan and blue) are consistent with the data in the most massive galaxies $M_{SPS} \gtrsim 10^{11.4}$.

The fact that MFL does not reproduce the fundamental plane for the most massive galaxies is consistent with results from strong gravitational lensing, which find average total mass density slopes that are close to isothermal $\gamma \simeq -2.08 \pm$

0.03 (Auger et al. 2010b), and thus shallower than MFL ($\gamma \sim -2.3$ for a Hernquist profile).

It might seem surprising that MFL models, which follow the virial fundamental plane, can reproduce the observed fundamental plane tilt. This can be explained by two effects which are shown for MFL models in Fig. 9. The first, as mentioned above, is that measurement errors (on stellar masses and sizes) increase the observed fundamental plane tilt (i.e., they make ∂_{VR} less negative). In Fig. 9 compare the solid and long-dashed lines for the effect of stellar mass errors, and the short-dashed and long-dashed lines for the effect of size errors. Note that errors on velocity dispersions do not contribute to the observed fundamental plane tilt. The second is a result of measuring the velocity dispersions within a fixed physical aperture, rather than within a relative aperture such as an effective radius. In Fig. 9 compare the dot-dashed line (which uses model velocity dispersions within the effective radius, σ_e) with the short-dashed line (which uses model aperture velocity dispersions, σ_{ap}). Each of these effects accounts for roughly half of the observed tilt of the fundamental plane for intermediate mass galaxies. The larger tilt at higher masses is mostly due to the curva-

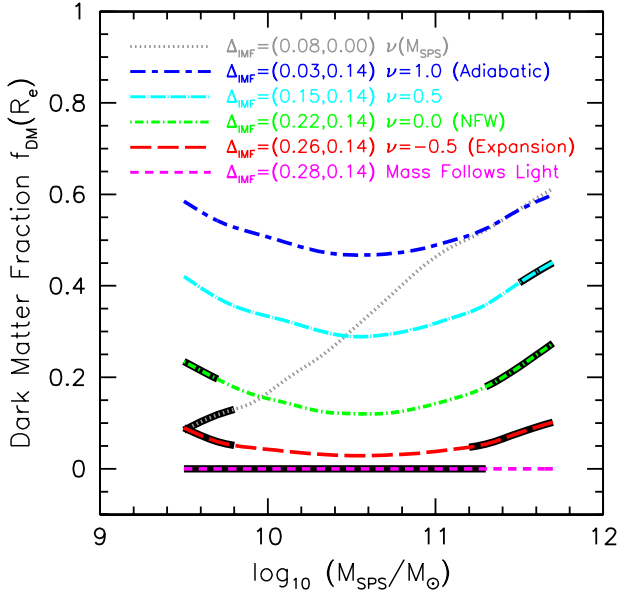


Figure 8. Dark matter fraction within an effective radius vs SPS mass. A universal IMF model (dotted grey line) requires dark matter fractions increasing with increasing mass, as found by numerous previous studies. Universal halo response models (colored lines) result in roughly constant dark matter fractions with a minimum at $M_{\text{SPS}} \sim 3 \times 10^{10} M_{\odot}$. The solid black lines indicate the models which provide acceptable fits to the fundamental plane constraints (see Fig. 7).

ture in the size-mass relation which increases the impact of stellar mass errors.

5.1 Mass dependence and literature comparison

A summary of the main results of this paper, together with a comparison to some recent results in the literature is given in Fig. 10. The various models with fixed halo responses are given by colored lines (with the same color and line type as in Figs. 4 & 8). The parameters of the relations between IMF mismatch parameter and SPS mass are given in Table 1. The corresponding relations between IMF mismatch parameter and stellar velocity dispersion (measured within the effective radius) are given in Table 2. The models that reproduce the fundamental plane constraints (from Fig. 7) are highlighted with thick black lines.

In the left panel we compare our results with those of Auger et al. (2010a), and Dutton et al. (2012, 2013) who directly compared true stellar masses with SPS masses. All three of these results are in excellent agreement with ours. The result from the study of strong gravitational lenses by Auger et al. (2010a) is shown as a green cross (we show their best fitting model which assumes NFW haloes). The vertical line indicates the 1σ uncertainty on $M_{\text{star}}/M_{\text{SPS}}$, the width of the diagonal line corresponds to the observed scatter in SPS masses, while the slope of the diagonal line shows the best fitting slope of the relation between $M_{\text{star}}/M_{\text{SPS}}$ and SPS mass. The result from a study of the densest early-type galaxies in the SDSS by Dutton et al. (2012) is shown as a magenta point (this study assumes MFL models and

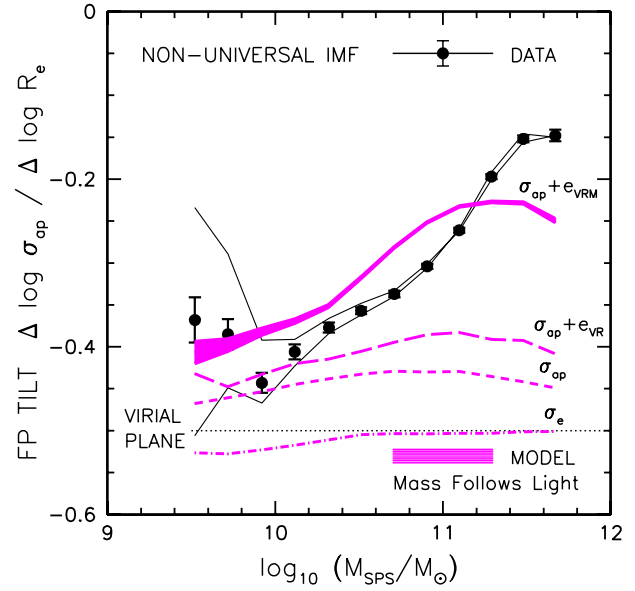


Figure 9. Effect of aperture and measurement errors on the fundamental plane tilt for models with mass-follows-light. A model with velocity dispersions measured within the effective radius, σ_e , closely follows the virial relation (dot-dashed line). Using aperture velocity dispersions, σ_{ap} , results in a weaker FP correlation by about $\simeq 0.06$ (short-dashed line). Measurement errors in sizes contribute $\simeq 0.04$ to the observed tilt (long-dashed line), while measurement errors on stellar masses (solid line) contribute up to $\simeq 0.15$ of the tilt at the highest masses.

justifies this based on the fact these galaxies follow the virial fundamental plane). The lower error bar shows the effect of changing the stellar anisotropy from $\beta = 0.0$ to $\beta = 0.5$. The result for bulge IMFs from a study of massive spiral galaxy strong lenses from Dutton et al. (2013) is given by the black square. The error bar corresponds to the 1σ uncertainty.

In the right panel of Fig. 10 we compare our results with Treu et al. (2010), Conroy & van Dokkum (2012) and Cappellari et al. (2012b) who compared the IMF mismatch with stellar velocity dispersion. These three results are in broad agreement with ours. The larger differences compared with the left panel are likely due to systematic errors in the conversion between SPS masses and velocity dispersion definitions. We detail the corrections we applied below. The results from the study of strong gravitational lenses by Treu et al. (2010) are shown with green squares (this study assumes NFW haloes with fixed scale radii). Here we have binned the individual measurements, so that the error bars correspond to the error on the mean. The slope inferred by Treu et al. (2010) is significantly steeper than what we favor, although the mean is in excellent agreement. The results from the study of stellar absorption lines by Conroy & van Dokkum (2012) are shown with black circles. Again here we have binned the individual measurements, so the error bars correspond to the error on the mean. We have converted their SPS masses from a Kroupa IMF into a Chabrier IMF by subtracting 0.035 dex. We have converted the aperture for the velocity dispersions from one eighth an effective radius to one effective radius by subtracting 0.06 dex. The results from the study of ATLAS3D galaxies by Cappellari

Table 2. Parameters of fits to IMF mismatch parameter vs velocity dispersion: $\Delta_{\text{IMF}} = a + b \log(\sigma_e/[130 \text{ km s}^{-1}])$

Halo Response ν	Anisotropy β	Δ_{IMF} zero a	Δ_{IMF} slope b
1.0	0.0	-0.049 ± 0.001	0.364 ± 0.003
0.5	0.0	0.084 ± 0.001	0.353 ± 0.002
0.0	0.0	0.164 ± 0.001	0.337 ± 0.002
-0.5	0.0	0.208 ± 0.001	0.316 ± 0.002
MFL	0.0	0.215 ± 0.001	0.298 ± 0.004
MFL	0.5	0.176 ± 0.001	0.299 ± 0.004

et al. (2012b) are given by the thin black line. We have converted their SPS masses from a Salpeter IMF to a Chabrier IMF by subtracting 0.23 dex. The grey shaded region corresponds to the 1σ uncertainty on their fit. Their slope is in excellent agreement with ours ($\simeq 1/3$), but there is a zero point offset of $\simeq 20\%$ compared to our best fitting MFL model.

6 DISCUSSION OF SYSTEMATIC EFFECTS

In this section we discuss how the simplifying assumptions of our model might lead to systematic biases in our results. We break these down into the following areas: dynamical models; stellar masses; and fundamental plane models.

6.1 Dynamical Models

We use spherical Jeans models to predict aperture velocity dispersions of early-type galaxies. However, early-type galaxies are in general not spherical, with average axis ratios decreasing (i.e., becoming flatter) with decreasing mass (e.g., Holden et al. 2012). We thus ignore any flattening induced by anisotropy or rotation in our models. Several studies have shown that spherical Jeans models do in fact recover accurate dynamical masses of non-spherical systems. For example, Cappellari et al. (2006) have shown that two and three integral models yield dynamical masses that are consistent with those obtained from a simple virial relation $M_{\text{dyn}} \propto \sigma_e^2 R_e$ for both fast- and slow-rotators. When combining strong lensing with kinematics to determine the slope of the total mass density profile, identical results (within the measurement errors) are obtained from two integral dynamical models with integral field kinematic data (Barnabé et al. 2011) and spherical Jeans models with a single kinematic measurement (Auger et al. 2010b).

For our fiducial models we assume isotropic velocity dispersions ($\beta = 0$), which is a good approximation for massive elliptical galaxies (e.g., Gerhard et al. 2001). Radially anisotropic velocity dispersions ($\beta > 0$) will result in higher σ_{ap} and thus lower stellar mass normalizations (see Fig. 5). In terms of the fundamental plane, $\beta = 0.5$ results in a weaker correlation by $\simeq 0.05$ than that for isotropic orbits, and thus will not be able to reconcile models with significant amounts of dark matter with the observed fundamental plane tilt.

6.2 Stellar Masses

The masses from SPS models are subject to a number of systematic uncertainties – from the treatment of uncertain aspects of stellar evolution, to the star formation and chemical enrichment histories of galaxies (e.g., Conroy et al. 2009; Gallazzi & Bell 2009). In principle these uncertainties could account for the factor of ~ 2 deviation in stellar masses from a Milky Way IMF that we infer. In practice, for old stellar populations, the effects of using different existing SPS models are of order 0.05-0.1 dex (e.g., Treu et al. 2010), and thus are not enough to reconcile our results with a universal IMF. As a specific example, a comparison of the stellar masses that we use in this study (from the MPA/JHU database) with those from Mendel et al. (2013) yields a systematic mass independent offset of $\simeq 0.04$ dex (MPA/JHU masses are lower) and a random uncertainty of $\simeq 0.08$ dex. These masses are based on both different SPS models – Bruzual & Charlot (2003) vs Conroy & Gunn (2010), and different photometry – SDSS vs Simard et al. (2011). Finally, we note that even if our conclusions regarding the IMF are biased by systematic uncertainties in SPS masses, our conclusions regarding the true stellar masses, dark matter fractions, and dark halo responses are independent of these uncertainties in SPS masses.

When parametrizing the deviation of the true stellar mass from the SPS stellar mass, $\Delta_{\text{IMF}} = M_{\text{star}}/M_{\text{SPS}}$, we have only considered variations as a function of M_{SPS} . This is driven by our decision to express scaling relations of galaxy properties, such as velocity dispersions and sizes, as a function of M_{SPS} , as well as defining the tilt of the fundamental plane in terms of the correlation between $\Delta \log \sigma_{\text{ap}}|M_{\text{SPS}}$ and $\Delta \log R_e|M_{\text{SPS}}$. In this context, if we were to consider Δ_{IMF} variation as a function of velocity dispersion, as has been suggested by numerous authors (e.g., Treu et al. 2010; Conroy & van Dokkum 2012; Cappellari et al. 2012b), we should recalculate the observed tilt of the fundamental plane for each variation considered, which would greatly increase the complexity of the model. However, since velocity dispersion and stellar mass are tightly correlated (e.g., see Fig. 1), these effects are small, and to first order any variation of Δ_{IMF} with velocity dispersion will also result in a equivalent variation with M_{SPS} . Fig. 10 indeed shows that in our models the IMF mismatch parameter is correlated with velocity dispersion, with a slope of $\simeq 0.33$ (see Table 2 for parameters of the fits). Our results are also consistent with results from previous measurements (e.g., Treu et al. 2010; Conroy & van Dokkum 2012; Cappellari et al. 2012b). As discussed above, the small (of order 10-20%) differences between the various measurements are consistent with systematic uncertainties in SPS masses and conversions between masses using different IMFs.

6.3 Fundamental Plane Models

When making model predictions for the tilt of the fundamental plane we assume (for simplicity) that variation in galaxy sizes at fixed stellar mass are independent of the properties of the dark matter halo (e.g., concentration, halo response parameter, halo mass). As we have shown above, with this assumption, models with halo contraction (and Milky Way type IMFs) predict a weaker fundamental plane

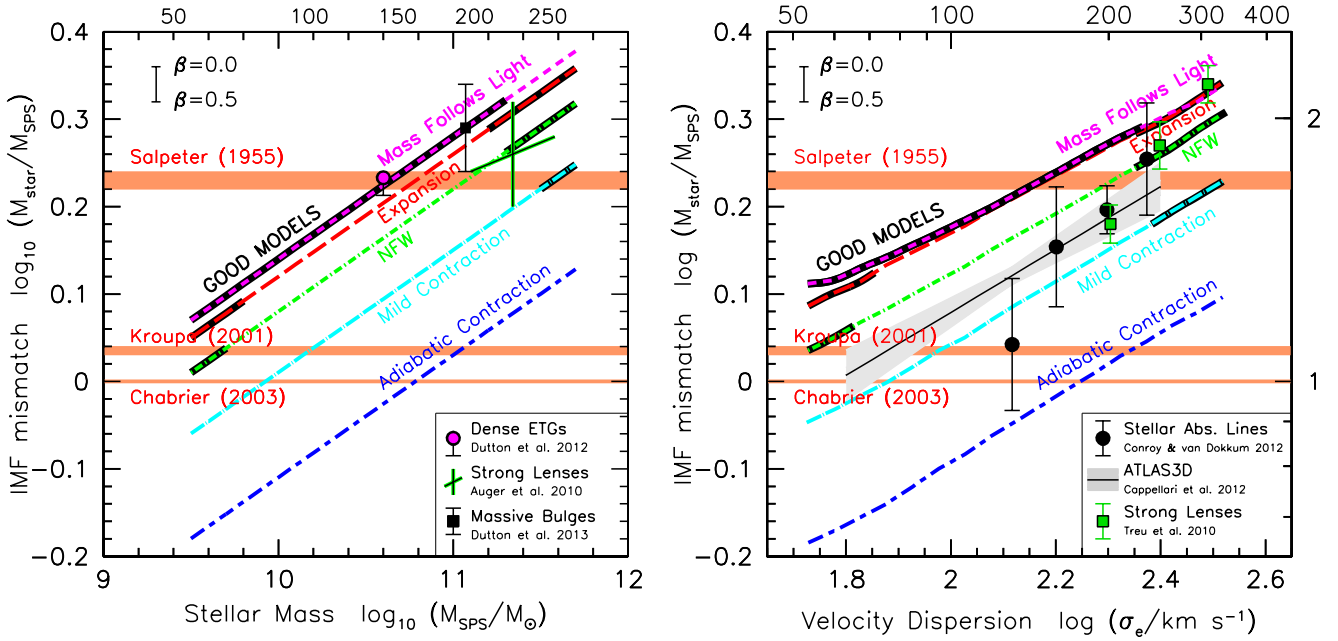


Figure 10. Summary of the main results for the stellar IMF and halo response of this paper. Reproducing the average Velocity - Mass (Faber-Jackson) relation is degenerate between IMF and dark halo response. For a universal dark halo response, a non-universal IMF is required (colored lines), with $M_{\text{star}}/M_{\text{SPS}} \propto M_{\text{SPS}}^{0.14}$ (left panel), or equivalently $M_{\text{star}}/M_{\text{SPS}} \propto \sigma_e^{0.33}$ (right panel), i.e., “heavier” IMFs in higher “mass” galaxies. The tilt of the stellar mass fundamental plane enables us to break this degeneracy. Acceptable models are indicated by thick solid black lines. The best models are mass follows light at low masses $M_{\text{SPS}} \lesssim 10^{11.2}$, and expansion or uncontracted NFW haloes for $M_{\text{SPS}} \gtrsim 10^{11.3}$. At the highest masses halo contraction is allowed given reasonable uncertainties in stellar mass errors. Changing the stellar anisotropy from $\beta = 0$ (isotropic orbits) to $\beta = 0.5$ only lowers the derived stellar masses by $\simeq 10\%$, as indicated by the error bar in the top left corner, (it does not change the conclusions regarding halo response). Our results are consistent with a number of recent studies as referenced by the caption in the lower right corner of each panel (see text for further details). In the left panel the upper horizontal axis shows the average aperture stellar velocity dispersions at the corresponding stellar masses.

tilt than observed. In order for such models to reproduce the observed fundamental plane tilt would require smaller galaxies (at fixed stellar mass) to have higher dark matter masses within an effective radius, and vice versa for larger galaxies. (We note that an interesting consequence of such a correlation is to reduce the scatter in the dark matter fractions within an effective radius). Qualitatively this could be achieved by introducing an anti-correlation between the size of a galaxy and the concentration of the dark matter halo, halo response parameter ν , or halo mass. Determining whether any of these correlations are expected in a Λ CDM context could be possible using cosmological hydrodynamical simulations, or semi-analytic models.

Strong gravitational lensing enables the slope of the total mass density profile to be measured within roughly the effective radius (e.g., Koopmans et al. 2006). This slope is generally referred to as γ' . Auger et al. (2010a) used this information implicitly to constrain the IMF and halo response. In Dutton & Treu (2013) the observed distribution of γ' is compared to that of a sub-sample of our models (with velocity dispersions $\sigma_{\text{ap}} \sim 250 \pm 40 \text{ km s}^{-1}$). Remarkably, the uncontracted NFW model, which best matches the fundamental plane tilt data at high masses (upper right panel of Fig. 7), also best matches the observed distribution of γ' . Not only does this provide independent confirmation of our model assumptions: i.e., that variation in galaxy sizes is uncorrelated with variation in halo masses and concentrations, it also shows that the observed non-homology in total

mass density profiles can be explained by a relatively simple model.

7 SUMMARY

We use the relations between aperture stellar velocity dispersion (σ_{ap}), stellar mass (M_{SPS}), and galaxy size (R_e) to constrain the dark halo response and stellar IMF in early-type galaxies. Our observational sample consists of $\sim 150\,000$ early-type galaxies from the SDSS/DR7 at redshift $z \sim 0.1$. We construct mass models with Λ CDM haloes (modified by contraction or expansion), as well as mass-follows-light (MFL), that reproduce the observed distribution of SPS stellar masses and galaxy sizes. Our models include uncorrelated scatter in galaxy sizes, halo masses and halo concentrations. The remaining free parameters of the model are constrained by the median relation between σ_{ap} and M_{SPS} (the Faber-Jackson relation), and the strength of the correlation between residuals of the σ_{ap} vs M_{SPS} and effective radius R_e vs M_{SPS} relations: $\partial_{\text{VR}} \equiv \Delta \log \sigma_{\text{ap}} / \Delta \log R_e$ (equivalent to the tilt of the fundamental plane).

Our constraints on the stellar IMF are obtained by comparing the true stellar masses (which we derive with our dynamical models) with those derived from stellar population synthesis models. Thus all of our conclusions regarding the IMF are dependent on there being no large systematic errors in SPS masses. Our constraints on the halo response are

however independent of these uncertainties. We summarize our results in Fig. 10 and as follows:

- Reproducing the median $\sigma_{\text{ap}} - M_{\text{SPS}}$ relation is not possible for models with *both* a universal IMF and universal dark halo response. Significant departures in either/or both are required.

- Models with a universal halo response to galaxy formation (as well as MFL) require heavier IMFs in higher mass galaxies and are consistent with $M_{\text{star}}/M_{\text{SPS}} \propto M_{\text{SPS}}^{0.14} \propto \sigma_e^{0.33}$. At a stellar mass of $M_{\text{SPS}} = 10^{11} M_{\odot}$ these models with adiabatic contraction require close to Chabrier IMFs, models with uncontracted NFW haloes require close to Salpeter IMFs, while MFL models require IMFs heavier than Salpeter.

- A model with a universal (close to Kroupa) IMF and mass dependent dark halo response ranging from expansion at low masses ($M_{\text{SPS}} \lesssim 10^{10} M_{\odot}$) to adiabatic contraction at high masses ($M_{\text{SPS}} \gtrsim 10^{11} M_{\odot}$) is able to reproduce the $\sigma_{\text{ap}} - M_{\text{SPS}}$ relation.

- We find that ∂_{VR} varies systematically with stellar mass. The minimum is $\partial_{\text{VR}} \simeq -0.45$ at $M_{\text{SPS}} = 10^{10} M_{\odot}$ (Chabrier IMF) and increases to $\partial_{\text{VR}} \simeq -0.15$ at $M_{\text{SPS}} = 10^{11.6} M_{\odot}$. The virial fundamental plane has $\partial_{\text{VR}} = -1/2$. And thus the observed tilt of the fundamental plane is not a constant, as is generally assumed.

- The MFL model successfully reproduces the mass dependent fundamental plane tilt for masses $M_{\text{SPS}} \lesssim 10^{11.2} M_{\odot}$. However, above $M_{\text{SPS}} \sim 10^{11.2}$ the MFL model progressively over-predicts the strength of ∂_{VR} . Reproducing the observations is possible with halo expansion for masses $M_{\text{SPS}} \gtrsim 10^{11.2}$, and uncontracted NFW haloes for $M_{\text{SPS}} \gtrsim 10^{11.3}$. At the highest masses models with halo contraction are also consistent with the data.

- Models with a universal IMF (and non-universal halo response) are unable to reproduce the tilt of the fundamental plane.

Our results are in agreement with several recent studies which also favor IMFs that are “heavier” than Salpeter in massive galactic spheroids, in addition to an effective stellar mass or velocity dispersion dependence to the IMF (van Dokkum & Conroy 2010; Auger et al. 2010a; Sonnenfeld et al. 2012; Conroy & van Dokkum 2012; Cappellari et al. 2012b; Newman et al. 2013; Dutton et al. 2013). As a final remark, we note that the absence of adiabatic contraction implied by our models indicates that non-dissipative mergers and/or feedback play an important role in the formation of early-type galaxies of *all* masses.

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APPENDIX A: CONSTRAINED Λ CDM BASED MASS MODELS OF EARLY-TYPE GALAXIES

In this appendix we describe the mass models we construct to reproduce the observed structural and dynamical scaling relations of early-type galaxies. These are the same as described in Dutton et al. (2011a). Our most general mass model consists of three spherical components: a stellar component with Sérsic index $n = 4$; a stellar component with Sérsic index $n = 1$; and a dark matter halo. The dark matter halo is an NFW (Navarro, Frenk, & White 1997) modified by the response of the halo to galaxy formation. This model has 7 parameters (4 for the stars and 3 for the dark matter), 5 of which are determined by observations and theory. The distribution of stellar mass in galaxies is described by three relations: half-light size vs SPS mass (for the $n = 1$ and $n = 4$ components) and de Vaucouleurs fraction f_{dev} vs SPS mass (the fits to these relations are given in Table A2). The relation between SPS mass and dark halo mass is taken from the compilation of observations by Dutton et al. (2010). The relation between dark halo concentration and dark halo mass is taken from Λ CDM N-body simulations in a WMAP5 cosmology (Macciò et al. 2008).

The two unknowns are the normalization of the stellar masses, which we term Δ_{IMF} , and the response of the dark matter halo to galaxy formation. Following Dutton et al. (2007; 2011) we consider a range of halo responses parametrized by the parameter ν . Where standard adiabatic contraction (Blumenthal et al. 1986) corresponds to $\nu = 1$, the contraction model of Gnedin et al. (2004) can be approximated with $\nu \simeq 0.8$, the contraction model of Abadi et al. (2010) can be approximated with $\nu \simeq 0.4$, an unmodified halo corresponds to $\nu = 0$, while expansion corresponds to $\nu < 0$. As a limiting case of maximum halo expansion we also consider models in which mass follows light (i.e., no dark matter).

The combinations of allowed Δ_{IMF} and ν are constrained by the observed velocity dispersion vs SPS mass relation (Fig. 1, Table A1). In Dutton et al. (2011a) we used empirical constraints (from strong lensing and dynamics) for the average conversion between circular velocity at the half-light radius $V_{\text{circ}}(R_e)$ and the velocity dispersion within the half-light radius, σ_e . In this paper we compute aperture velocity dispersions for our models by solving the spherical Jeans equations, as describe below.

A1 Predicting SDSS aperture velocity dispersions.

As described in the previous section, we have spherical models for the distribution of total and stellar mass. Given an assumption of the anisotropy profile we can then solve the spherical Jeans equations to get the radial velocity dispersion profile. We can then compute the projected velocity dispersions inside the SDSS aperture including the effects of seeing. The relevant equations are given below.

We consider spherical galaxy models with 3D stellar density distribution $\rho_*(r)$, and projected stellar density distribution $\Sigma_*(R)$. The radial component $\sigma_r(r)$ of the velocity dispersion tensor is found by solving the Jeans equations:

$$\frac{d(\rho_*\sigma_r^2)}{dr} + \frac{2\beta}{r}\rho_*\sigma_r^2 = -\rho_*\frac{GM(r)}{r^2}, \quad (\text{A1})$$

where β is the velocity anisotropy, and $M(r)$ is the spherically enclosed mass within radius r . The solution of the Jeans equation is given by

$$\rho_*\sigma_r^2 = \frac{1}{I} \int_r^\infty I \rho_* \frac{GM}{x^2} dx \quad (\text{A2})$$

where $I = \exp \int (2\beta/r) dr$ is the integrating factor. For constant β the integrating factor is $I = r^{2\beta}$. If we start with a 2D surface density profile (e.g., a Sérsic profile), the 3D surface density profile is given by

$$\rho_*(r) = -\frac{1}{\pi} \int_r^\infty \frac{d\Sigma_*(R)}{dR} \frac{dR}{\sqrt{R^2 - r^2}}. \quad (\text{A3})$$

Alternatively, if we start with a 3D density profile (e.g., a Hernquist profile which approximates a Sérsic $n = 4$ profile), the projected density profile is

$$\Sigma_*(R) = 2 \int_R^\infty \rho_*(r) \frac{r}{\sqrt{r^2 - R^2}} dr. \quad (\text{A4})$$

In practice, for our default models, we adopt two components: an exponential (in projection) for which Eq. A3 has an analytic solution (e.g., van den Bosch & de Zeeuw 1996), and a Hernquist profile for which Eq. A4 has an analytic solution (Hernquist 1990). The parameters of these two components that we use in our models are given in Table A2.

The projected velocity dispersion is given by

$$\Sigma_*\sigma_p^2 = 2 \int_R^\infty \left[1 - \beta \frac{R^2}{r^2} \right] \rho_*\sigma_r^2 \frac{r}{\sqrt{r^2 - R^2}} dr. \quad (\text{A5})$$

The SDSS spectra are measured within a 3 arcsec diameter aperture, so the aperture projected velocity dispersion is given by

$$\sigma_{\text{ap}}^2 = \frac{\int_0^{R_{\text{ap}}} \langle \Sigma_* \sigma_p^2 \rangle 2\pi R dR}{\int_0^{R_{\text{ap}}} \langle \Sigma_* \rangle 2\pi R dR}. \quad (\text{A6})$$

Where the angled brackets indicate variables that have been convolved with the seeing. We assuming a Gaussian with FWHM=1.4 arcsec, which is the median seeing for SDSS (Simard et al. 2011).

Fig. A1 shows an example mass model consisting of an NFW dark matter halo and a Hernquist bulge of stars. The upper panel shows circular velocity (black lines) and aperture velocity dispersion (red lines) profiles. The total circular velocity is given by the solid black line, while the contribution from the stars is given by the black dashed line. The dark matter halo makes up the difference between these two lines. The aperture velocity dispersions are given for different values of the anisotropy parameter, β , chosen to bracket the values observed in early-type galaxies (Gerhard et al. 2001).

The vertical lines mark useful apertures: R_e is the projected half-light radius (also known as the effective radius), $R_{1/2}$ is the 3D half-light radius. The two most common apertures for measuring or ‘‘correcting’’ aperture velocity dispersions are R_e and $R_e/8$.

As shown by (e.g., Wolf et al. 2010), if the radial velocity dispersion profile is constant (i.e., $d \ln \sigma_r^2 / d \ln r = 0$), then the mass within the 3D half-light radius $M_{1/2} = 3\sigma_{\text{los}}^2 R_{1/2} / G$, where σ_{los}^2 is the integrated line-of-sight velocity dispersion of the system. This can be more compactly

Table A1. Observed aperture velocity dispersion (σ_{ap}) - stellar mass (M_{SPS}) and circularized effective radius (R_e) - stellar mass relations from Fig. 1, and the correlation between the residuals of these relations from Fig. 3

$\log_{10}(M_{\text{SPS}}/M_{\odot})$			$\log_{10}(\sigma_{\text{ap}}/\text{km s}^{-1})$			$\log_{10}(R_e/\text{kpc})$			$\Delta \log_{10}(\sigma_{\text{ap}})/\Delta \log_{10}(R_e)$
min	max	median	median	16th % ile	84th % ile	median	16th % ile	84th % ile	
9.4	9.6	9.515	1.748±0.009	1.602	1.856	0.078±0.012	-0.133	0.236	-0.368±0.027 ^(+0.134) _(-0.138)
9.6	9.8	9.712	1.822±0.005	1.710	1.942	0.083±0.009	-0.106	0.256	-0.385±0.018 ^(+0.096) _(-0.064)
9.8	10.0	9.912	1.896±0.004	1.786	2.028	0.139±0.006	-0.051	0.313	-0.443±0.012 ^(+0.051) _(-0.024)
10.0	10.2	10.112	1.977±0.002	1.862	2.091	0.199±0.004	0.012	0.361	-0.406±0.009 ^(+0.015) _(-0.017)
10.2	10.4	10.313	2.056±0.001	1.955	2.153	0.260±0.002	0.106	0.425	-0.377±0.006 ^(+0.011) _(-0.007)
10.4	10.6	10.508	2.119±0.001	2.031	2.208	0.348±0.002	0.206	0.498	-0.357±0.004 ^(+0.009) _(-0.005)
10.6	10.8	10.707	2.179±0.001	2.093	2.261	0.453±0.001	0.324	0.592	-0.337±0.004 ^(+0.004) _(-0.003)
10.8	11.0	10.903	2.238±0.001	2.155	2.310	0.564±0.001	0.450	0.691	-0.304±0.003 ^(+0.003) _(-0.002)
11.0	11.2	11.098	2.294±0.001	2.218	2.359	0.676±0.001	0.568	0.796	-0.261±0.003 ^(+0.002) _(-0.001)
11.2	11.4	11.293	2.347±0.001	2.280	2.405	0.791±0.001	0.688	0.908	-0.197±0.003 ^(+0.005) _(-0.004)
11.4	11.6	11.486	2.392±0.001	2.333	2.447	0.921±0.001	0.814	1.042	-0.152±0.004 ^(+0.006) _(-0.004)
11.6	11.8	11.678	2.431±0.001	2.375	2.482	1.064±0.002	0.951	1.181	-0.148±0.007 ^(+0.000) _(-0.002)

Table A2. Parameters of the fitting formula (Eqs. 4 & 5) for various scaling relations used in this paper.

y	x	α	β	x_0	y_0	γ
$\log_{10}(\sigma_{\text{ap}}/\text{km s}^{-1})$	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	0.42	0.20	10.7	2.18	1.0
$\log_{10}(R_e/\text{kpc})$	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	0.00	0.70	10.2	0.22	1.0
$\log_{10}(R_{\text{ap}}/\text{kpc})$	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	0.45	0.24	11.1	0.54	1.2
$\sigma_{\log R_{\text{ap}}}$	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	0.046	-0.037	10.1	0.098	2.0
f_{deV}	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	0.17	-0.22	10.9	0.65	2.0
$\log_{10}(R_{\text{deV}}/\text{kpc})$	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	-0.01	0.55	10.0	-0.08	2.0
$\log_{10}(R_{\text{exp}}/\text{kpc})$	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	0.29	0.61	10.1	0.39	1.0
$e \log \sigma_{\text{ap}}$	$\log_{10}(\sigma_{\text{ap}}/\text{km s}^{-1})$	-0.8	0.0	1.7	0.093	3.8
$e \log R_e$	$\log_{10}(R_e/\text{kpc})$	0.035	...
$e \log M_{\text{SPS}}$	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	0.092	...
y	x	y_1	y_2	x_0	...	γ
$\sigma_{\log_{10}(\sigma_{\text{ap}})}$	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	0.12	0.045	10.7	...	1.0
$\sigma_{\log_{10}(R_e)}$	$\log_{10}(M_{\text{SPS}}/M_{\odot})$	0.18	0.10	10.55	...	1.8

expressed in terms of circular velocity: $V_{1/2} = \sqrt{3}\sigma_{\text{los}}^2$. However, in general galaxies do not have constant velocity dispersion profiles, and for galaxies in SDSS the observed aperture typically contains less half the light (see below). Thus we expect some variation from the formula from Wolf et al. (2010).

The lower panel in Fig. A1 shows the relation between the circular velocity at the 3D half-light radius ($V_{1/2}$), and the projected velocity dispersion ($\sigma_{\text{ap}}(R)$) measured within a radius R . For large apertures $R \sim 2R_e$ the circular velocity is indeed almost independent of anisotropy. However, for the typical apertures for SDSS galaxies ($0.5 \lesssim R_e \lesssim 1.0$), there is a non-negligible dependence of circular velocity on anisotropy. Furthermore, when using velocity dispersions within on eighth of an effective radius, there is a large dependence of circular velocity on anisotropy $V_{1/2}/\sigma_{\text{ap}}$ varies from 1.3 to 1.8. Thus by correcting the aperture to smaller radii than observed information is lost, while correcting the aperture to larger radii than observed a specific mass profile is assumed. This motivates us to model the aperture velocity dispersions directly.

The aperture one measures the velocity dispersions in-

side also impacts the strength of non-homology on the derived dynamical masses. Using relations from Bertin et al. (2002) and Cappellari et al. (2006) Fig. A2 shows that effects of non-homology on dynamical masses are significantly weaker when velocity dispersions are measured within the effective radius (as is typical of galaxies in our study) compared to one eighth of the effective radius (as is often used in the literature e.g., Trujillo et al. 2004; Taylor et al. 2010).

Since the standard aperture correction to fiber velocity dispersions (e.g., Jorgensen et al. 1995) results in a constant offset between velocity dispersions measured with R_e and $R_e/8$, Fig. A2 reveals a fundamental inconsistency. Obviously, the dynamical masses should be independent of the aperture used to measure the velocity dispersion. In order for this to be the case with mass-follows-light Sérsic models, requires the aperture correction depends on Sérsic index (see Fig. A3):

$$\sigma_{e8}/\sigma_e = \sqrt{c(R_e)/c(R_e/8)}, \quad (\text{A7})$$

where $c(R_e)$ is (Cappellari et al. (2006)

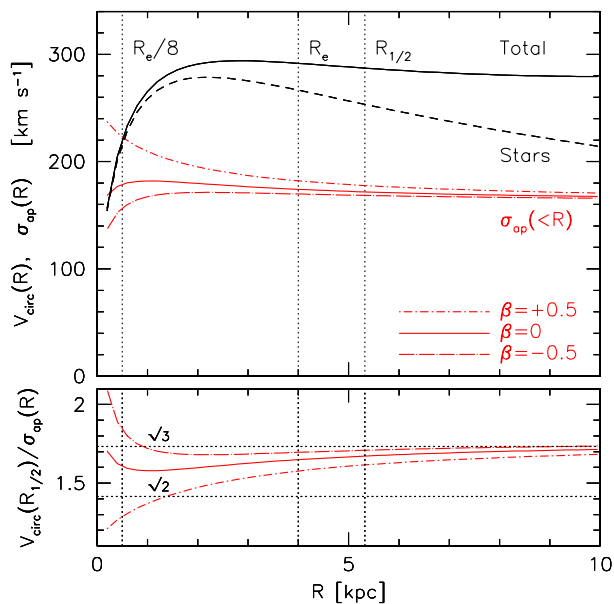


Figure A1. Example circular velocity and projected velocity-dispersion profiles for a model galaxy made of a Hernquist sphere of stars and a cosmologically motivated NFW dark matter halo.

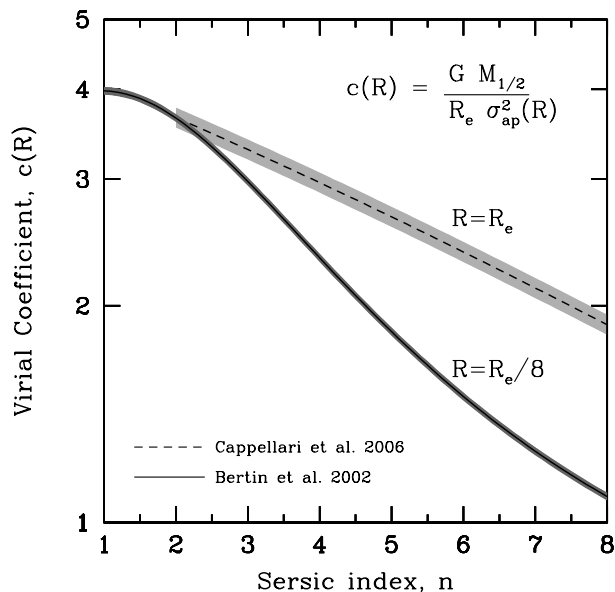


Figure A2. Virial coefficient (assuming isotropy and mass-follows-light) as a function of Sérsic index for velocity dispersions measured within the effective radius, R_e (using the relation from Cappellari et al. 2006), and one eighth of the effective radius (using the relation from Bertin et al. 2002). The shaded regions show the maximum quoted error in the fitting formulae. The effect of non-homology on dynamical masses is weaker when velocity dispersions are measured within larger apertures.

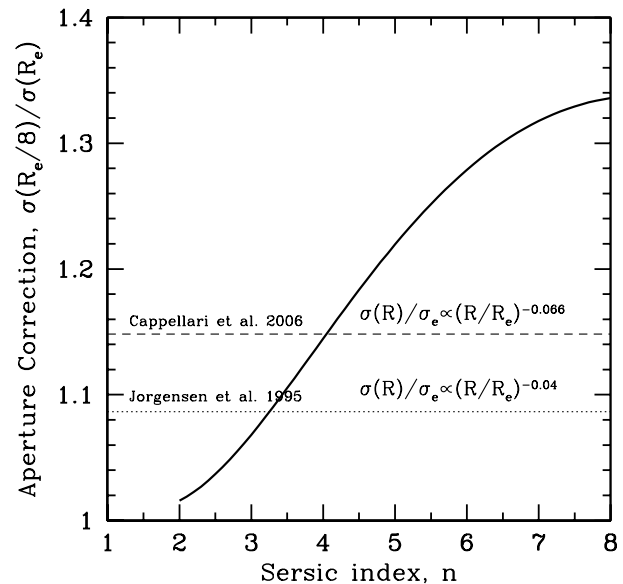


Figure A3. Aperture correction as a function of Sérsic index as implied by mass follows light models with isotropic stellar orbits from Fig. A2. The standard aperture corrections (Jorgensen et al. 1995 - dotted line; Cappellari et al. 2006 - dashed line) are independent of Sérsic index, and thus inconsistent with mass-follows-light models with high ($n \gtrsim 4$) or low ($n \lesssim 3$) Sérsic indices.

$$c(R_e) = \frac{1}{2} [8.87 - 0.831n + 0.0241n^2], \quad (\text{A8})$$

and $c(R_e/8)$ is (Bertin et al. 2002)

$$c(R_e/8) = \frac{1}{2} \{73.32/[10.465 + (n - 0.95)^2] + 0.954\}. \quad (\text{A9})$$

The factor of half in front of the virial coefficients is due to our defining the dynamical mass to be with the spherical half-light radius, rather than the total mass.

A2 Physical aperture sizes

Since we are modeling the aperture velocity dispersion, we need to know the physical size of the aperture. This will depend on the redshift of the galaxy. Fig. A4 shows the aperture radius in kpc as a function of stellar mass. In the upper panel the solid points show the median relation, while the solid line is a fit to these data points (see Table A2 for the parameters of the fit). The red dashed line shows the median effective radius (from Fig. 1), which shows that for all but the lowest and highest mass galaxies the average SDSS aperture is close to the half-light radius. For the most massive galaxies the median aperture is roughly $0.5R_e$. There is scatter in the aperture radius at fixed mass, but it turns out not to induce any significant scatter to the model velocity dispersions.

A3 Sampling of Galaxies

The observed sampling of the stellar masses of galaxies is not uniform. The distribution is very roughly log-normal with a peak at $M_{\text{SPS}} = 10^{11} M_{\odot}$ (error bars in Fig. A5).

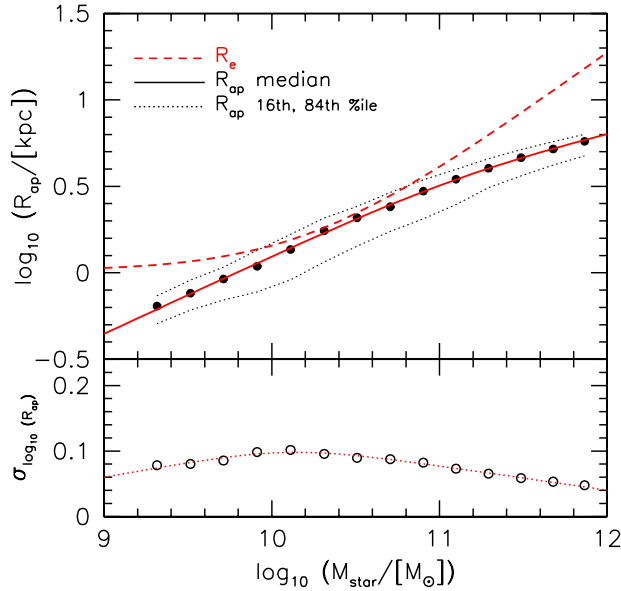


Figure A4. Aperture size - stellar mass relation. *Upper panel:* Solid points show median of aperture sizes in kpc, solid line shows a fit to these points. The dotted lines show the 16th and 84th percentiles. For comparison the red dashed line shows the median half-light radius. This shows that for all but the highest and lowest masses, the SDSS fiber aperture, on average, corresponds to the half-light radius. *Lower panel:* Scatter in the aperture sizes.

Measurement uncertainties in stellar masses will preferentially scatter galaxies away from the peak. We fit the distribution of stellar masses with a set of Gaussians (red lines in Fig. A5), and since the measurement errors are roughly constant, we can thus deconvolve the observed distribution of stellar masses analytically (green lines in Fig. A5). The differences between the model and deconvolved model are shown in the lower panel of Fig. A5. The most significant differences occur for high masses ($M_{\text{SPS}} \gtrsim 10^{11.5} M_{\odot}$), where the deconvolved model has up to a factor of 1.6 fewer galaxies. The net effect of the non-uniform stellar mass distribution coupled to errors on stellar masses is to make the observed relations (slightly) shallower than the true relations.

A4 Adding scatter to the models

We add both intrinsic and observational sources of scatter to our models. There are three primary sources of intrinsic scatter: 1) Scatter in galaxy size at fixed stellar mass; 2) Scatter in the “pristine” dark halo concentration at fixed halo mass; and 3) Scatter in dark halo mass at fixed stellar mass. The scatter in size at fixed stellar mass is taken from the observed RM relation (Fig. 1). The scatter in the pristine halo concentration for relaxed haloes in cosmological simulations is $\simeq 0.11$ dex (Jing 2000; Wechsler et al. 2002; Macciò et al. 2008). The scatter in stellar mass at fixed halo mass is about 0.15 dex (e.g., More et al. 2011). However due to shallow slope of the stellar mass vs halo mass relation at high halo masses, the scatter in halo mass at fixed stellar mass increases with stellar mass. The results from More et al. (2011) for red galaxies can be approximated by

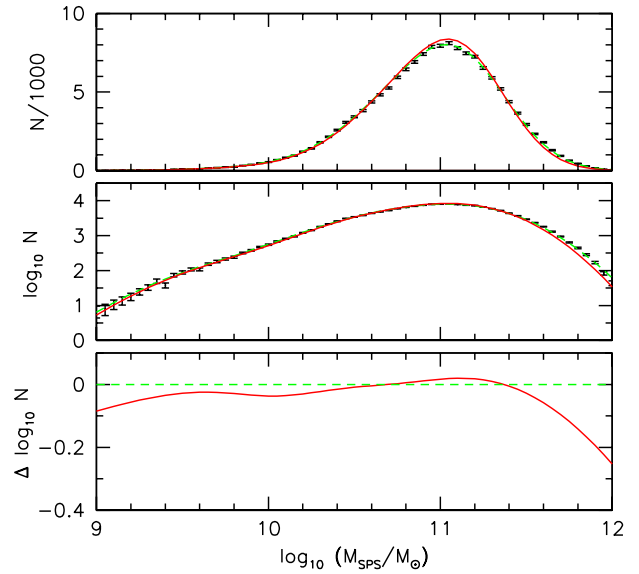


Figure A5. Observed distribution of galaxy stellar masses (assuming a Chabrier IMF). *Upper panel:* black points with error bars show the data, red lines show a triple Gaussian fit, green lines show the intrinsic distribution after correcting for measurement errors of 0.1 dex in stellar mass. *Middle panel:* Same as upper panel but for a logarithmic scale. *Lower panel:* Difference between $\log_{10} N$ of the model and deconvolved model. At high stellar masses the differences can be up to a factor of ~ 1.6 .

$$\sigma_{\log M_{\text{vir}}} = 0.15 + 0.2(\log M_{\text{SPS}} - 10.4), \text{ with a minimum of } 0.15.$$

Additionally there is scatter in the aperture radius at fixed stellar mass from the redshift sampling of galaxies, and is given in Fig. A4. It turns out that this adds negligible scatter to the VM relation, and so we do not include it in our fiducial models.

There are measurement errors in stellar masses, sizes and velocity dispersions. These measurement errors are roughly constant (Fig. A6) with $\sigma_{\log M_{\text{SPS}}} \simeq 0.1$, $\sigma_{\log R_e} \simeq 0.035$ and $\sigma_{\log \sigma_{\text{ap}}} \simeq 0.04$. For our purposes the measurement errors in stellar masses and sizes are more important than the measurement errors in velocity dispersions. This is because we bin galaxies in both stellar mass and size, but not velocity dispersion. Errors in stellar masses can change the slope of the correlation between VM and RM residuals, and thus are especially important to account for.

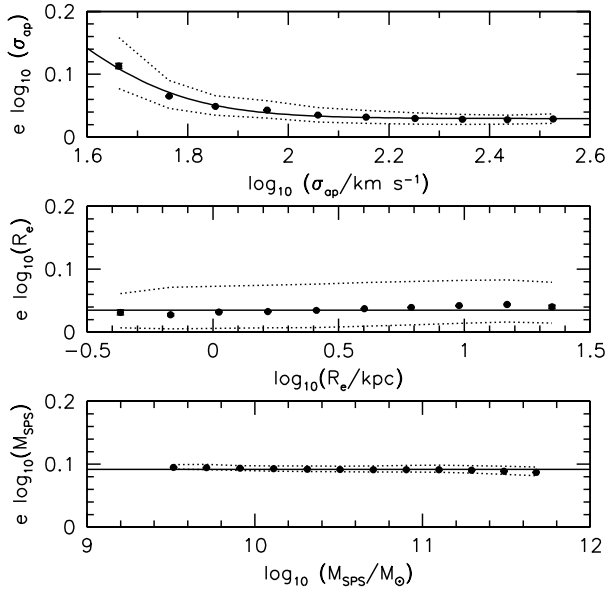


Figure A6. Measurement errors on velocity dispersion (σ_{ap}), half-light size (R_e), and stellar mass (M_{SPS}). Typical errors are 0.03 dex on velocity dispersion, 0.03 dex on size, and 0.1 dex on stellar mass. The average errors are fitted with Eq. 4, with parameters given in Table A2.