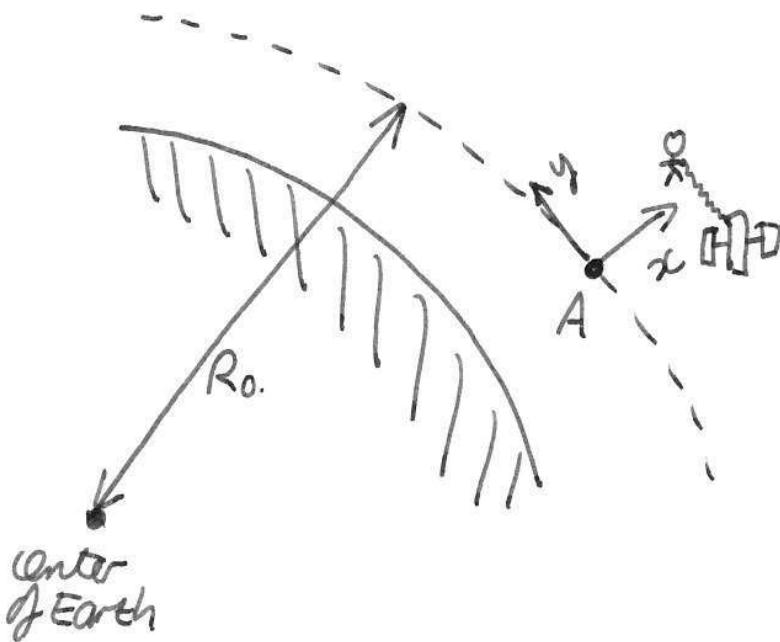


③ Astronaut on a bungee cord

⑥



A is "guiding center" of the perturbed orbits.

① Let \underline{r}_1 be posⁿ vector of astronaut
 \underline{r}_2 " " " " space station

Then the full equation of motion for the astronaut is

$$m_1 \ddot{\underline{r}}_1 = -\frac{GMm_1}{r_1^2} \hat{\underline{r}}_1 + k(\underline{r}_2 - \underline{r}_1)$$

Following approach used in class, we split into radial and tangential components :

$$\ddot{R}_1 - R_1 \dot{\phi}_1 = -\frac{GM}{R_1^2} + \frac{k}{m_1} (\underline{r}_2 - \underline{r}_1) \cdot \hat{\underline{R}} \quad \dots \textcircled{1}$$

$$R_1 \ddot{\phi}_1 + 2\dot{R}_1 \dot{\phi}_1 = \frac{k}{m_1} (\underline{r}_2 - \underline{r}_1) \cdot \hat{\underline{\phi}} \quad \dots \textcircled{2}$$

As in class, we set

$$R_1 = R_0 + \delta c_1$$

$$\phi_1 = \Omega_0 t + \gamma / R_0$$

where $\Omega_0 = (GM/R_0^3)^{1/2}$ is ang. velocity of reference circular orbit

This means that

(7)

$$\begin{aligned}\underline{x}_1 &= (R_0 + x_1) \hat{\underline{R}} + y_1 \hat{\underline{q}} \\ \underline{x}_2 &= (R_0 + x_2) \hat{\underline{R}} + y_2 \hat{\underline{q}}\end{aligned}$$

So equation ① becomes

$$\ddot{x}_1 - (R_0 + x_1)(\omega_0 + \dot{y}/R_0)^2 = -\frac{GM}{(R_0 + x_1)^2} + \frac{k}{m_1} (x_2 - x_1)$$

$$\Rightarrow \ddot{x}_1 - R_0 \omega_0^2 - \omega_0^2 x_1 - 2R_0 \dot{y}_1 \omega_0 / R_0 \\ = -\frac{GM}{R_0^2} + 2x_1 \frac{GM}{R_0^3} + \frac{k}{m_1} (x_2 - x_1)$$

(dropping terms like \dot{y}_1^2 and $x_1 \dot{y}_1$, since they are small, and Taylor expanding $GM/(R_0 + x_1)^2$ to first order)

$$\Rightarrow \ddot{x}_1 - R_0 \omega_0^2 - \omega_0^2 x_1 - 2\omega_0 \dot{y}_1 = -R_0 \omega_0^2 + 2x_1 \omega_0^2 + \frac{k}{m_1} (x_2 - x_1)$$

where we have used
fact that $\omega_0^2 = GM/R_0^3$

$$\Rightarrow \ddot{x}_1 - 3\omega_0^2 x_1 - 2\omega_0 \dot{y}_1 - \frac{k}{m_1} (x_2 - x_1) = 0 \quad \dots \textcircled{3}$$

Equation ② becomes

$$(R_0 + x_1) \ddot{y}_1 / R_0 + 2\dot{x}_1 (\omega_0 + \dot{y}/R_0) = \frac{k}{m_1} (y_2 - y_1)$$

$$\Rightarrow \ddot{y}_1 + 2\dot{x}_1 \omega_0 - \frac{k}{m_1} (y_2 - y_1) = 0 \quad \dots \textcircled{4}$$

where we have neglected terms like $x_1 \ddot{y}_1$ & $\dot{x}_1 \dot{y}_1$
since they are small in comparison.

Equations ③ & ④ are the required equations of motion

(b) The derivation of the equation of motion for the space station⁽⁸⁾ will look exactly the same except that the labels "1" and "2" will be transposed. So,

$$\ddot{x}_2 - 3\omega_0^2 x_2 - 2\omega_0 \dot{y}_2 + -\frac{k}{m_2} (x_1 - x_2) = 0 \quad \dots \textcircled{5}$$

$$\ddot{y}_2 + 2\dot{x}_2 \omega_0 - \frac{k}{m_2} (y_1 - y_2) = 0 \quad \dots \textcircled{6}$$

Subtract (5) from (3) gives

$$\ddot{x}_1 - \ddot{x}_2 - 3\omega_0^2 x_1 + 3\omega_0^2 x_2 - 2\omega_0 \dot{y}_1 + 2\omega_0 \dot{y}_2 - \frac{k}{m_1} (x_2 - x_1) + \frac{k}{m_2} (x_1 - x_2) = 0$$

$$\Rightarrow (\ddot{x}_1 - \ddot{x}_2) - 3\omega_0^2 (x_1 - x_2) - 2\omega_0 (\dot{y}_1 - \dot{y}_2) + k(x_1 - x_2) \left(\frac{1}{m_2} + \frac{1}{m_1} \right) = 0$$

Let $\Delta x = x_1 - x_2$ and $\Delta y = y_1 - y_2$. So, this last eqⁿ reads

$$\ddot{\Delta x} - 3\omega_0^2 \Delta x - 2\omega_0 \Delta y + k \Delta x \left(\frac{1}{m_2} + \frac{1}{m_1} \right) = 0$$

But $m_2 \gg m_1$, so $\frac{1}{m_2} \ll \frac{1}{m_1}$. Thus, neglecting $\frac{1}{m_2}$ term gives

$$\ddot{\Delta x} - (3\omega_0^2 - \frac{k}{m_1}) \Delta x - 2\omega_0 \Delta y = 0 \quad \dots \textcircled{7}$$

Subtract (6) from (4)

$$\ddot{y}_1 - \ddot{y}_2 + 2\dot{x}_1 \omega_0 - 2\dot{x}_2 \omega_0 - \frac{k}{m_1} (y_2 - y_1) + \frac{k}{m_2} (y_1 - y_2) = 0$$

$$\Rightarrow \ddot{\Delta y} + 2\omega_0 \Delta x + k \Delta y \left(\frac{1}{m_1} + \frac{1}{m_2} \right) = 0$$

$$\Rightarrow \ddot{\Delta y} + 2\omega_0 \Delta x + \frac{k}{m_1} \Delta y = 0 \quad \dots \textcircled{8}$$

As REQUIRED

⑥ k/m_1 has units of frequency-squared, so it should be compared with the only other frequency in the problem, Ω_{R_0} . Suppose that

$$\frac{k}{m_1} \gg \Omega_{\text{R}_0}^2$$

Then, we can essentially neglect the terms containing Ω_{R_0} in the equation of motion. So, we have

$$\ddot{\Delta x} + \frac{k}{m_1} \Delta x = 0$$

$$\ddot{\Delta y} + \frac{k}{m_1} \Delta y = 0$$

This is the simple harmonic oscillator eqn... both Δx and Δy execute SHO with frequency $\omega = \sqrt{k/m_1}$, i.e.

$$\Delta x = A \cos(\omega t + \phi_A)$$

$$\Delta y = B \cos(\omega t + \phi_B)$$

$$\omega = \sqrt{k/m_1} \text{ and } A, B, \phi_A, \phi_B \text{ constants}$$

So, the astronaut executes "orbits" around the space-station. The space-station is at the center of the elliptical orbit and the period of the orbit is $T = 2\pi/\omega$.

⑦ Need to combine eqns to eliminate Δy . Start with

$$\ddot{\Delta x} - (3\Omega_{\text{R}_0}^2 - \frac{k}{m_1}) \Delta x - 2\Omega_{\text{R}_0} \dot{\Delta y} = 0 \dots$$

$$\Rightarrow \ddot{\Delta x} - (3\Omega_{\text{R}_0}^2 - \frac{k}{m_1}) \Delta x - 2\Omega_{\text{R}_0} \ddot{\Delta y} = 0 \quad \text{differentiate wrt time.}$$

But, we know that

$$\ddot{\Delta y} = -2\Omega_{\text{R}_0} \dot{\Delta x} - \frac{k}{m_1} \Delta y$$

(10)

Subst. this into eqⁿ for $\ddot{\Delta}x$ gives

$$\ddot{\Delta}x - (3\Omega_0^2 - \frac{k}{m_1})\Delta\dot{x} - 2\Omega_0(-2\Omega_0\Delta\dot{x} - \frac{k}{m_1}\Delta y) = 0$$

$$\Rightarrow \ddot{\Delta}x + (\Omega_0^2 + \frac{k}{m_1})\Delta\dot{x} + 2\Omega_0\frac{k}{m_1}\Delta y = 0$$

$$\Rightarrow \ddot{\Delta}x + (\Omega_0^2 + \frac{k}{m_1})\ddot{\Delta}x + 2\Omega_0\frac{k}{m_1}\Delta y = 0$$

But, from ⑦ we have

$$2\Omega_0\Delta y = \ddot{\Delta}x - (3\Omega_0^2 - \frac{k}{m_1})\Delta x$$

Subst. this into eqⁿ for $\ddot{\Delta}x$ gives

$$\ddot{\Delta}x + (\Omega_0^2 + \frac{k}{m_1})\ddot{\Delta}x + \cancel{2\Omega_0\frac{k}{m_1}}(\ddot{\Delta}x - [3\Omega_0^2 - \frac{k}{m_1}]\Delta x) = 0$$

$$\Rightarrow \ddot{\Delta}x + (\Omega_0^2 + \frac{2k}{m_1})\ddot{\Delta}x - \frac{k}{m_1}(3\Omega_0^2 - \frac{k}{m_1})\Delta x = 0$$

This is the required differential equation.

To get characteristic equation, substitute in $\Delta x = A e^{\alpha t}$.

Then

$$\dot{\Delta}x = A\alpha e^{\alpha t} = \alpha \Delta x$$

$$\ddot{\Delta}x = \alpha \dot{\Delta}x = \alpha^2 \Delta x$$

$$\therefore \ddot{\Delta}x = \alpha^4 \Delta x$$

So, we get

$$\alpha^4 \Delta x + (\Omega_0^2 + \frac{2k}{m_1})\alpha^2 \Delta x - \frac{k}{m_1}(3\Omega_0^2 - \frac{k}{m_1})\Delta x = 0$$

$$\Rightarrow \alpha^4 + (\Omega_0^2 + \frac{2k}{m_1})\alpha^2 - \frac{k}{m_1}(3\Omega_0^2 - \frac{k}{m_1}) = 0$$

As REQUIRED.

② Suppose that the characteristic equation has a positive real root α . Then the general solution of the differential equation will have a term that looks like $A e^{\alpha t}$

But $e^{\alpha t} \rightarrow \infty$ as $t \rightarrow \infty$ and so solution blows up!!

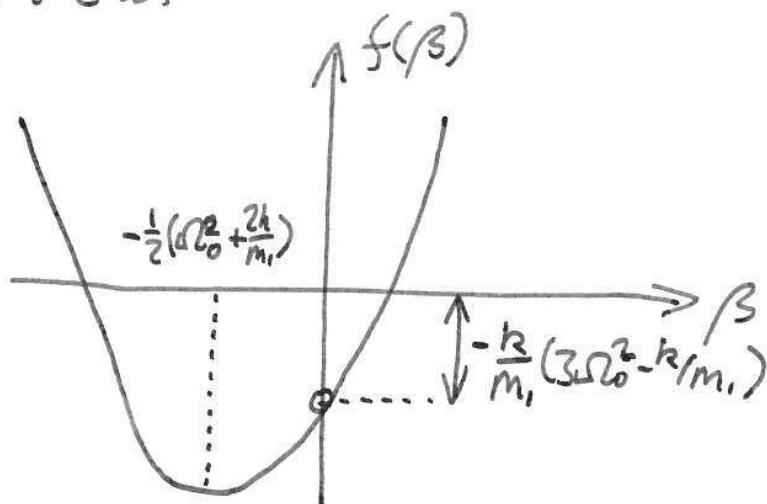
View characteristic equation as a quadratic in $\beta = \alpha^2$. Then there will be a positive real root if and only if the quadratic for β has a positive real root.

③ Look at characteristic equation as quadratic in $\beta = \alpha^2$.

$$\beta^2 + (\omega_0^2 + \frac{2k}{m_1})\beta - \frac{k}{m_1}(3\omega_0^2 - \frac{k}{m_1}) = 0$$

$$\text{i.e. } f(\beta) = 0, \quad f(\beta) = \beta^2 + (\omega_0^2 + \frac{2k}{m_1})\beta - \frac{k}{m_1}(3\omega_0^2 - \frac{k}{m_1})$$

Let's graph this :



The equation $f(\beta) = 0$ has real roots if and only if

$$\frac{k}{m_1}(3\omega_0^2 - k/m_1) \geq 0$$

$$\Rightarrow k \leq 3\omega_0^2 m_1$$

Thus, if the bungee cord is weak ($k < 3\pi^2 m$),
then the general equation of the differential equation
will have an exponentially diverging piece.

The astronaut will drift away from the station
at an exponential rate !!

(2)