

# Data Representations

- Computers store data as different variable types, e.g. integer, floating point, complex, etc.
- Different machines have different wordlengths, e.g. 4-byte `ints` on a 32-bit machine (Pentium), 8-byte `ints` on a 64-bit machine (Alpha).
- This makes (binary) data non-portable.

# Integers

- All data types represented by 0's and 1's.
- An integer value:

$$j = \sum_{i=1}^N s_i \times 2^{N-i}$$

- $N$  = # of bits in word
- $s_i$  = value of bit  $i$  in binary string  $s$
- e.g. 0 0 0 0 0 1 1 0 =  $2^2 + 2^1 = 6$  for 8-bit word.
- Use "two's complement" method for sign.

# Integers, Cont'd

- Largest value that can be represented is  $2^N - 1$ .
- For 32-bit word this is 4,294,967,295.
- Arithmetic with integers is exact, except:
  - When division results in remainder.
  - Result exceeds largest representable integer  
e.g.  $2 \times 10^9 + 3 \times 10^9 = \text{overflow error}$
- Note multiplication by 2's can be achieved by left-shift, which is very fast (in C: "<<" operator).

# Two's Complement

- Exploits finite size of data representations (cyclic groups) and properties of binary arithmetic.
- To get negative of binary number, invert all bits and add 1 to the result.

e.g.  $1 = 00000001$  in 8-bit

invert bits:  $11111110$

add 1:  $00000001$

result:  $11111111 = -1$

- In 8 bits, signed char ranges from -128 to +127.

# Negative Powers of 2

- Binary notation can be extended to cover negative powers of 2, e.g. "110.101" is:

$$1 \times 2^2 + 1 \times 2^1 + 1 \times 2^{-1} + 1 \times 2^{-3} = 6.625$$

- Can represent real numbers by specifying some location in the word as the "binary point" → fixed-point representation.
- In practice, use some bits for an exponent → floating-point representation.

# Floats

- For most machines these days, real numbers are represented by floating-point format:

$$x = s \times M \times B^{e-E}$$

$s$  = sign                       $B$  = base (usually 2, sometimes 16)

$M$  = mantissa                 $e$  = exponent

$E$  = bias, usually 127.

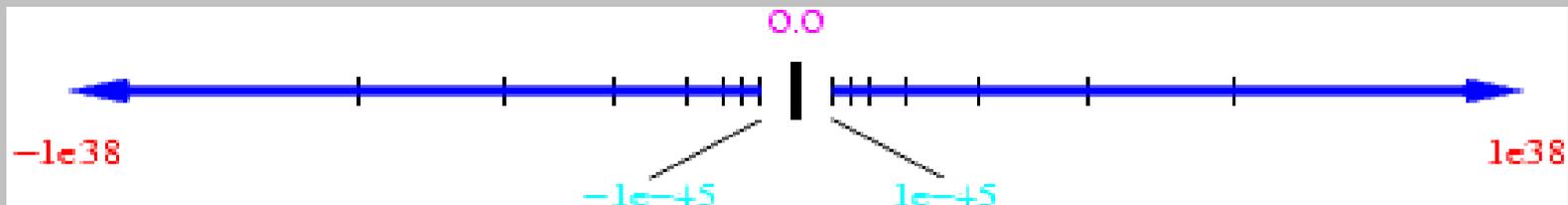
- In past, manufacturers used different number of bits for each of  $M$  and  $e$  → non-portable code.

# Floats, Cont'd

- Currently, most manufacturers adopt IEEE standard:
  - $s = 1^{\text{st}}$  bit
  - Next 8 bits are  $e$
  - Last 23 bits are  $M$ , expressed as a binary fraction, either  $1.F$ , or, if  $e=0$ ,  $0.F$ , where  $F$  is in base 2.
- Largest single-precision float  $f_{\text{max}} = 2^{127} \approx 10^{38}$ .
- Smallest (and least precise!)  $f_{\text{min}} = 2^{-149} \approx 10^{-45}$ .

# Round-off Error

- Not all values along real axis can be represented.
- There are  $10^{38}$  integers between  $f_{\min}$  &  $f_{\max}$ , but only  $2^{32} \approx 10^9$  bit patterns.



- Values  $< |10^{-45}|$  result in "underflow" error.
- If value cannot be represented, next nearest value is produced. Difference between desired and actual value is called "round-off error" (RE).

# Round-off Error, Cont'd

- Smallest value  $e_m$  for which  $1 + e_m > 1$  is called "machine accuracy", typically  $\sim 10^{-7}$  for 32 bits.
- Double precision greatly reduces  $e_m$  ( $\sim 10^{-16}$ ).
- RE accumulates in a calculation:
  - Random walk: total error  $N^{1/2} e_m$  after  $N$  operations.
  - But algorithms rarely random  $\rightarrow$  linear error  $N e_m$ .

# Round-off Error, Cont'd

- Subtraction of two very nearly equal numbers can give rise to large RE.

e.g. Solution of quadratic equation...

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

...can go badly wrong whenever  $ac \ll b^2$  (Cf. PS#2).

- RE cannot be avoided—it is a consequence of using a finite number of bits to represent real values.

# Truncation Error

- In practice, most numerical algorithms approximate desired solution with a finite number of arithmetic operations.
  - e.g. evaluating integral by quadrature
  - summing series using finite number of terms
- Difference between true solution and numerical approximation to solution is called "truncation error" (TE).

# Truncation Error, Cont'd

- TE exists even on "perfect" machine with no RE.
- TE is under programmer's control; much effort goes into reducing it.
- Usually RE and TE do not interact.
- Sometimes TE can amplify RE until it swamps calculation. Solution is then called unstable.  
e.g. Integer powers of Golden Mean (Cf. PS#2).