

Fluid Dynamics

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- The equations of fluid dynamics are coupled PDEs that form an IVP (hyperbolic).
- Use the techniques described so far, plus additions.

Fluid Dynamics in Astrophysics

- 99% of normal matter in the Universe is in gas or plasma (ionized gas) phase
- Whenever mean free path $\lambda \ll$ problem scale L in a plasma, can use continuum equations to describe evolution of macroscopic variables, e.g., density, pressure, etc.
- Mathematically,

$$\lambda \simeq \frac{1}{\sigma n} \sim \frac{10^{16}}{[n/1 \text{ cm}^{-3}]} \text{ cm},$$

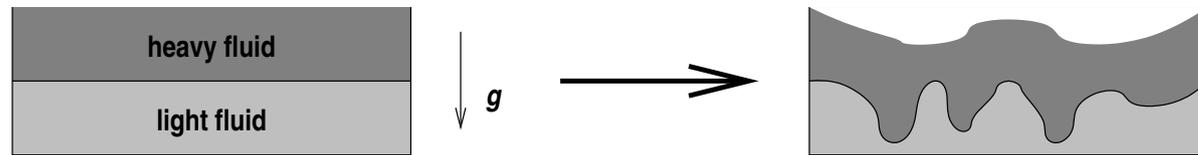
where $\sigma =$ classical cross-section of atom or ion ($\sim \pi r_{\text{Bohr}}^2$).

● Where is $\lambda \ll L$ in astrophysics?

Medium	$\sim n \text{ (cm}^{-3}\text{)}$	$\sim \lambda \text{ (cm)}$	$\sim L \text{ (cm)}$	Scale
planetary atmosphere	10^{20}	10^{-4}	10^{2-3}	1–10 m
stellar interior	10^{24}	10^{-8}	10^{11}	$1 R_{\odot}$
protoplanetary disk	10^{10}	10^6	10^{13}	1 AU
GMC	10	10^{15}	10^{19}	10 pc
diffuse ISM	1	10^{16}	10^{20}	100 pc
cluster gas	0.1	10^{17}	10^{22}	10 kpc
universe	10^{-6}	10^{22}	$> 10^{24}$	$> 1 \text{ Mpc}$

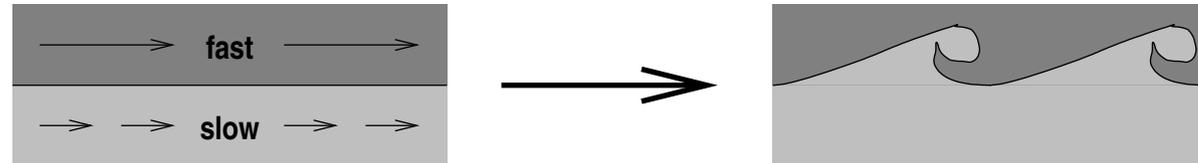
- What would we like to learn from studying fluid dynamics?
 1. Steady-state structure of certain fluid flows, e.g., stellar structure, accretion and winds around stars and compact objects
 2. Time evolution of system, e.g.,
 - stellar evolution
 - ISM=interstellar medium and IGM=intergalactic medium
 - Propagation of shocks through clumpy medium (SN explosions).
 - Accretion flows onto protostar or black hole.
 - Formation of structure in universe.
 3. Growth and saturation of instabilities, e.g.,

- Rayleigh-Taylor:



- Important in SN explosions, ISM, etc.

- Kelvin-Helmholtz:



- Important in jets and outflows in ISM.

- To study these phenomena, must use equations of fluid dynamics.

Equations of Fluid Dynamics

1. Continuity equation:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0, \quad (1)$$

where ρ = mass density, \mathbf{v} = velocity, and $\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$.

● Sometimes see this written as:

$$\frac{D\rho}{Dt} = -\rho \nabla \cdot \mathbf{v},$$

where $\frac{D}{Dt} \equiv \frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla$ = Lagrangian or co-moving or substantive derivative (rate of change of ρ in fluid frame, as opposed to $\frac{\partial}{\partial t}$ = Eulerian derivative, rate of change in lab frame).

- For an incompressible fluid, ρ is constant in space and time, so the continuity equation reduces to:

$$\nabla \cdot \mathbf{v} = 0.$$

- The continuity equation is a statement of *mass conservation*.

2 Euler's equation (equation of motion):

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \frac{\mathbf{F}}{\rho} - \frac{1}{\rho} \nabla p, \quad (2)$$

where p = pressure and \mathbf{F} = any external force (other than gas pressure) acting on a unit volume.

• More compactly,

$$\rho \frac{D\mathbf{v}}{Dt} = \mathbf{F} - \nabla p.$$

• For gravity, have $\mathbf{F} = -\rho \nabla \phi$, where $\nabla^2 \phi = 4\pi G\rho$. In hydrostatic equilibrium, $\mathbf{F} = \nabla p$, so there is no mass flow. E.g., in 1-D, have $dp/dr = -\rho GM(r)/r^2 = -g\rho$, where g = gravitational acceleration.

- For viscosity, $\mathbf{F} = \mu \nabla^2 \mathbf{v}$, where μ = coefficient of dynamical viscosity, assuming $\rho = \text{constant}$ (incompressible fluid). If there are no other force terms in \mathbf{F} , this gives the Navier-Stokes equation.
- Similarly, can add force terms for electric and/or magnetic fields.
- For the steady flow of a gas, $\partial \mathbf{v} / \partial t = \mathbf{0}$ and, if there are no external forces, get

$$\rho \mathbf{v} \cdot \nabla \mathbf{v} = -\nabla p,$$

which is Bernoulli's equation for compressible flow.

- Euler's equation is a statement of *momentum conservation*.

3 Energy equation:

$$\frac{\partial e}{\partial t} + \nabla \cdot [(e + p)\mathbf{v}] = 0, \quad (3)$$

where $e \equiv \rho(\varepsilon + \frac{1}{2}v^2)$ = energy density (energy/volume) and ε = specific internal energy (energy/mass).

● In Lagrange form,

$$\frac{De}{Dt} = -e(\nabla \cdot \mathbf{v}) - \nabla \cdot (p\mathbf{v}),$$

or, more compactly,

$$\frac{D\varepsilon}{Dt} = -\frac{p}{\rho}(\nabla \cdot \mathbf{v}).$$

● The energy equation is a statement of *energy conservation* (there are many alternative ways to write the energy equation, depending on the context, e.g., using specific enthalpy ($= \varepsilon + p/\rho$), specific entropy combined with temperature and heat transfer, etc.).

4 Equation of state:

$$p = p(\rho, \varepsilon). \quad (4)$$

- Needed to close system.
- E.g., for ideal gas, $p = (\gamma - 1)\rho\varepsilon$, where $\gamma =$ adiabatic index (= ratio of specific heats at constant volume and pressure).^a
For ideal monatomic, diatomic, and polyatomic gases, $\gamma = 5/3$, $7/5$, and $4/3$, respectively.

^aAlso have $pV^\gamma = \text{constant}$, $TV^{\gamma-1} = \text{constant}$, $Tp^{(1-\gamma)/\gamma} = \text{constant}$.

Solving the Equations of Fluid Dynamics

- There are many choices one can make when adopting a numerical algorithm to solve the equations of fluid dynamics, e.g.,
 1. Finite differencing methods, including:
 - (a) Flux-conservative form.
 - (b) Operator splitting.
 2. Particle methods (e.g., smoothed particle hydrodynamics, or SPH).

- Schematically (will discuss methods in *italics*),

